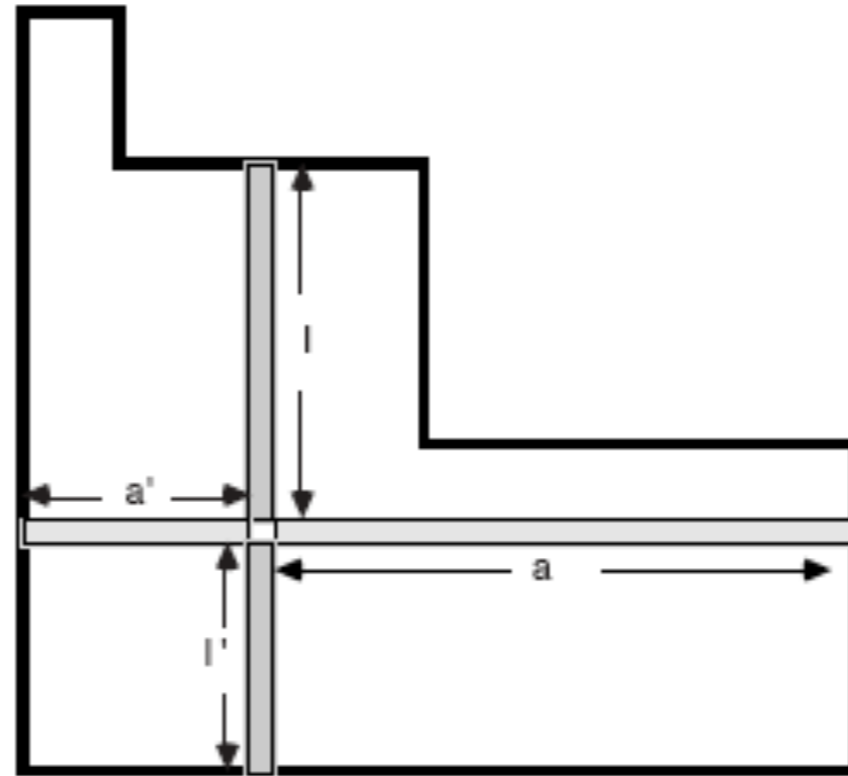


A New Recursion
In
The Theory of Macdonald Polynomials

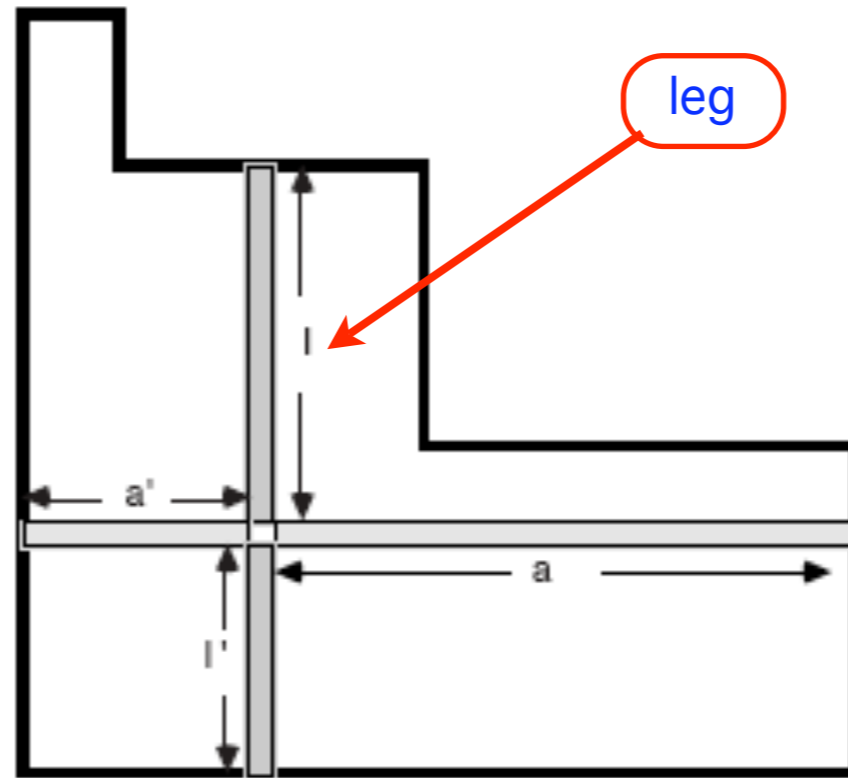
Joint work
with
Jim Haglund

Some Basic Ingredients

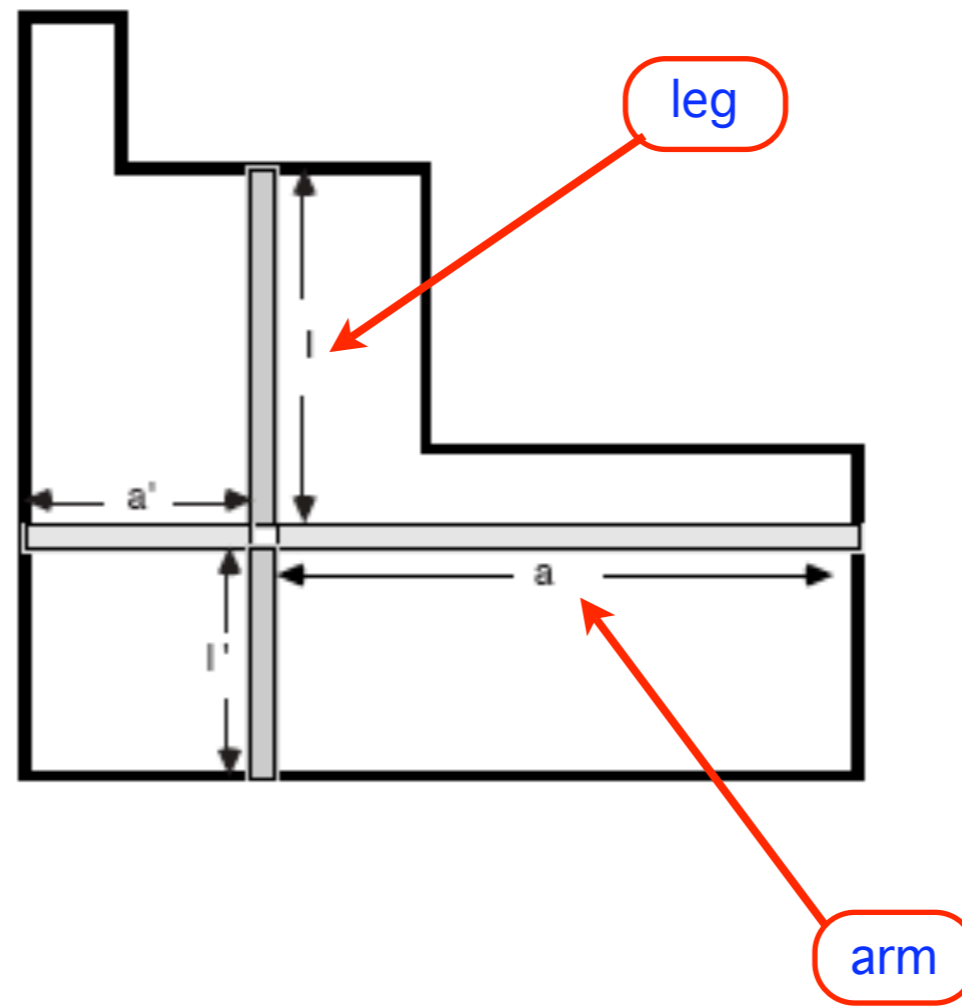
Some Basic Ingredients



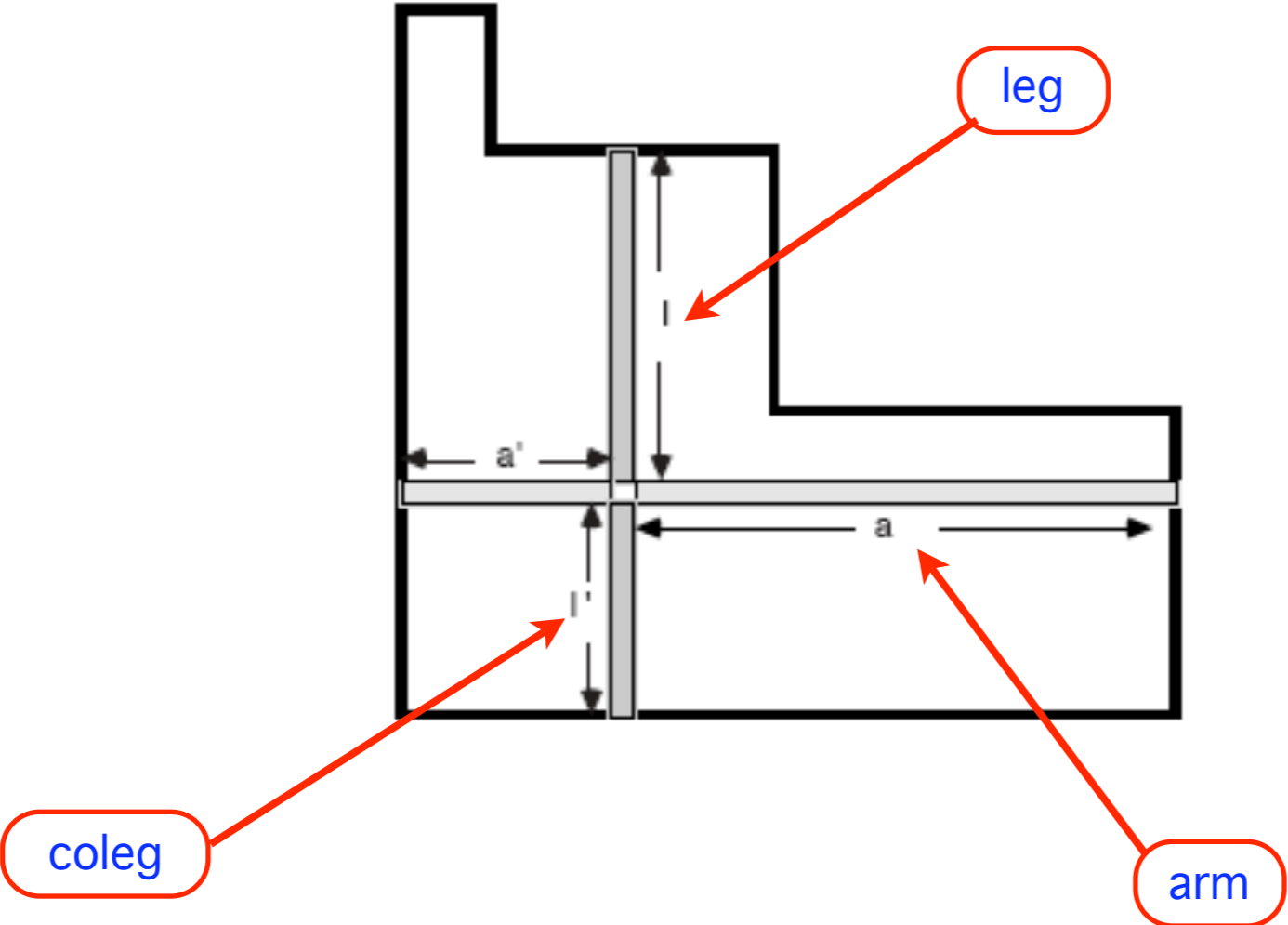
Some Basic Ingredients



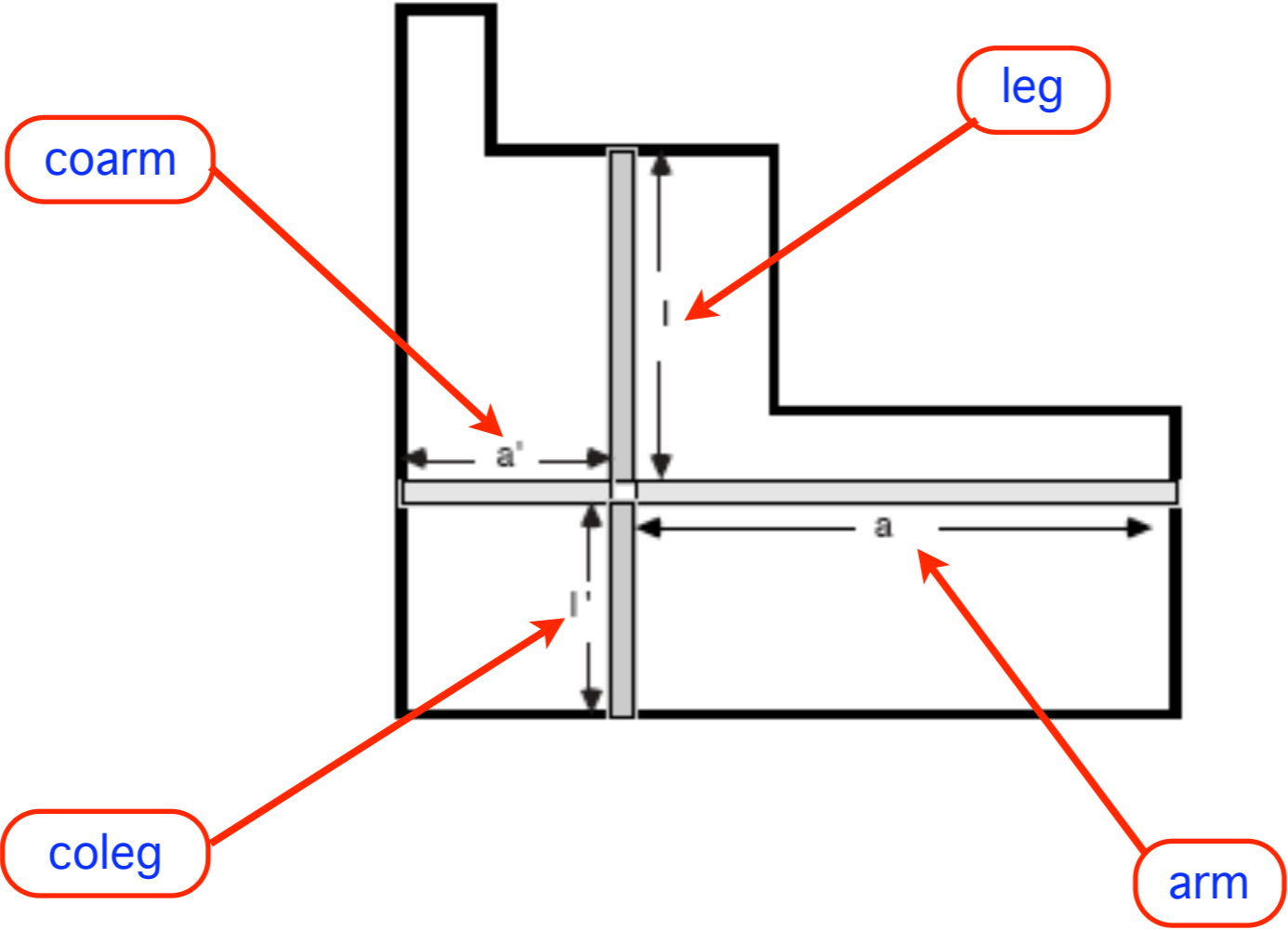
Some Basic Ingredients



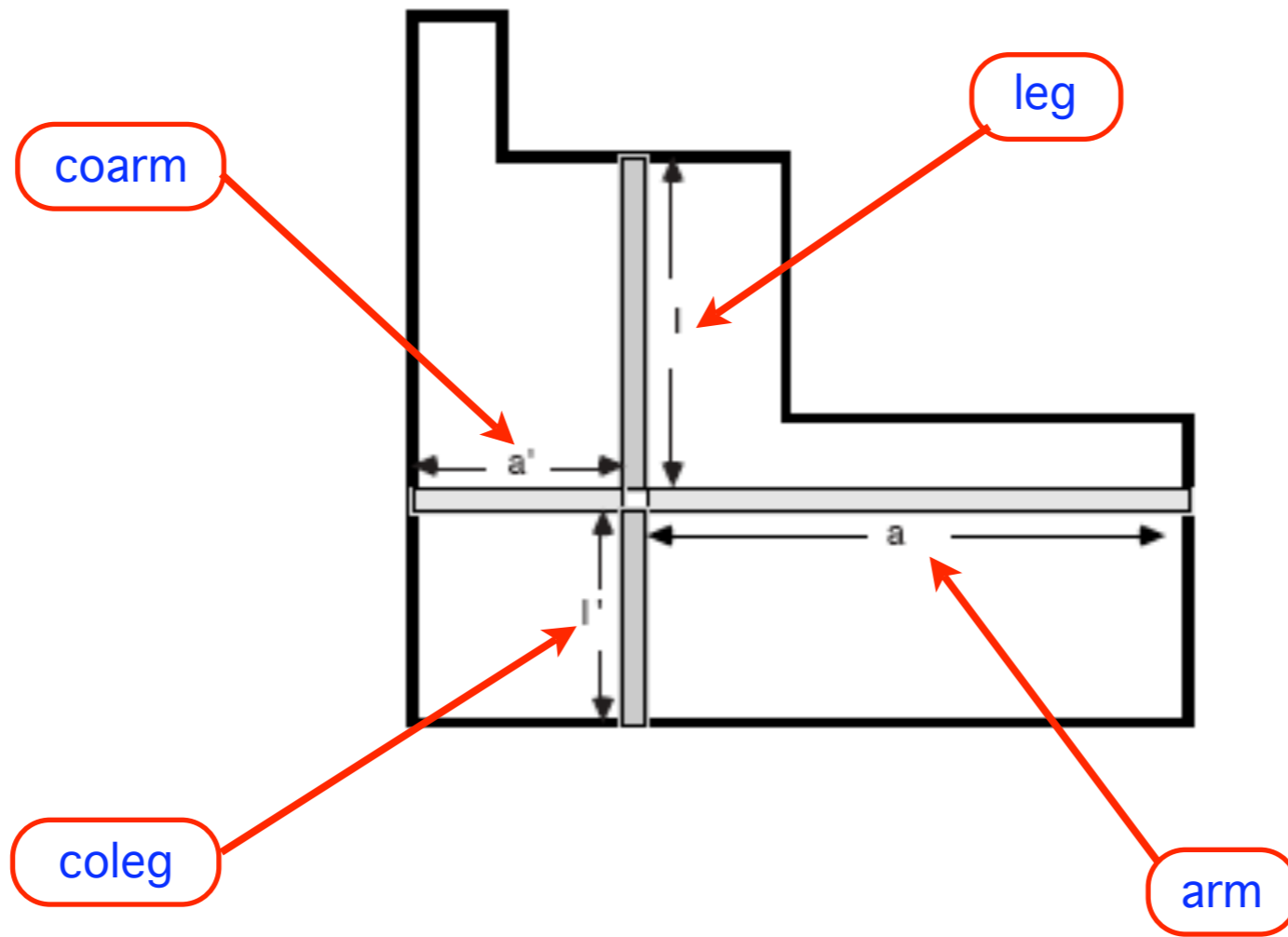
Some Basic Ingredients



Some Basic Ingredients

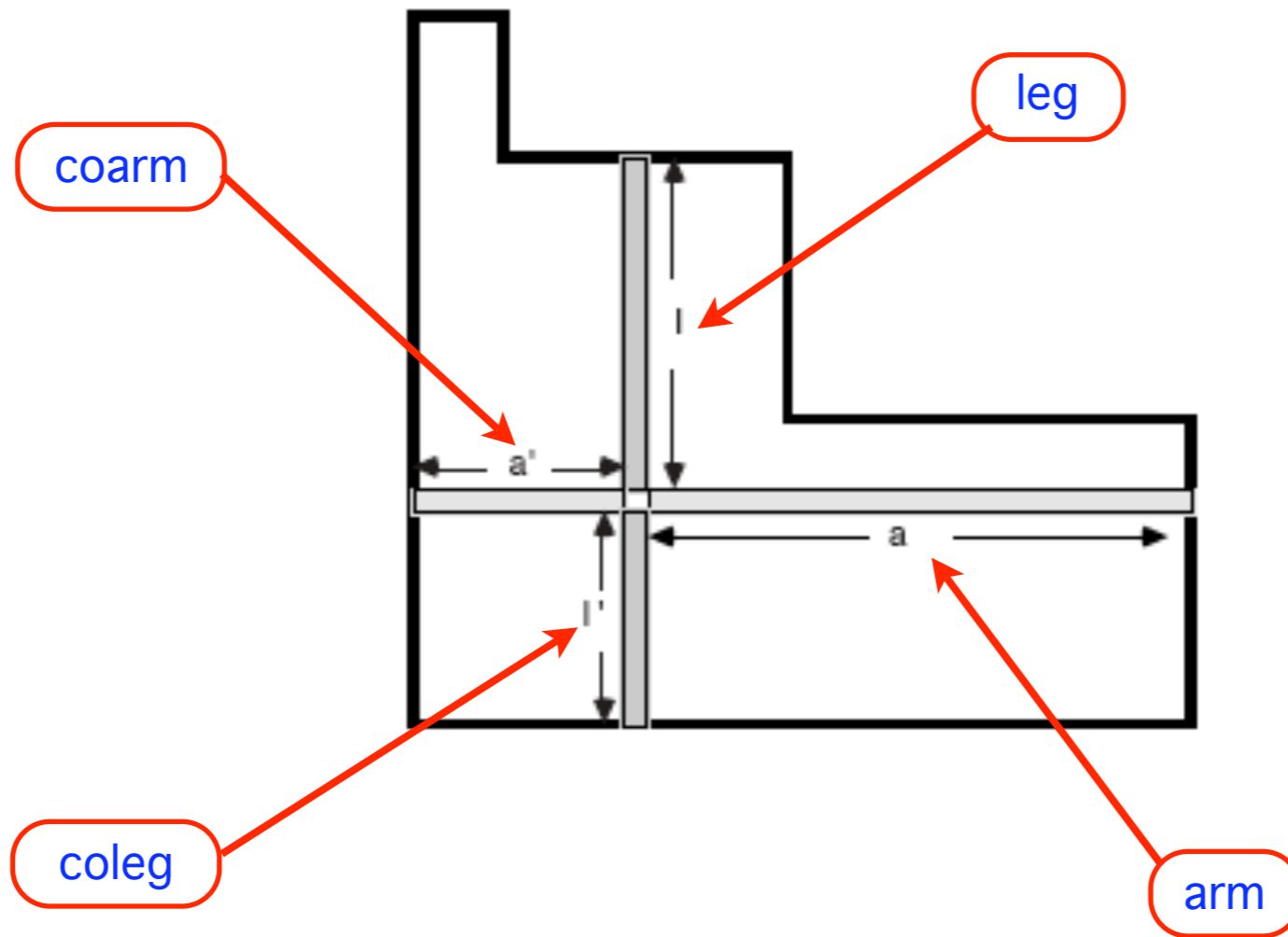


