Solving second order linear ODEs with constant coefficients —using differential operators and their inverses

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A general second order linear ODE with constant coefficients has the form

$$y''(t) + py'(t) + qy(t) = g(t).$$
(1)

We first consider homogeneous equations, which means $g(t) \equiv 0$. In this case, writing (1) in terms of the differential operator D introduced in our discussion of first order linear ODEs gives

$$(D^2 + pD + q)[y(t)] = 0, (2)$$

where D^2 is interpreted as

$$D^{2}[y(t)] = D[D[y(t)]] = D[y'(t)] = y''(t).$$

If we knew the inverse operator $(D^2 + pD + q)^{-1}$, we could apply it to both sides of (2) and get

$$y(t) = (D^2 + pD + q)^{-1}[0],$$

which would be a solution to (2). So we need to figure out the inverse operator for $D^2 + pD + q$.

This second order differential operator should remind us of the quadratic polynomials we studied in high school algebra, like

$$x^2 + px + q$$

Remember that such polynomials can be factored:

$$x^{2} + px + q = (x - r_{1})(x - r_{2}),$$
(3)

where r_1 and r_2 are the roots (solutions) of the quadratic equation

$$x^2 + px + q = 0. (4)$$

This suggests that we might be able to factor the second order differential operator $D^2 + pD + q$ as the product of first order differential operators: $(D - r_1)(D - r_2)$, where r_1 and

 r_2 are the roots of (4), which is called the *characteristic equation* for (2). To check if this is true, we can compute:

$$(D - r_1)(D - r_2)[y(t)] = (D - r_1)[(D - r_2)[y(t)]]$$

= $(D - r_1)[y'(t) - r_2y(t)]$
= $D[y'(t) - r_2y(t)] - r_1[y'(t) - r_2y(t)]$
= $y''(t) - r_2y'(t) - r_1y'(t) + r_1r_2y(t)$
= $y''(t) - (r_1 + r_2)y'(t) + r_1r_2y(t)$.

Since multiplying out the right side of (3) tells us that $-(r_1 + r_2) = p$ and $r_1r_2 = q$, we can conclude that this factorization of the second order differential operator is right:

$$D^{2} + pD + q = (D - r_{1})(D - r_{2}).$$
(5)

Now we can use (5) to rewrite (2) as

$$(D - r_1)(D - r_2)[y(t)] = 0.$$
 (6)

Since

$$(D - r_1)(D - r_2)[y(t)] = (D - r_1)[(D - r_2)[y(t)]]$$

we can solve (6) be using what we already know about the inverses of first order differential operators:

$$(D - r_2)[y(t)] = (D - r_1)^{-1}[0]$$

$$y(t) = (D - r_2)^{-1} [(D - r_1)^{-1}[0]].$$
(7)

That is, since

$$(D - r_1)^{-1}[0] = e^{r_1 t} \int^t e^{-r_1 s}[0] ds$$

= $e^{r_1 t} c$,

(7) becomes

$$y(t) = (D - r_2)^{-1} [ce^{r_1 t}]$$

= $e^{r_2 t} \int^t e^{-r_2 s} ce^{r_1 s} ds$
= $e^{r_2 t} \int^t ce^{(r_1 - r_2)s} ds.$ (8)

Now there are two cases, depending on whether $r_1 = r_2$ or not.

If $r_1 \neq r_2$, we evaluate the integral in (8) to get:

$$y(t) = e^{r_2 t} \left(\frac{c}{r_1 - r_2} e^{(r_1 - r_2)t} + c_2 \right)$$

= $c_1 e^{r_1 t} + c_2 e^{r_2 t},$ (9)

where we have renamed the constant $c/(r_1 - r_2) = c_1$.

If $r_1 = r_2 = r$, the integral in (8) is even simpler:

$$y(t) = e^{rt} \int^t c ds$$

= $e^{rt} (ct + c_2)$
= $c_1 t e^{rt} + c_2 e^{rt}$, (10)

where we have renamed the constant $c = c_1$.

Thus, to solve (2) we find the roots r_1 and r_2 of the characteristic equation (4). If they are equal the general solution is (10); if they are different, the general solution is (9).

Sometimes the roots of the characteristic equation (4) are complex numbers $a \pm bi$. In this case (9) becomes

$$y(t) = c_1 e^{(a+bi)t} + c_2 e^{(a-bi)t}$$

= $e^{at} (c_1 e^{ibt} + c_2 e^{-ibt}).$ (11)

We can eliminate the imaginary exponents in (11) by using Euler's formula:

$$e^{i\theta} = \cos\theta + i\sin\theta.$$

Then

$$y(t) = e^{at} \left(c_1 \left(\cos(bt) + i \sin(bt) \right) + c_2 \left(\cos(-bt) + i \sin(-bt) \right) \right)$$

= $e^{at} \left((c_1 + c_2) \cos(bt) + i (c_1 - c_2) \sin(bt) \right)$
= $e^{at} \left(d_1 \cos(bt) + d_2 \sin(bt) \right),$ (12)

where we have renamed the constant $c_1 + c_2 = d_1$ and the constant $i(c_1 - c_2) = d_2$. (12) is the solution to (2) when the roots of the characteristic equation (4) are complex.