Some Basic Ingredients



$$n(\mu) = \sum l = \sum l' = \sum (i-1)\mu_i = \sum \binom{\mu'_i}{2}$$

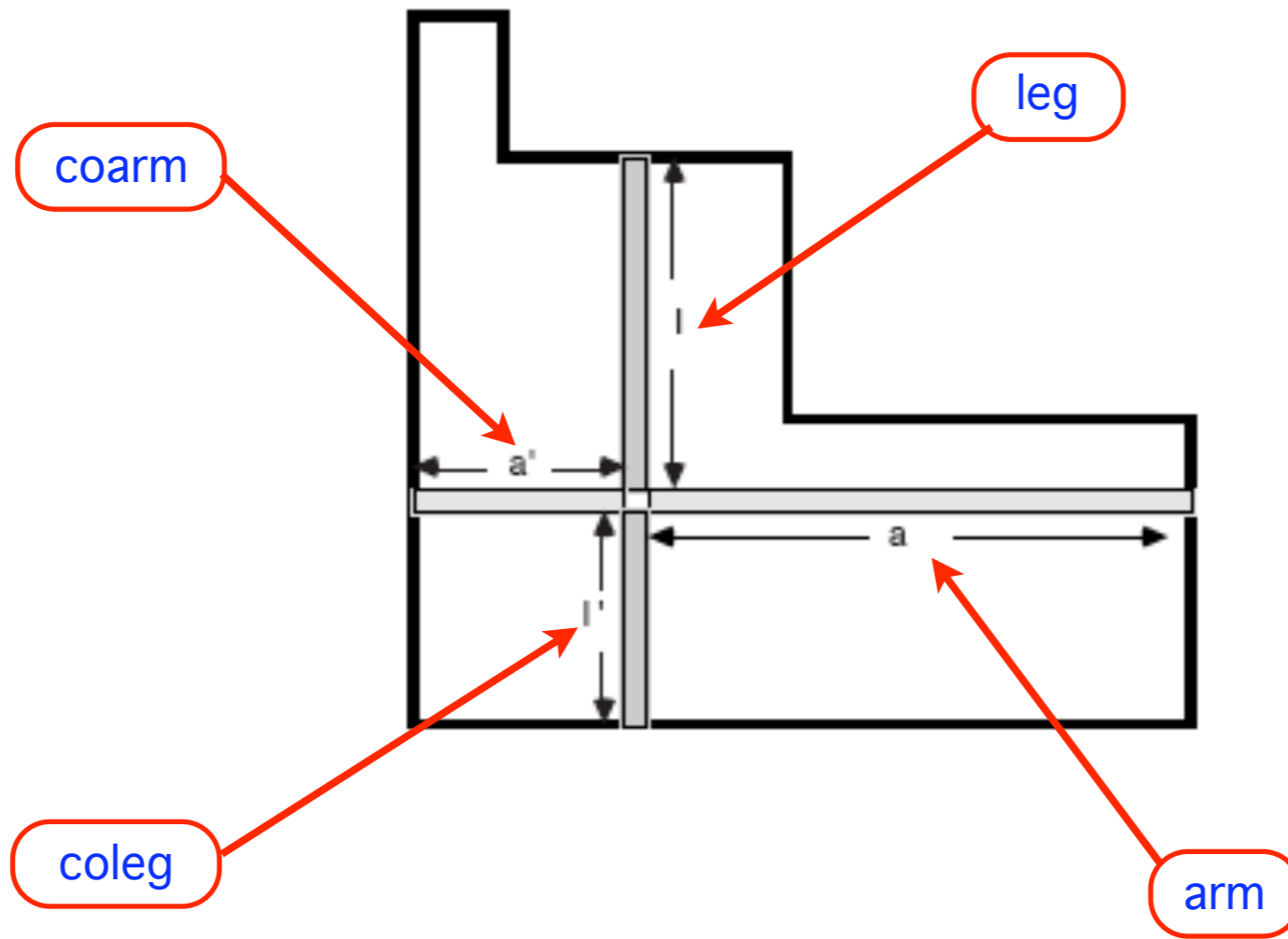
Some Basic Ingredients



$$n(\mu) = \sum l = \sum l' = \sum (i-1)\mu_i = \sum \binom{\mu'_i}{2}$$

$$\sum q^{a'} t^{l'} = B_\mu(q, t)$$

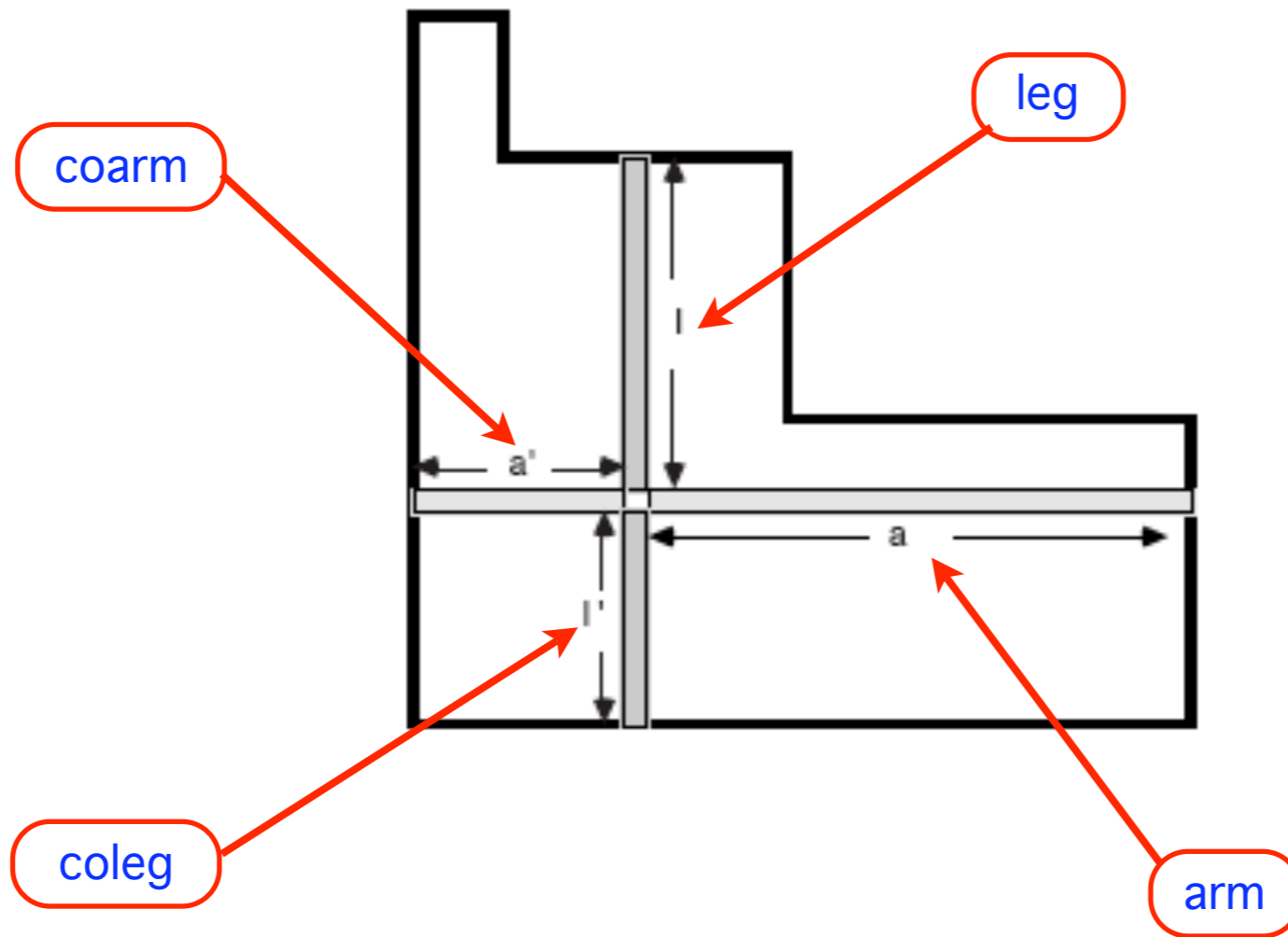
Some Basic Ingredients



$$n(\mu) = \sum l = \sum l' = \sum (i-1)\mu_i = \sum \binom{\mu'_i}{2}$$

$$\sum q^{a'} t^{l'} = B_\mu(q, t) \quad \prod^{o,o} (1 - q^{a'} t^{l'}) = \Pi_\mu(q, t)$$

Some Basic Ingredients

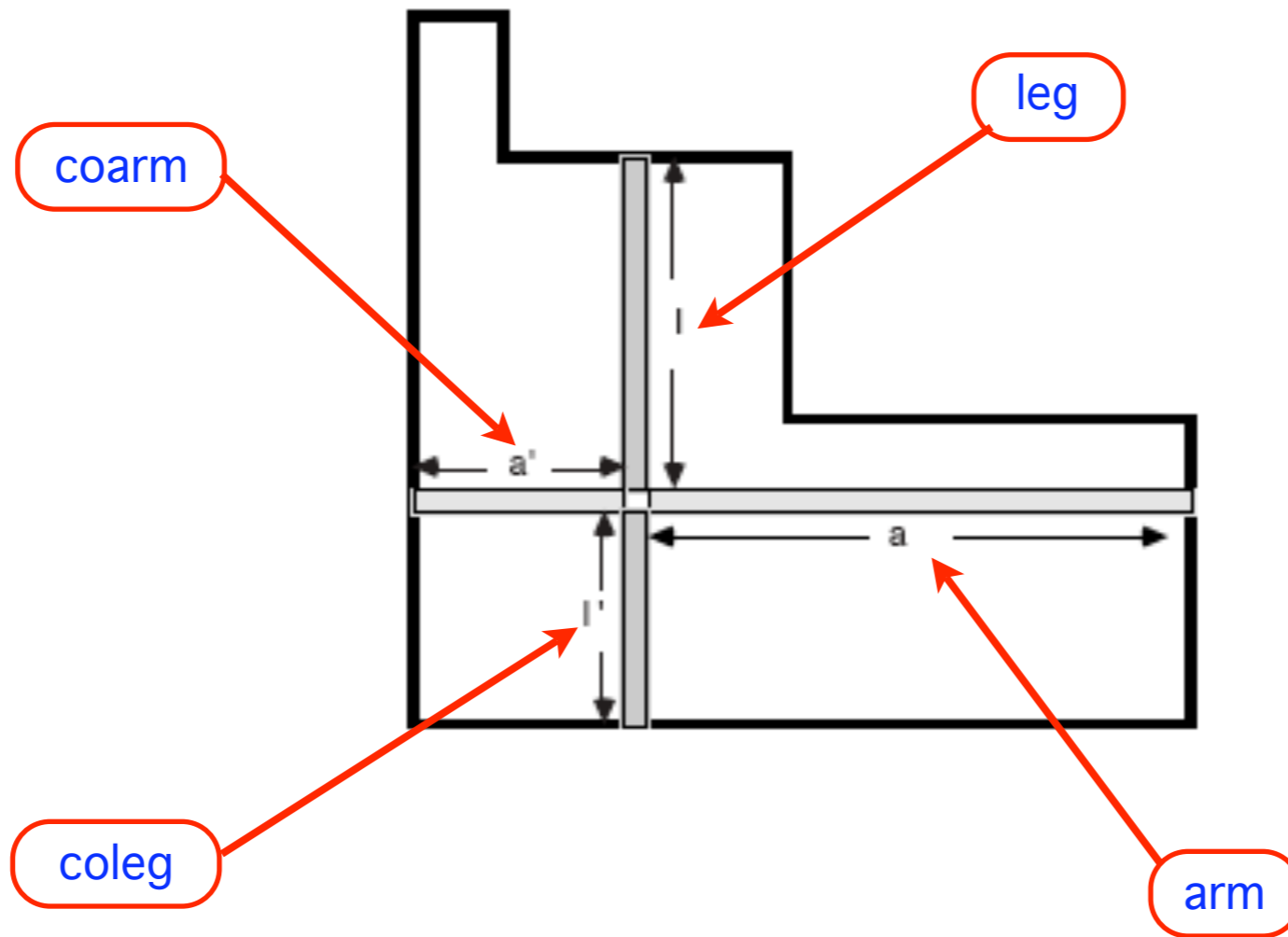


$$n(\mu) = \sum l = \sum l' = \sum (i-1)\mu_i = \sum \binom{\mu'_i}{2}$$

$$\sum q^{a'} t^{l'} = B_\mu(q, t) \quad \prod^{o,o} (1 - q^{a'} t^{l'}) = \Pi_\mu(q, t)$$

$$\prod (q^a - t^{l+1}) = \tilde{h}_\mu(q, t)$$

Some Basic Ingredients



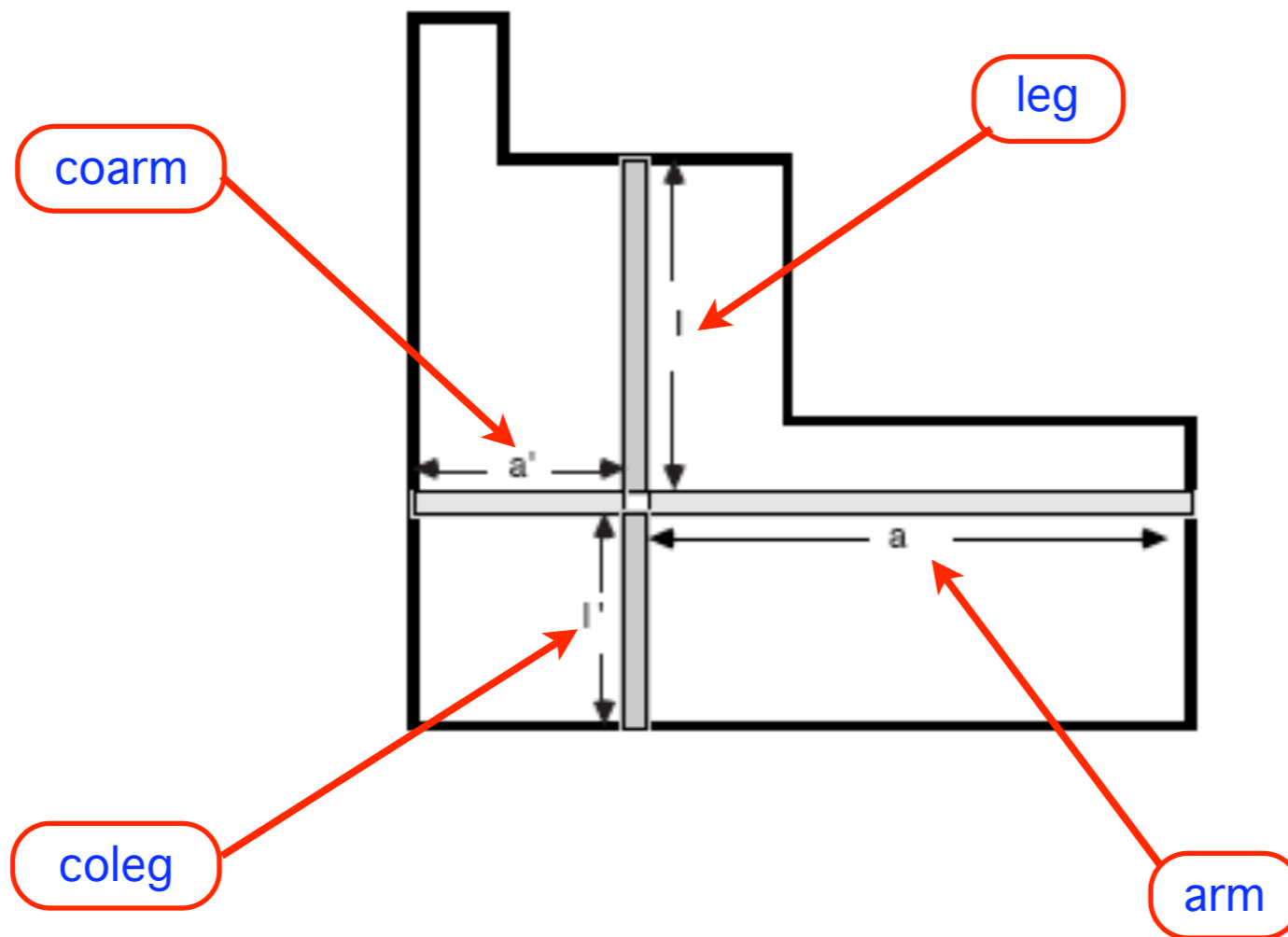
$$n(\mu) = \sum l = \sum l' = \sum (i-1)\mu_i = \sum \binom{\mu'_i}{2}$$

$$\sum q^{a'} t^{l'} = B_\mu(q, t) \quad \prod^{o,o} (1 - q^{a'} t^{l'}) = \Pi_\mu(q, t)$$

$$\prod (q^a - t^{l+1}) = \tilde{h}_\mu(q, t)$$

$$\prod (t^l - q^{a+1}) = \tilde{h}'_\mu(q, t)$$

Some Basic Ingredients

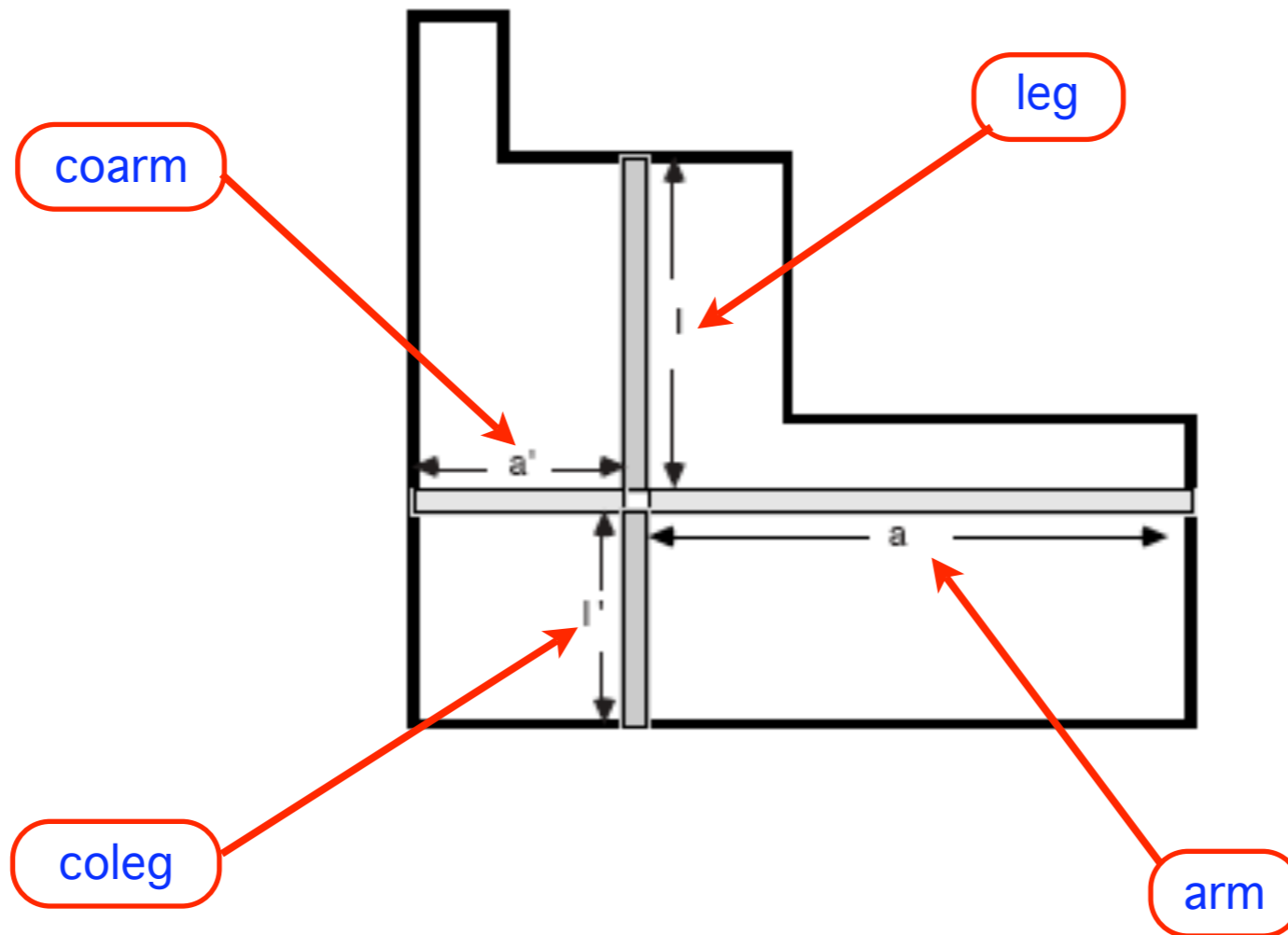


$$n(\mu) = \sum l = \sum l' = \sum (i-1)\mu_i = \sum \binom{\mu'_i}{2}$$

$$\sum q^{a'} t^{l'} = B_\mu(q, t) \quad \prod^{o,o} (1 - q^{a'} t^{l'}) = \Pi_\mu(q, t)$$

$$\begin{aligned} \prod(q^a - t^{l+1}) &= \tilde{h}_\mu(q, t) \\ \prod(t^l - q^{a+1}) &= \tilde{h}'_\mu(q, t) \end{aligned} \Rightarrow w_\mu(q, t) = \tilde{h}_\mu(q, t) \times \tilde{h}'_\mu(q, t)$$

Some Basic Ingredients



$$n(\mu) = \sum l = \sum l' = \sum (i-1)\mu_i = \sum \binom{\mu'_i}{2}$$

$$\sum q^{a'} t^{l'} = B_\mu(q, t) \quad \prod^{o,o} (1 - q^{a'} t^{l'}) = \Pi_\mu(q, t)$$

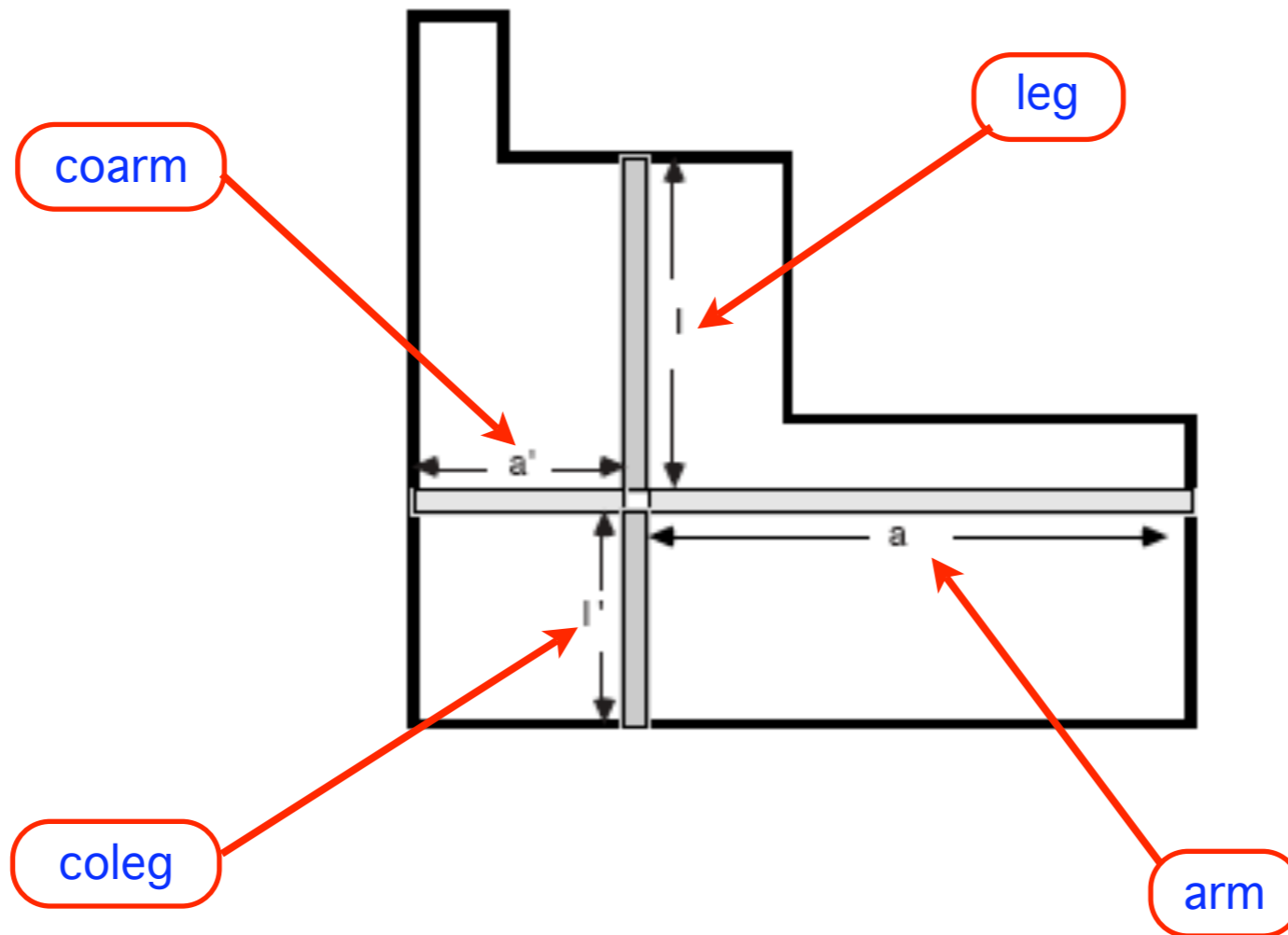
$$\prod (q^a - t^{l+1}) = \tilde{h}_\mu(q, t)$$

$$\prod (t^l - q^{a+1}) = \tilde{h}'_\mu(q, t)$$

$$w_\mu(q, t) = \tilde{h}_\mu(q, t) \times \tilde{h}'_\mu(q, t)$$

$$M = (1-t)(1-q)$$

Some Basic Ingredients



$$n(\mu) = \sum l = \sum l' = \sum (i-1)\mu_i = \sum \binom{\mu'_i}{2}$$

$$\sum q^{a'} t^{l'} = B_\mu(q, t) \quad \prod^{o,o} (1 - q^{a'} t^{l'}) = \Pi_\mu(q, t)$$

$$\prod (q^a - t^{l+1}) = \tilde{h}_\mu(q, t) \quad \Rightarrow \quad w_\mu(q, t) = \tilde{h}_\mu(q, t) \times \tilde{h}'_\mu(q, t)$$

$$\prod (t^l - q^{a+1}) = \tilde{h}'_\mu(q, t)$$

$$M = (1-t)(1-q)$$

The Macdonald polynomials

The Macdonald polynomials
we will work with are

The Macdonald polynomials

we will work with are

the unique symmetric function basis $\{\tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}]\}_\mu$

The Macdonald polynomials

we will work with are

the unique symmetric function basis $\{\tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}]\}_\mu$

such that

The Macdonald polynomials

we will work with are

the unique symmetric function basis $\{\tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t]\}_\mu$

such that

$$1) \quad \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] \Big|_{S[\mathbf{n}]} = 1$$

The Macdonald polynomials

we will work with are

the unique symmetric function basis $\{\tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}]\}_t$

such that

$$1) \quad \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] \Big|_{\mathbf{S}[\mathbf{n}]} = 1$$

$$2) \quad \langle \tilde{H}_\mu, \tilde{H}_\lambda \rangle_* = \chi(\lambda = \mu) \mathbf{w}_\mu(\mathbf{q}, \mathbf{t})$$

The Macdonald polynomials

we will work with are

the unique symmetric function basis $\{\tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t]\}_t$

such that

$$1) \quad \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] \Big|_{\mathbf{S}[\mathbf{n}]} = 1$$

$$2) \quad \langle \tilde{H}_\mu, \tilde{H}_\lambda \rangle_* = \chi(\lambda = \mu) \mathbf{w}_\mu(\mathbf{q}, t)$$

$$\langle p_\alpha, p_\beta \rangle_* = \chi(\alpha = \beta) z_\alpha \prod_{\alpha_i > 0} (-1)^{\alpha_i - 1} (1 - t^{\alpha_i})(1 - t^{\beta_i})$$

The Macdonald polynomials

we will work with are

the unique symmetric function basis $\{\tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t]\}_t$

such that

$$1) \quad \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] \Big|_{\mathbf{S}[\mathbf{n}]} = 1$$

$$2) \quad \langle \tilde{H}_\mu, \tilde{H}_\lambda \rangle_* = \chi(\lambda = \mu) \mathbf{w}_\mu(\mathbf{q}, t)$$

$$\langle p_\alpha, p_\beta \rangle_* = \chi(\alpha = \beta) z_\alpha \prod_{\alpha_i > 0} (-1)^{\alpha_i - 1} (1 - t^{\alpha_i})(1 - t^{\beta_i})$$

The Visual Representation of a polynomial P[q,t]

The Macdonald polynomials

we will work with are

the unique symmetric function basis $\{\tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t]\}_t$

such that

$$1) \quad \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] \Big|_{\mathbf{S}[\mathbf{n}]} = 1$$

$$2) \quad \langle \tilde{H}_\mu, \tilde{H}_\lambda \rangle_* = \chi(\lambda = \mu) \mathbf{w}_\mu(\mathbf{q}, t)$$

$$\langle p_\alpha, p_\beta \rangle_* = \chi(\alpha = \beta) z_\alpha \prod_{\alpha_i > 0} (-1)^{\alpha_i - 1} (1 - t^{\alpha_i})(1 - t^{\beta_i})$$

The Visual Representation of a polynomial P[q,t]

$$8 q^3 + 36 q^2 t + 54 q t^2 + 27 t^3 + 12 q^2 + 36 q t + 27 t^2 + 6 q + 9 t + 1$$

The Macdonald polynomials

we will work with are

the unique symmetric function basis $\{\tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t]\}_t$

such that

$$1) \quad \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] \Big|_{\mathbf{S}[\mathbf{n}]} = 1$$

$$2) \quad \langle \tilde{H}_\mu, \tilde{H}_\lambda \rangle_* = \chi(\lambda = \mu) \mathbf{w}_\mu(\mathbf{q}, t)$$

$$\langle p_\alpha, p_\beta \rangle_* = \chi(\alpha = \beta) z_\alpha \prod_{\alpha_i > 0} (-1)^{\alpha_i - 1} (1 - t^{\alpha_i})(1 - t^{\beta_i})$$

The Visual Representation of a polynomial P[q,t]

$$8 q^3 + 36 q^2 t + 54 q t^2 + 27 t^3 + 12 q^2 + 36 q t + 27 t^2 + 6 q + 9 t + 1$$

$$\begin{bmatrix} 27 & 0 & 0 & 0 \\ 27 & 54 & 0 & 0 \\ 9 & 36 & 36 & 0 \\ 1 & 6 & 12 & 8 \end{bmatrix}$$

The Macdonald polynomials

we will work with are

the unique symmetric function basis $\{\tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t]\}_t$

such that

$$1) \quad \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] \Big|_{\mathcal{S}[\mathbf{n}]} = 1$$

$$2) \quad \langle \tilde{H}_\mu, \tilde{H}_\lambda \rangle_* = \chi(\lambda = \mu) \mathbf{w}_\mu(\mathbf{q}, t)$$

$$\langle p_\alpha, p_\beta \rangle_* = \chi(\alpha = \beta) z_\alpha \prod_{\alpha_i > 0} (-1)^{\alpha_i - 1} (1 - t^{\alpha_i})(1 - t^{\beta_i})$$

The Visual Representation of a polynomial P[q,t]

$$8 q^3 + 36 q^2 t + 54 q t^2 + 27 t^3 + 12 q^2 + 36 q t + 27 t^2 + 6 q + 9 t + 1$$

$$\mathbf{t}^r \begin{array}{c} \uparrow \\ 3 \\ 2 \\ 1 \\ 0 \end{array} \begin{bmatrix} 27 & 0 & 0 & 0 \\ 27 & 54 & 0 & 0 \\ 9 & 36 & 36 & 0 \\ 1 & 6 & 12 & 8 \end{bmatrix}$$

The Macdonald polynomials

we will work with are

the unique symmetric function basis $\{\tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t]\}_t$

such that

$$1) \quad \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] \Big|_{\mathcal{S}[\mathbf{n}]} = 1$$

$$2) \quad \langle \tilde{H}_\mu, \tilde{H}_\lambda \rangle_* = \chi(\lambda = \mu) \mathbf{w}_\mu(\mathbf{q}, t)$$

$$\langle p_\alpha, p_\beta \rangle_* = \chi(\alpha = \beta) z_\alpha \prod_{\alpha_i > 0} (-1)^{\alpha_i - 1} (1 - t^{\alpha_i})(1 - t^{\beta_i})$$

The Visual Representation of a polynomial P[q,t]

$$8q^3 + 36q^2t + 54qt^2 + 27t^3 + 12q^2 + 36qt + 27t^2 + 6q + 9t + 1$$

$$\begin{array}{c} \mathbf{t}^r \\ \uparrow \\ 3 \\ 2 \\ 1 \\ 0 \end{array} \begin{array}{c} \left[\begin{array}{cccc} 27 & 0 & 0 & 0 \\ 27 & 54 & 0 & 0 \\ 9 & 36 & 36 & 0 \\ 1 & 6 & 12 & 8 \end{array} \right] \end{array} \begin{array}{c} \\ \\ \\ \rightarrow \\ 0 \quad 1 \quad 2 \quad 3 \end{array} \\ \mathbf{q}^s$$

The Macdonald polynomials

we will work with are

the unique symmetric function basis $\{\tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t]\}_t$

such that

$$1) \quad \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] \Big|_{\mathcal{S}[\mathbf{n}]} = 1$$

$$2) \quad \langle \tilde{H}_\mu, \tilde{H}_\lambda \rangle_* = \chi(\lambda = \mu) \mathbf{w}_\mu(\mathbf{q}, t)$$

$$\langle p_\alpha, p_\beta \rangle_* = \chi(\alpha = \beta) z_\alpha \prod_{\alpha_i > 0} (-1)^{\alpha_i - 1} (1 - t^{\alpha_i})(1 - t^{\beta_i})$$

The Visual Representation of a polynomial P[q,t]

$$8q^3 + 36q^2t + 54qt^2 + 27t^3 + 12q^2 + 36qt + 27t^2 + 6q + 9t + 1$$

$$\begin{array}{c}
 \begin{array}{c} 3 \\ 2 \\ 1 \\ 0 \end{array} \uparrow \mathbf{t}^r \\
 \begin{array}{c} \boxed{27} \quad 0 \quad 0 \quad 0 \\ 27 \quad 54 \quad 0 \quad 0 \\ 9 \quad 36 \quad 36 \quad 0 \\ 1 \quad 6 \quad 12 \quad 8 \end{array} \\
 \begin{array}{c} 0 \quad 1 \quad 2 \quad 3 \end{array} \rightarrow \mathbf{q}^s
 \end{array}$$

The Macdonald polynomials

we will work with are

the unique symmetric function basis $\{\tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t]\}_t$

such that

$$1) \quad \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] \Big|_{\mathcal{S}[\mathbf{n}]} = 1$$

$$2) \quad \langle \tilde{H}_\mu, \tilde{H}_\lambda \rangle_* = \chi(\lambda = \mu) \mathbf{w}_\mu(\mathbf{q}, t)$$

$$\langle p_\alpha, p_\beta \rangle_* = \chi(\alpha = \beta) z_\alpha \prod_{\alpha_i > 0} (-1)^{\alpha_i - 1} (1 - t^{\alpha_i})(1 - t^{\beta_i})$$

The Visual Representation of a polynomial P[q,t]

$$8q^3 + 36q^2t + 54qt^2 + 27t^3 + 12q^2 + 36qt + 27t^2 + 6q + 9t + 1$$

$$\begin{array}{c}
 3 \\
 2 \\
 1 \\
 0
 \end{array}
 \begin{array}{c}
 \uparrow \\
 \text{t}^r \\
 \uparrow \\
 \uparrow \\
 \uparrow
 \end{array}
 \begin{array}{c}
 \boxed{27} \quad 0 \quad 0 \quad 0 \\
 27 \quad 54 \quad 0 \quad 0 \\
 9 \quad \boxed{36} \quad 36 \quad 0 \\
 1 \quad 6 \quad 12 \quad 8
 \end{array}
 \begin{array}{c}
 0 \quad 1 \quad 2 \quad 3 \\
 \leftarrow \\
 \text{q}^s \\
 \leftarrow
 \end{array}$$

The Macdonald polynomials

we will work with are

the unique symmetric function basis $\{\tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t]\}_t$

such that

$$1) \quad \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] \Big|_{S[\mathbf{n}]} = 1$$

$$2) \quad \langle \tilde{H}_\mu, \tilde{H}_\lambda \rangle_* = \chi(\lambda = \mu) \mathbf{w}_\mu(\mathbf{q}, t)$$

$$\langle p_\alpha, p_\beta \rangle_* = \chi(\alpha = \beta) z_\alpha \prod_{\alpha_i > 0} (-1)^{\alpha_i - 1} (1 - t^{\alpha_i})(1 - t^{\beta_i})$$

The Visual Representation of a polynomial P[q,t]

$$8q^3 + 36q^2t + 54qt^2 + 27t^3 + 12q^2 + 36qt + 27t^2 + 6q + 9t + 1$$

$$\begin{array}{c}
 3 \\
 2 \\
 1 \\
 0
 \end{array}
 \begin{array}{c}
 \uparrow \\
 \text{t}^r \\
 \uparrow \\
 \uparrow \\
 \uparrow
 \end{array}
 \begin{array}{c}
 \boxed{27} \quad 0 \quad 0 \quad 0 \\
 27 \quad 54 \quad 0 \quad 0 \\
 9 \quad \boxed{36} \quad 36 \quad 0 \\
 1 \quad 6 \quad 12 \quad 8
 \end{array}
 \begin{array}{c}
 0 \quad 1 \quad 2 \quad 3 \\
 \leftarrow \\
 \text{q}^s \\
 \leftarrow
 \end{array}$$

next

Our Macdonald polynomials have Schur function expansion

Our Macdonald polynomials have Schur function expansion

$$\tilde{H}_\mu(x; q, t) = \sum_{\lambda} S_\lambda(x) \tilde{K}_{\lambda, \mu}(q, t)$$

Our Macdonald polynomials have Schur function expansion

$$\tilde{H}_\mu(x; q, t) = \sum_{\lambda} S_\lambda(x) \tilde{K}_{\lambda, \mu}(q, t)$$

where

Our Macdonald polynomials have Schur function expansion

$$\tilde{H}_\mu(x; q, t) = \sum_{\lambda} S_\lambda(x) \tilde{K}_{\lambda, \mu}(q, t)$$

where

$$\tilde{K}_{\lambda\mu}(\mathbf{q}, t) = t^{n(\mu)} K_{\lambda\mu}(\mathbf{q}, 1/t)$$

Our Macdonald polynomials have Schur function expansion

$$\tilde{H}_\mu(x; q, t) = \sum_{\lambda} S_\lambda(x) \tilde{K}_{\lambda, \mu}(q, t)$$

where

$$\tilde{K}_{\lambda\mu}(\mathbf{q}, t) = t^{n(\mu)} K_{\lambda\mu}(\mathbf{q}, 1/t)$$

with $K_{\lambda\mu}(\mathbf{q}, t)$ the Macdonald q, t -Kostka coefficient.

Our Macdonald polynomials have Schur function expansion

$$\tilde{H}_\mu(x; q, t) = \sum_{\lambda} S_{\lambda}(x) \tilde{K}_{\lambda, \mu}(q, t)$$

where

$$\tilde{K}_{\lambda\mu}(\mathbf{q}, t) = t^{n(\mu)} K_{\lambda\mu}(\mathbf{q}, 1/t)$$

with $K_{\lambda\mu}(\mathbf{q}, t)$ the Macdonald q, t -Kostka coefficient.

$$\tilde{H}_{[3,2]}(x; q, t) =$$

Our Macdonald polynomials have Schur function expansion

$$\tilde{H}_\mu(x; q, t) = \sum_{\lambda} S_{\lambda}(x) \tilde{K}_{\lambda, \mu}(q, t)$$

where

$$\tilde{K}_{\lambda\mu}(\mathbf{q}, t) = t^{n(\mu)} K_{\lambda\mu}(\mathbf{q}, 1/t)$$

with $K_{\lambda\mu}(\mathbf{q}, t)$ the Macdonald q, t -Kostka coefficient.

$$\tilde{H}_{[3,2]}(x; q, t) = s_5 + s_{4,1} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} + s_{3,2} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} + s_{3,1,1} q \begin{bmatrix} 1 & 0 & 0 \\ 1 & 2 & 1 \\ 0 & 0 & 1 \end{bmatrix} +$$

Our Macdonald polynomials have Schur function expansion

$$\tilde{H}_\mu(x; q, t) = \sum_{\lambda} S_{\lambda}(x) \tilde{K}_{\lambda, \mu}(q, t)$$

where

$$\tilde{K}_{\lambda\mu}(\mathbf{q}, t) = t^{n(\mu)} K_{\lambda\mu}(\mathbf{q}, 1/t)$$

with $K_{\lambda\mu}(\mathbf{q}, t)$ the Macdonald q, t -Kostka coefficient.

$$\begin{aligned} \tilde{H}_{[3,2]}(x; q, t) = & s_5 + s_{4,1} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} + s_{3,2} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} + s_{3,1,1} q \begin{bmatrix} 1 & 0 & 0 \\ 1 & 2 & 1 \\ 0 & 0 & 1 \end{bmatrix} + \\ & + s_{2,2,1} q \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} + s_{2,1,1,1} t q^2 \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} + s_{1,1,1,1,1} t^2 q^4 \end{aligned}$$

Our Macdonald polynomials have Schur function expansion

$$\tilde{H}_\mu(x; q, t) = \sum_{\lambda} S_\lambda(x) \tilde{K}_{\lambda, \mu}(q, t)$$

where

$$\tilde{K}_{\lambda\mu}(\mathbf{q}, t) = t^{n(\mu)} K_{\lambda\mu}(\mathbf{q}, 1/t)$$

with $K_{\lambda\mu}(\mathbf{q}, t)$ the Macdonald q, t -Kostka coefficient.

$$\begin{aligned} \tilde{H}_{[3,2]}(x; q, t) = & s_5 + s_{4,1} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} + s_{3,2} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} + s_{3,1,1} q \begin{bmatrix} 1 & 0 & 0 \\ 1 & 2 & 1 \\ 0 & 0 & 1 \end{bmatrix} + \\ & + s_{2,2,1} q \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} + s_{2,1,1,1} t q^2 \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} + s_{1,1,1,1,1} t^2 q^4 \end{aligned}$$

next

The Jig Saw Puzzle

The Jig Saw Puzzle

of

The Jig Saw Puzzle

of

Schur Function Expansions

The Jig Saw Puzzle

$\tilde{H}_{[1,1,1,1]}(\mathbf{X}; \mathbf{q}, t)$

of

Schur Function Expansions

The Jig Saw Puzzle

$\tilde{H}_{[1,1,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{1,1,1,1} \\ s_{2,1,1} \\ s_{2,2} + s_{2,1,1} \\ s_{3,1} + s_{2,1,1} \\ s_{3,1} + s_{2,2} \\ s_{3,1} \\ s_4 \end{bmatrix}$$

of

Schur Function Expansions

next

The Jig Saw Puzzle

$\tilde{H}_{[1,1,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{1,1,1,1} \\ s_{2,1,1} \\ s_{2,2} + s_{2,1,1} \\ s_{3,1} + s_{2,1,1} \\ s_{3,1} + s_{2,2} \\ s_{3,1} \\ s_4 \end{bmatrix}$$

Frobenius characteristic of
the linear span
of derivatives of
the Vandermonde determinant

of
Schur Function Expansions

The Jig Saw Puzzle

$\tilde{H}_{[1,1,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{1,1,1,1} \\ s_{2,1,1} \\ s_{2,2} + s_{2,1,1} \\ s_{3,1} + s_{2,1,1} \\ s_{3,1} + s_{2,2} \\ s_{3,1} \\ s_4 \end{bmatrix}$$

Frobenius characteristic of
the linear span
of derivatives of
the Vandermonde determinant

$\tilde{H}_{[2,1,1]}[\mathbf{X}; \mathbf{q}, t]$

of
Schur Function Expansions

The Jig Saw Puzzle

$\tilde{H}_{[1,1,1,1]}[X; q, t]$

$$\begin{bmatrix} s_{1,1,1,1} \\ s_{2,1,1} \\ s_{2,2} + s_{2,1,1} \\ s_{3,1} + s_{2,1,1} \\ s_{3,1} + s_{2,2} \\ s_{3,1} \\ s_4 \end{bmatrix}$$

Frobenius characteristic of
the linear span
of derivatives of
the Vandermonde determinant

$\tilde{H}_{[2,1,1]}[X; q, t]$

$$\begin{bmatrix} s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} + s_{2,2} & s_{2,1,1} \\ s_{3,1} & s_{2,2} + s_{2,1,1} \\ s_4 & s_{3,1} \end{bmatrix}$$

of
Schur Function Expansions

The Jig Saw Puzzle

$\tilde{H}_{[1,1,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{1,1,1,1} \\ s_{2,1,1} \\ s_{2,2} + s_{2,1,1} \\ s_{3,1} + s_{2,1,1} \\ s_{3,1} + s_{2,2} \\ s_{3,1} \\ s_4 \end{bmatrix}$$

Frobenius characteristic of
the linear span
of derivatives of
the Vandermonde determinant

of

Schur Function Expansions

$\tilde{H}_{[2,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} + s_{2,2} & s_{2,1,1} \\ s_{3,1} & s_{2,2} + s_{2,1,1} \\ s_4 & s_{3,1} \end{bmatrix}$$

$\tilde{H}_{[4]}[\mathbf{X}; \mathbf{q}, t]$

The Jig Saw Puzzle

$\tilde{H}_{[1,1,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{1,1,1,1} \\ s_{2,1,1} \\ s_{2,2} + s_{2,1,1} \\ s_{3,1} + s_{2,1,1} \\ s_{3,1} + s_{2,2} \\ s_{3,1} \\ s_4 \end{bmatrix}$$

Frobenius characteristic of
the linear span
of derivatives of
the Vandermonde determinant

of

Schur Function Expansions

$\tilde{H}_{[2,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} + s_{2,2} & s_{2,1,1} \\ s_{3,1} & s_{2,2} + s_{2,1,1} \\ s_4 & s_{3,1} \end{bmatrix}$$

$\tilde{H}_{[4]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,2} & s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} & s_{3,1} + s_{2,1,1} & s_{2,1,1} \\ s_4 & s_{3,1} & s_{2,2} \end{bmatrix}$$

The Jig Saw Puzzle

$\tilde{H}_{[1,1,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{1,1,1,1} \\ s_{2,1,1} \\ s_{2,2} + s_{2,1,1} \\ s_{3,1} + s_{2,1,1} \\ s_{3,1} + s_{2,2} \\ s_{3,1} \\ s_4 \end{bmatrix}$$

Frobenius characteristic of
the linear span
of derivatives of
the Vandermonde determinant

of

Schur Function Expansions

$\tilde{H}_{[2,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} + s_{2,2} & s_{2,1,1} \\ s_{3,1} & s_{2,2} + s_{2,1,1} \\ s_4 & s_{3,1} \end{bmatrix}$$

$\tilde{H}_{[4]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,2} & s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} & s_{3,1} + s_{2,1,1} & s_{2,1,1} \\ s_4 & s_{3,1} & s_{2,2} \end{bmatrix}$$

$\tilde{H}_{[3,1]}[\mathbf{X}; \mathbf{q}, t]$

The Jig Saw Puzzle

$\tilde{H}_{[1,1,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{1,1,1,1} \\ s_{2,1,1} \\ s_{2,2} + s_{2,1,1} \\ s_{3,1} + s_{2,1,1} \\ s_{3,1} + s_{2,2} \\ s_{3,1} \\ s_4 \end{bmatrix}$$

Frobenius characteristic of
the linear span
of derivatives of
the Vandermonde determinant

of

Schur Function Expansions

$\tilde{H}_{[2,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} + s_{2,2} & s_{2,1,1} \\ s_{3,1} & s_{2,2} + s_{2,1,1} \\ s_4 & s_{3,1} \end{bmatrix}$$

$\tilde{H}_{[4]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,2} & s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} & s_{3,1} + s_{2,1,1} & s_{2,1,1} \\ s_4 & s_{3,1} & s_{2,2} \end{bmatrix}$$

$\tilde{H}_{[3,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{3,1} & s_{2,2} + s_{2,1,1} & s_{2,1,1} & s_{1,1,1,1} \\ s_4 & s_{3,1} & s_{3,1} + s_{2,2} & s_{2,1,1} \end{bmatrix}$$

The Jig Saw Puzzle

$\tilde{H}_{[1,1,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{1,1,1,1} \\ s_{2,1,1} \\ s_{2,2} + s_{2,1,1} \\ s_{3,1} + s_{2,1,1} \\ s_{3,1} + s_{2,2} \\ s_{3,1} \\ s_4 \end{bmatrix}$$

Frobenius characteristic of
the linear span
of derivatives of
the Vandermonde determinant

of

Schur Function Expansions

$\tilde{H}_{[2,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} + s_{2,2} & s_{2,1,1} \\ s_{3,1} & s_{2,2} + s_{2,1,1} \\ s_4 & s_{3,1} \end{bmatrix}$$

$\tilde{H}_{[4]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,2} & s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} & s_{3,1} + s_{2,1,1} & s_{2,1,1} \\ s_4 & s_{3,1} & s_{2,2} \end{bmatrix}$$

$\tilde{H}_{[3,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{3,1} & s_{2,2} + s_{2,1,1} & s_{2,1,1} & s_{1,1,1,1} \\ s_4 & s_{3,1} & s_{3,1} + s_{2,2} & s_{2,1,1} \end{bmatrix}$$

$\tilde{H}_{[2,2]}[\mathbf{X}; \mathbf{q}, t]$

The Jig Saw Puzzle

$\tilde{H}_{[1,1,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{1,1,1,1} \\ s_{2,1,1} \\ s_{2,2} + s_{2,1,1} \\ s_{3,1} + s_{2,1,1} \\ s_{3,1} + s_{2,2} \\ s_{3,1} \\ s_4 \end{bmatrix}$$

Frobenius characteristic of
the linear span
of derivatives of
the Vandermonde determinant

of

Schur Function Expansions

$\tilde{H}_{[2,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} + s_{2,2} & s_{2,1,1} \\ s_{3,1} & s_{2,2} + s_{2,1,1} \\ s_4 & s_{3,1} \end{bmatrix}$$

$\tilde{H}_{[4]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,2} & s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} & s_{3,1} + s_{2,1,1} & s_{2,1,1} \\ s_4 & s_{3,1} & s_{2,2} \end{bmatrix}$$

$\tilde{H}_{[3,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{3,1} & s_{2,2} + s_{2,1,1} & s_{2,1,1} & s_{1,1,1,1} \\ s_4 & s_{3,1} & s_{3,1} + s_{2,2} & s_{2,1,1} \end{bmatrix}$$

$\tilde{H}_{[2,2]}[\mathbf{X}; \mathbf{q}, t]$

$$[s_4, s_{3,1}, s_{3,1} + s_{2,2}, s_{3,1} + s_{2,1,1}, s_{2,2} + s_{2,1,1}, s_{2,1,1}, s_{1,1,1,1}]$$

next

The Jig Saw Puzzle

$\tilde{H}_{[1,1,1,1]}[\mathbf{X}; \mathbf{q}, t]$

Frobenius characteristic of
the linear span
of derivatives of
the Vandermonde determinant

$$\begin{bmatrix} s_{1,1,1,1} \\ s_{2,1,1} \\ s_{2,2} + s_{2,1,1} \\ s_{3,1} + s_{2,1,1} \\ s_{3,1} + s_{2,2} \\ s_{3,1} \\ s_4 \end{bmatrix}$$

of

Schur Function Expansions

$\tilde{H}_{[2,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} + s_{2,2} & s_{2,1,1} \\ s_{3,1} & s_{2,2} + s_{2,1,1} \\ s_4 & s_{3,1} \end{bmatrix}$$

$\tilde{H}_{[4]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,2} & s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} & s_{3,1} + s_{2,1,1} & s_{2,1,1} \\ s_4 & s_{3,1} & s_{2,2} \end{bmatrix}$$

$\tilde{H}_{[3,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{3,1} & s_{2,2} + s_{2,1,1} & s_{2,1,1} & s_{1,1,1,1} \\ s_4 & s_{3,1} & s_{3,1} + s_{2,2} & s_{2,1,1} \end{bmatrix}$$

$\tilde{H}_{[2,2]}[\mathbf{X}; \mathbf{q}, t]$

$$[s_4, s_{3,1}, s_{3,1} + s_{2,2}, s_{3,1} + s_{2,1,1}, s_{2,2} + s_{2,1,1}, s_{2,1,1}, s_{1,1,1,1}]$$

They are all
deformations
of
the S_n Harmonics

next

The Jig Saw Puzzle

$\tilde{H}_{[1,1,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{1,1,1,1} \\ s_{2,1,1} \\ s_{2,2} + s_{2,1,1} \\ s_{3,1} + s_{2,1,1} \\ s_{3,1} + s_{2,2} \\ s_{3,1} \\ s_4 \end{bmatrix}$$

Frobenius characteristic of the linear span of derivatives of the Vandermonde determinant

of Schur Function Expansions

What makes the Schur functions move???

$\tilde{H}_{[2,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} + s_{2,2} & s_{2,1,1} \\ s_{3,1} & s_{2,2} + s_{2,1,1} \\ s_4 & s_{3,1} \end{bmatrix}$$

$\tilde{H}_{[4]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,2} & s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} & s_{3,1} + s_{2,1,1} & s_{2,1,1} \\ s_4 & s_{3,1} & s_{2,2} \end{bmatrix}$$

$\tilde{H}_{[3,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{3,1} & s_{2,2} + s_{2,1,1} & s_{2,1,1} & s_{1,1,1,1} \\ s_4 & s_{3,1} & s_{3,1} + s_{2,2} & s_{2,1,1} \end{bmatrix}$$

$\tilde{H}_{[2,2]}[\mathbf{X}; \mathbf{q}, t]$

$$[s_4, s_{3,1}, s_{3,1} + s_{2,2}, s_{3,1} + s_{2,1,1}, s_{2,2} + s_{2,1,1}, s_{2,1,1}, s_{1,1,1,1}]$$

They are all deformations of the S_n Harmonics

The Jig Saw Puzzle

$\tilde{H}_{[1,1,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{1,1,1,1} \\ s_{2,1,1} \\ s_{2,2} + s_{2,1,1} \\ s_{3,1} + s_{2,1,1} \\ s_{3,1} + s_{2,2} \\ s_{3,1} \\ s_4 \end{bmatrix}$$

Frobenius characteristic of
the linear span
of derivatives of
the Vandermonde determinant

of
Schur Function Expansions

$\tilde{H}_{[2,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} + s_{2,2} & s_{2,1,1} \\ s_{3,1} & s_{2,2} + s_{2,1,1} \\ s_4 & s_{3,1} \end{bmatrix}$$

What makes
the Schur functions
move???

Macdonald Reciprocity

$\tilde{H}_{[4]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,2} & s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} & s_{3,1} + s_{2,1,1} & s_{2,1,1} \\ s_4 & s_{3,1} & s_{2,2} \end{bmatrix}$$

They are all
deformations
of
the S_n Harmonics

$\tilde{H}_{[3,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{3,1} & s_{2,2} + s_{2,1,1} & s_{2,1,1} & s_{1,1,1,1} \\ s_4 & s_{3,1} & s_{3,1} + s_{2,2} & s_{2,1,1} \end{bmatrix}$$

$\tilde{H}_{[2,2]}[\mathbf{X}; \mathbf{q}, t]$

$$[s_4, s_{3,1}, s_{3,1} + s_{2,2}, s_{3,1} + s_{2,1,1}, s_{2,2} + s_{2,1,1}, s_{2,1,1}, s_{1,1,1,1}]$$

The Jig Saw Puzzle

$\tilde{H}_{[1,1,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{1,1,1,1} \\ s_{2,1,1} \\ s_{2,2} + s_{2,1,1} \\ s_{3,1} + s_{2,1,1} \\ s_{3,1} + s_{2,2} \\ s_{3,1} \\ s_4 \end{bmatrix}$$

Frobenius characteristic of the linear span of derivatives of the Vandermonde determinant

$\tilde{H}_{[2,1,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} + s_{2,2} & s_{2,1,1} \\ s_{3,1} & s_{2,2} + s_{2,1,1} \\ s_4 & s_{3,1} \end{bmatrix}$$

$\tilde{H}_{[4]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,2} & s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} & s_{3,1} + s_{2,1,1} & s_{2,1,1} \\ s_4 & s_{3,1} & s_{2,2} \end{bmatrix}$$

of
Schur Function Expansions

What makes the Schur functions move???

Macdonald Reciprocity

$$\frac{\tilde{H}_\mu[B_\lambda(\mathbf{q}, t)]}{\Pi_\mu(\mathbf{q}, t)} = \frac{\tilde{H}_\lambda[B_\mu(\mathbf{q}, t)]}{\Pi_\lambda(\mathbf{q}, t)}$$

They are all deformations of the S_n Harmonics

$\tilde{H}_{[3,1]}[\mathbf{X}; \mathbf{q}, t]$

$$\begin{bmatrix} s_{3,1} & s_{2,2} + s_{2,1,1} & s_{2,1,1} & s_{1,1,1,1} \\ s_4 & s_{3,1} & s_{3,1} + s_{2,2} & s_{2,1,1} \end{bmatrix}$$

$\tilde{H}_{[2,2]}[\mathbf{X}; \mathbf{q}, t]$

$$[s_4, s_{3,1}, s_{3,1} + s_{2,2}, s_{3,1} + s_{2,1,1}, s_{2,2} + s_{2,1,1}, s_{2,1,1}, s_{1,1,1,1}]$$

next

The Jig Saw Puzzle

$\tilde{H}_{[1,1,1,1]}[X; \mathbf{q}, t]$

$$\begin{bmatrix} s_{1,1,1,1} \\ s_{2,1,1} \\ s_{2,2} + s_{2,1,1} \\ s_{3,1} + s_{2,1,1} \\ s_{3,1} + s_{2,2} \\ s_{3,1} \\ s_4 \end{bmatrix}$$

Frobenius characteristic of the linear span of derivatives of the Vandermonde determinant

$\tilde{H}_{[2,1,1]}[X; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} + s_{2,2} & s_{2,1,1} \\ s_{3,1} & s_{2,2} + s_{2,1,1} \\ s_4 & s_{3,1} \end{bmatrix}$$

$\tilde{H}_{[4]}[X; \mathbf{q}, t]$

$$\begin{bmatrix} s_{2,2} & s_{2,1,1} & s_{1,1,1,1} \\ s_{3,1} & s_{3,1} + s_{2,1,1} & s_{2,1,1} \\ s_4 & s_{3,1} & s_{2,2} \end{bmatrix}$$

They are all deformations of the S_n Harmonics

$\tilde{H}_{[3,1]}[X; \mathbf{q}, t]$

$$\begin{bmatrix} s_{3,1} & s_{2,2} + s_{2,1,1} & s_{2,1,1} & s_{1,1,1,1} \\ s_4 & s_{3,1} & s_{3,1} + s_{2,2} & s_{2,1,1} \end{bmatrix}$$

$\tilde{H}_{[2,2]}[X; \mathbf{q}, t]$

$$[s_4, s_{3,1}, s_{3,1} + s_{2,2}, s_{3,1} + s_{2,1,1}, s_{2,2} + s_{2,1,1}, s_{2,1,1}, s_{1,1,1,1}]$$

of Schur Function Expansions

What makes the Schur functions move???

Macdonald Reciprocity

$$\frac{\tilde{H}_\mu[B_\lambda(\mathbf{q}, t)]}{\Pi_\mu(\mathbf{q}, t)} = \frac{\tilde{H}_\lambda[B_\mu(\mathbf{q}, t)]}{\Pi_\lambda(\mathbf{q}, t)}$$

What else ?

k-Schur expansion of Macdonald Polynomials

k-Schur expansion of Macdonald Polynomials

(for 2 bounded partitions of 4)

k-Schur expansion of Macdonald Polynomials

(for 2 bounded partitions of 4)

$H([2, 2])$

k-Schur expansion of Macdonald Polynomials

(for 2 bounded partitions of 4)

$$H([2, 2]) = q^2 A_{1,1,1,1} + (q + tq) A_{2,1,1} + A_{2,2}$$

k-Schur expansion of Macdonald Polynomials

(for 2 bounded partitions of 4)

$$H([2, 2]) = q^2 A_{1,1,1,1} + (q + tq) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} 0 & A_{2,1,1} & 0 \\ A_{2,2} & A_{2,1,1} & A_{1,1,1,1} \end{bmatrix}$$

k-Schur expansion of Macdonald Polynomials

(for 2 bounded partitions of 4)

$$H([2,2]) = q^2 A_{1,1,1,1} + (q + tq) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} 0 & A_{2,1,1} & 0 \\ A_{2,2} & A_{2,1,1} & A_{1,1,1,1} \end{bmatrix}$$

$$H([2,1,1])$$

k-Schur expansion of Macdonald Polynomials

(for 2 bounded partitions of 4)

$$H([2, 2]) = q^2 A_{1,1,1,1} + (q + tq) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} 0 & A_{2,1,1} & 0 \\ A_{2,2} & A_{2,1,1} & A_{1,1,1,1} \end{bmatrix}$$

$$H([2, 1, 1]) = tq A_{1,1,1,1} + (q + t^2) A_{2,1,1} + A_{2,2}$$

k-Schur expansion of Macdonald Polynomials

(for 2 bounded partitions of 4)

$$H([2, 2]) = q^2 A_{1,1,1,1} + (q + tq) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} 0 & A_{2,1,1} & 0 \\ A_{2,2} & A_{2,1,1} & A_{1,1,1,1} \end{bmatrix}$$

$$H([2, 1, 1]) = tq A_{1,1,1,1} + (q + t^2) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} A_{2,1,1} & 0 \\ 0 & A_{1,1,1,1} \\ A_{2,2} & A_{2,1,1} \end{bmatrix}$$

k-Schur expansion of Macdonald Polynomials

(for 2 bounded partitions of 4)

$$H([2, 2]) = q^2 A_{1,1,1,1} + (q + tq) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} 0 & A_{2,1,1} & 0 \\ A_{2,2} & A_{2,1,1} & A_{1,1,1,1} \end{bmatrix}$$

$$H([2, 1, 1]) = tq A_{1,1,1,1} + (q + t^2) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} A_{2,1,1} & 0 \\ 0 & A_{1,1,1,1} \\ A_{2,2} & A_{2,1,1} \end{bmatrix}$$

$$H([1, 1, 1, 1])$$

k-Schur expansion of Macdonald Polynomials

(for 2 bounded partitions of 4)

$$H([2, 2]) = q^2 A_{1,1,1,1} + (q + tq) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} 0 & A_{2,1,1} & 0 \\ A_{2,2} & A_{2,1,1} & A_{1,1,1,1} \end{bmatrix}$$

$$H([2, 1, 1]) = tq A_{1,1,1,1} + (q + t^2) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} A_{2,1,1} & 0 \\ 0 & A_{1,1,1,1} \\ A_{2,2} & A_{2,1,1} \end{bmatrix}$$

$$H([1, 1, 1, 1]) = t^4 A_{1,1,1,1} + (t^2 + t^3) A_{2,1,1} + A_{2,2}$$

k-Schur expansion of Macdonald Polynomials

(for 2 bounded partitions of 4)

$$H([2, 2]) = q^2 A_{1,1,1,1} + (q + tq) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} 0 & A_{2,1,1} & 0 \\ A_{2,2} & A_{2,1,1} & A_{1,1,1,1} \end{bmatrix}$$

$$H([2, 1, 1]) = tq A_{1,1,1,1} + (q + t^2) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} A_{2,1,1} & 0 \\ 0 & A_{1,1,1,1} \\ A_{2,2} & A_{2,1,1} \end{bmatrix}$$

$$H([1, 1, 1, 1]) = t^4 A_{1,1,1,1} + (t^2 + t^3) A_{2,1,1} + A_{2,2}$$

$$\begin{bmatrix} A_{1,1,1,1} \\ A_{2,1,1} \\ A_{2,1,1} \\ 0 \\ A_{2,2} \end{bmatrix}$$

k-Schur expansion of Macdonald Polynomials

(for 2 bounded partitions of 4)

$$H([2, 2]) = q^2 A_{1,1,1,1} + (q + tq) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} 0 & A_{2,1,1} & 0 \\ A_{2,2} & A_{2,1,1} & A_{1,1,1,1} \end{bmatrix}$$

$$H([2, 1, 1]) = tq A_{1,1,1,1} + (q + t^2) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} A_{2,1,1} & 0 \\ 0 & A_{1,1,1,1} \\ A_{2,2} & A_{2,1,1} \end{bmatrix}$$

$$H([1, 1, 1, 1]) = t^4 A_{1,1,1,1} + (t^2 + t^3) A_{2,1,1} + A_{2,2}$$

$$\begin{bmatrix} A_{1,1,1,1} \\ A_{2,1,1} \\ A_{2,1,1} \\ 0 \\ A_{2,2} \end{bmatrix}$$

next

k-Schur expansion of Macdonald Polynomials

(for 2 bounded partitions of 4)

$$H([2, 2]) = q^2 A_{1,1,1,1} + (q + tq) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} 0 & A_{2,1,1} & 0 \\ A_{2,2} & A_{2,1,1} & A_{1,1,1,1} \end{bmatrix}$$

$$H([2, 1, 1]) = tq A_{1,1,1,1} + (q + t^2) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} A_{2,1,1} & 0 \\ 0 & A_{1,1,1,1} \\ A_{2,2} & A_{2,1,1} \end{bmatrix}$$

$$H([1, 1, 1, 1]) = t^4 A_{1,1,1,1} + (t^2 + t^3) A_{2,1,1} + A_{2,2}$$

$$\begin{bmatrix} A_{1,1,1,1} \\ A_{2,1,1} \\ A_{2,1,1} \\ 0 \\ A_{2,2} \end{bmatrix}$$

(for 2 bounded partitions of 6)

next

k-Schur expansion of Macdonald Polynomials

(for 2 bounded partitions of 4)

$$H([2, 2]) = q^2 A_{1,1,1,1} + (q + tq) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} 0 & A_{2,1,1} & 0 \\ A_{2,2} & A_{2,1,1} & A_{1,1,1,1} \end{bmatrix}$$

$$H([2, 1, 1]) = tq A_{1,1,1,1} + (q + t^2) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} A_{2,1,1} & 0 \\ 0 & A_{1,1,1,1} \\ A_{2,2} & A_{2,1,1} \end{bmatrix}$$

$$H([1, 1, 1, 1]) = t^4 A_{1,1,1,1} + (t^2 + t^3) A_{2,1,1} + A_{2,2}$$

$$\begin{bmatrix} A_{1,1,1,1} \\ A_{2,1,1} \\ A_{2,1,1} \\ 0 \\ A_{2,2} \end{bmatrix}$$

(for 2 bounded partitions of 6)

$$H_{2,2,2} \rightarrow , \begin{bmatrix} 0 & A_{2,2,1,1} & A_{2,1,1,1,1} & 0 \\ 0 & A_{2,2,1,1} & A_{2,1,1,1,1} & 0 \\ A_{2,2,2} & A_{2,2,1,1} & A_{2,1,1,1,1} & A_{1,1,1,1,1,1} \end{bmatrix}$$

next

k-Schur expansion of Macdonald Polynomials

(for 2 bounded partitions of 4)

$$H([2,2]) = q^2 A_{1,1,1,1} + (q + tq) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} 0 & A_{2,1,1} & 0 \\ A_{2,2} & A_{2,1,1} & A_{1,1,1,1} \end{bmatrix}$$

$$H([2,1,1]) = tq A_{1,1,1,1} + (q + t^2) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} A_{2,1,1} & 0 \\ 0 & A_{1,1,1,1} \\ A_{2,2} & A_{2,1,1} \end{bmatrix}$$

$$H([1,1,1,1]) = t^4 A_{1,1,1,1} + (t^2 + t^3) A_{2,1,1} + A_{2,2}$$

$$\begin{bmatrix} A_{1,1,1,1} \\ A_{2,1,1} \\ A_{2,1,1} \\ 0 \\ A_{2,2} \end{bmatrix}$$

(for 2 bounded partitions of 6)

$$H_{2,2,2} \rightarrow , \begin{bmatrix} 0 & A_{2,2,1,1} & A_{2,1,1,1,1} & 0 \\ 0 & A_{2,2,1,1} & A_{2,1,1,1,1} & 0 \\ A_{2,2,2} & A_{2,2,1,1} & A_{2,1,1,1,1} & A_{1,1,1,1,1,1} \end{bmatrix}$$

$$H_{2,2,1,1} \rightarrow , \begin{bmatrix} A_{2,2,1,1} & A_{2,1,1,1,1} & 0 \\ 0 & A_{2,1,1,1,1} & 0 \\ 0 & A_{2,2,1,1} & A_{1,1,1,1,1,1} \\ A_{2,2,2} & A_{2,2,1,1} & A_{2,1,1,1,1} \end{bmatrix}$$

next

k-Schur expansion of Macdonald Polynomials

(for 2 bounded partitions of 4)

$$H([2,2]) = q^2 A_{1,1,1,1} + (q + tq) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} 0 & A_{2,1,1} & 0 \\ A_{2,2} & A_{2,1,1} & A_{1,1,1,1} \end{bmatrix}$$

$$H([2,1,1]) = tq A_{1,1,1,1} + (q + t^2) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} A_{2,1,1} & 0 \\ 0 & A_{1,1,1,1} \\ A_{2,2} & A_{2,1,1} \end{bmatrix}$$

$$H([1,1,1,1]) = t^4 A_{1,1,1,1} + (t^2 + t^3) A_{2,1,1} + A_{2,2}$$

$$\begin{bmatrix} A_{1,1,1,1} \\ A_{2,1,1} \\ A_{2,1,1} \\ 0 \\ A_{2,2} \end{bmatrix}$$

(for 2 bounded partitions of 6)

$$H_{2,2,2} \rightarrow , \begin{bmatrix} 0 & A_{2,2,1,1} & A_{2,1,1,1,1} & 0 \\ 0 & A_{2,2,1,1} & A_{2,1,1,1,1} & 0 \\ A_{2,2,2} & A_{2,2,1,1} & A_{2,1,1,1,1} & A_{1,1,1,1,1,1} \end{bmatrix}$$

$$H_{2,2,1,1} \rightarrow , \begin{bmatrix} A_{2,2,1,1} & A_{2,1,1,1,1} & 0 \\ 0 & A_{2,1,1,1,1} & 0 \\ 0 & A_{2,2,1,1} & A_{1,1,1,1,1,1} \\ A_{2,2,2} & A_{2,2,1,1} & A_{2,1,1,1,1} \end{bmatrix}$$

$$H_{2,1,1,1,1} \rightarrow , \begin{bmatrix} A_{2,1,1,1,1} & 0 \\ 0 & 0 \\ A_{2,2,1,1} & A_{1,1,1,1,1,1} \\ A_{2,2,1,1} & A_{2,1,1,1,1} \\ 0 & A_{2,1,1,1,1} \\ 0 & 0 \\ A_{2,2,2} & A_{2,2,1,1} \end{bmatrix}$$

next

k-Schur expansion of Macdonald Polynomials

(for 2 bounded partitions of 4)

$$H([2, 2]) = q^2 A_{1,1,1,1} + (q + tq) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} 0 & A_{2,1,1} & 0 \\ A_{2,2} & A_{2,1,1} & A_{1,1,1,1} \end{bmatrix}$$

$$H([2, 1, 1]) = tq A_{1,1,1,1} + (q + t^2) A_{2,1,1} + A_{2,2} \quad \begin{bmatrix} A_{2,1,1} & 0 \\ 0 & A_{1,1,1,1} \\ A_{2,2} & A_{2,1,1} \end{bmatrix}$$

$$H([1, 1, 1, 1]) = t^4 A_{1,1,1,1} + (t^2 + t^3) A_{2,1,1} + A_{2,2}$$

$$\begin{bmatrix} A_{1,1,1,1} \\ A_{2,1,1} \\ A_{2,1,1} \\ 0 \\ A_{2,2} \end{bmatrix}$$

(for 2 bounded partitions of 6)

$$H_{2,2,2} \rightarrow , \begin{bmatrix} 0 & A_{2,2,1,1} & A_{2,1,1,1,1} & 0 \\ 0 & A_{2,2,1,1} & A_{2,1,1,1,1} & 0 \\ A_{2,2,2} & A_{2,2,1,1} & A_{2,1,1,1,1} & A_{1,1,1,1,1,1} \end{bmatrix}$$

$$H_{2,2,1,1} \rightarrow , \begin{bmatrix} A_{2,2,1,1} & A_{2,1,1,1,1} & 0 \\ 0 & A_{2,1,1,1,1} & 0 \\ 0 & A_{2,2,1,1} & A_{1,1,1,1,1,1} \\ A_{2,2,2} & A_{2,2,1,1} & A_{2,1,1,1,1} \end{bmatrix}$$

$$H_{2,1,1,1,1} \rightarrow , \begin{bmatrix} A_{2,1,1,1,1} & 0 \\ 0 & 0 \\ A_{2,2,1,1} & A_{1,1,1,1,1,1} \\ A_{2,2,1,1} & A_{2,1,1,1,1} \\ 0 & A_{2,1,1,1,1} \\ 0 & 0 \\ A_{2,2,2} & A_{2,2,1,1} \end{bmatrix}$$

$$H_{1,1,1,1,1,1} \rightarrow , \begin{bmatrix} A_{1,1,1,1,1,1} \\ A_{2,1,1,1,1} \\ A_{2,1,1,1,1} \\ A_{2,1,1,1,1} \\ A_{2,2,1,1} \\ A_{2,2,1,1} \\ A_{2,2,1,1} \\ 0 \\ 0 \\ A_{2,2,2} \end{bmatrix}$$

next


Some remarkable determinants

Some remarkable determinants

(1,0)	(1,1)
(0,0)	(0,1)

Some remarkable determinants

(1,0)	(1,1)
(0,0)	(0,1)



Some remarkable determinants

(1,0)	(1,1)
(0,0)	(0,1)

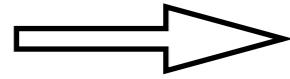


$$\Delta_{2,2}(\mathbf{X}, \mathbf{Y}) = \det$$

$$\begin{pmatrix} x_1^0 y_1^0 & x_2^0 y_2^0 & x_3^0 y_3^0 & x_4^0 y_4^0 \\ x_1^0 y_1^1 & x_2^0 y_2^1 & x_3^0 y_3^1 & x_4^0 y_4^1 \\ x_1^1 y_1^0 & x_2^1 y_2^0 & x_3^1 y_3^0 & x_4^1 y_4^0 \\ x_1^1 y_1^1 & x_2^1 y_2^1 & x_3^1 y_3^1 & x_4^1 y_4^1 \end{pmatrix}$$

Some remarkable determinants

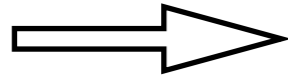
(1,0)	(1,1)
(0,0)	(0,1)



$$\Delta_{2,2}(X, Y) = \det \begin{pmatrix} x_1^0 y_1^0 & x_2^0 y_2^0 & x_3^0 y_3^0 & x_4^0 y_4^0 \\ x_1^0 y_1^1 & x_2^0 y_2^1 & x_3^0 y_3^1 & x_4^0 y_4^1 \\ x_1^1 y_1^0 & x_2^1 y_2^0 & x_3^1 y_3^0 & x_4^1 y_4^0 \\ x_1^1 y_1^1 & x_2^1 y_2^1 & x_3^1 y_3^1 & x_4^1 y_4^1 \end{pmatrix} = \det \begin{pmatrix} 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 \\ x_1 & x_2 & x_3 & x_4 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 \end{pmatrix}$$

Some remarkable determinants

(1,0)	(1,1)
(0,0)	(0,1)



$$\Delta_{2,2}(X, Y) = \det \begin{pmatrix} x_1^0 y_1^0 & x_2^0 y_2^0 & x_3^0 y_3^0 & x_4^0 y_4^0 \\ x_1^0 y_1^1 & x_2^0 y_2^1 & x_3^0 y_3^1 & x_4^0 y_4^1 \\ x_1^1 y_1^0 & x_2^1 y_2^0 & x_3^1 y_3^0 & x_4^1 y_4^0 \\ x_1^1 y_1^1 & x_2^1 y_2^1 & x_3^1 y_3^1 & x_4^1 y_4^1 \end{pmatrix} = \det \begin{pmatrix} 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 \\ x_1 & x_2 & x_3 & x_4 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 \end{pmatrix}$$

(2,0)		
(1,0)	(1,1)	(1,2)
(0,0)	(0,1)	(0,2)

Some remarkable determinants

(1,0)	(1,1)
(0,0)	(0,1)



$\Delta_{2,2}(X, Y)$

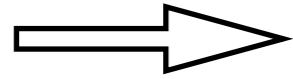
$$= \det \begin{pmatrix} x_1^0 y_1^0 & x_2^0 y_2^0 & x_3^0 y_3^0 & x_4^0 y_4^0 \\ x_1^0 y_1^1 & x_2^0 y_2^1 & x_3^0 y_3^1 & x_4^0 y_4^1 \\ x_1^1 y_1^0 & x_2^1 y_2^0 & x_3^1 y_3^0 & x_4^1 y_4^0 \\ x_1^1 y_1^1 & x_2^1 y_2^1 & x_3^1 y_3^1 & x_4^1 y_4^1 \end{pmatrix} = \det \begin{pmatrix} 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 \\ x_1 & x_2 & x_3 & x_4 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 \end{pmatrix}$$

(2,0)		
(1,0)	(1,1)	(1,2)
(0,0)	(0,1)	(0,2)



Some remarkable determinants

(1,0)	(1,1)
(0,0)	(0,1)



$$\Delta_{2,2}(X, Y) = \det \begin{pmatrix} x_1^0 y_1^0 & x_2^0 y_2^0 & x_3^0 y_3^0 & x_4^0 y_4^0 \\ x_1^0 y_1^1 & x_2^0 y_2^1 & x_3^0 y_3^1 & x_4^0 y_4^1 \\ x_1^1 y_1^0 & x_2^1 y_2^0 & x_3^1 y_3^0 & x_4^1 y_4^0 \\ x_1^1 y_1^1 & x_2^1 y_2^1 & x_3^1 y_3^1 & x_4^1 y_4^1 \end{pmatrix} = \det \begin{pmatrix} 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 \\ x_1 & x_2 & x_3 & x_4 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 \end{pmatrix}$$

(2,0)		
(1,0)	(1,1)	(1,2)
(0,0)	(0,1)	(0,2)



$$\Delta_{331}(X, Y) = \det \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 & y_5 & y_5 & y_7 \\ y_1^2 & y_2^2 & y_3^2 & y_4^2 & y_5^2 & y_6^2 & y_7^2 \\ x_1 & x_2 & x_3 & x_4 & x_5 & x_6 & x_7 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 & x_5 y_5 & x_6 y_6 & x_7 y_7 \\ x_1 y_1^2 & x_2 y_2^2 & x_3 y_3^2 & x_4 y_4^2 & x_5 y_5^2 & x_6 y_6^2 & x_7 y_7^2 \\ x_1^2 & x_2^2 & x_3^2 & x_4^2 & x_5^2 & x_6^2 & x_7^2 \end{pmatrix}$$

Some remarkable determinants

(1,0)	(1,1)
(0,0)	(0,1)



$$\Delta_{2,2}(X, Y) = \det \begin{pmatrix} x_1^0 y_1^0 & x_2^0 y_2^0 & x_3^0 y_3^0 & x_4^0 y_4^0 \\ x_1^0 y_1^1 & x_2^0 y_2^1 & x_3^0 y_3^1 & x_4^0 y_4^1 \\ x_1^1 y_1^0 & x_2^1 y_2^0 & x_3^1 y_3^0 & x_4^1 y_4^0 \\ x_1^1 y_1^1 & x_2^1 y_2^1 & x_3^1 y_3^1 & x_4^1 y_4^1 \end{pmatrix} = \det \begin{pmatrix} 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 \\ x_1 & x_2 & x_3 & x_4 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 \end{pmatrix}$$

(2,0)		
(1,0)	(1,1)	(1,2)
(0,0)	(0,1)	(0,2)

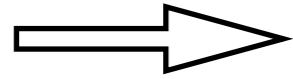


$$\Delta_{331}(X, Y) = \det \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 & y_5 & y_5 & y_7 \\ y_1^2 & y_2^2 & y_3^2 & y_4^2 & y_5^2 & y_6^2 & y_7^2 \\ x_1 & x_2 & x_3 & x_4 & x_5 & x_6 & x_7 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 & x_5 y_5 & x_6 y_6 & x_7 y_7 \\ x_1 y_1^2 & x_2 y_2^2 & x_3 y_3^2 & x_4 y_4^2 & x_5 y_5^2 & x_6 y_6^2 & x_7 y_7^2 \\ x_1^2 & x_2^2 & x_3^2 & x_4^2 & x_5^2 & x_6^2 & x_7^2 \end{pmatrix}$$

General definition

Some remarkable determinants

(1,0)	(1,1)
(0,0)	(0,1)



$$\Delta_{2,2}(X, Y) = \det \begin{pmatrix} x_1^0 y_1^0 & x_2^0 y_2^0 & x_3^0 y_3^0 & x_4^0 y_4^0 \\ x_1^0 y_1^1 & x_2^0 y_2^1 & x_3^0 y_3^1 & x_4^0 y_4^1 \\ x_1^1 y_1^0 & x_2^1 y_2^0 & x_3^1 y_3^0 & x_4^1 y_4^0 \\ x_1^1 y_1^1 & x_2^1 y_2^1 & x_3^1 y_3^1 & x_4^1 y_4^1 \end{pmatrix} = \det \begin{pmatrix} 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 \\ x_1 & x_2 & x_3 & x_4 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 \end{pmatrix}$$

(2,0)		
(1,0)	(1,1)	(1,2)
(0,0)	(0,1)	(0,2)



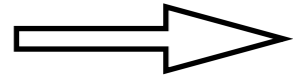
$$\Delta_{331}(X, Y) = \det \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 & y_5 & y_5 & y_7 \\ y_1^2 & y_2^2 & y_3^2 & y_4^2 & y_5^2 & y_6^2 & y_7^2 \\ x_1 & x_2 & x_3 & x_4 & x_5 & x_6 & x_7 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 & x_5 y_5 & x_6 y_6 & x_7 y_7 \\ x_1 y_1^2 & x_2 y_2^2 & x_3 y_3^2 & x_4 y_4^2 & x_5 y_5^2 & x_6 y_6^2 & x_7 y_7^2 \\ x_1^2 & x_2^2 & x_3^2 & x_4^2 & x_5^2 & x_6^2 & x_7^2 \end{pmatrix}$$

General definition

If $(p_1, q_1), (p_2, q_2), \dots, (p_n, q_n)$ are the cells of the Ferrers diagram of $\mu \vdash n$ then

Some remarkable determinants

(1,0)	(1,1)
(0,0)	(0,1)



$$\Delta_{2,2}(X, Y) = \det \begin{pmatrix} x_1^0 y_1^0 & x_2^0 y_2^0 & x_3^0 y_3^0 & x_4^0 y_4^0 \\ x_1^0 y_1^1 & x_2^0 y_2^1 & x_3^0 y_3^1 & x_4^0 y_4^1 \\ x_1^1 y_1^0 & x_2^1 y_2^0 & x_3^1 y_3^0 & x_4^1 y_4^0 \\ x_1^1 y_1^1 & x_2^1 y_2^1 & x_3^1 y_3^1 & x_4^1 y_4^1 \end{pmatrix} = \det \begin{pmatrix} 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 \\ x_1 & x_2 & x_3 & x_4 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 \end{pmatrix}$$

(2,0)		
(1,0)	(1,1)	(1,2)
(0,0)	(0,1)	(0,2)



$$\Delta_{331}(X, Y) = \det \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 & y_5 & y_5 & y_7 \\ y_1^2 & y_2^2 & y_3^2 & y_4^2 & y_5^2 & y_6^2 & y_7^2 \\ x_1 & x_2 & x_3 & x_4 & x_5 & x_6 & x_7 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 & x_5 y_5 & x_6 y_6 & x_7 y_7 \\ x_1 y_1^2 & x_2 y_2^2 & x_3 y_3^2 & x_4 y_4^2 & x_5 y_5^2 & x_6 y_6^2 & x_7 y_7^2 \\ x_1^2 & x_2^2 & x_3^2 & x_4^2 & x_5^2 & x_6^2 & x_7^2 \end{pmatrix}$$

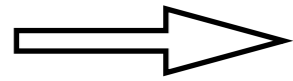
General definition

If $(p_1, q_1), (p_2, q_2), \dots, (p_n, q_n)$ are the cells of the Ferrers diagram of $\mu \vdash n$ then

$$\Delta_\mu(x, y) = \det \|x_j^{p_i} y_j^{q_i}\|_{i,j=1}^n$$

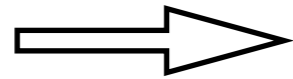
Some remarkable determinants

(1,0)	(1,1)
(0,0)	(0,1)



$$\Delta_{2,2}(X, Y) = \det \begin{pmatrix} x_1^0 y_1^0 & x_2^0 y_2^0 & x_3^0 y_3^0 & x_4^0 y_4^0 \\ x_1^0 y_1^1 & x_2^0 y_2^1 & x_3^0 y_3^1 & x_4^0 y_4^1 \\ x_1^1 y_1^0 & x_2^1 y_2^0 & x_3^1 y_3^0 & x_4^1 y_4^0 \\ x_1^1 y_1^1 & x_2^1 y_2^1 & x_3^1 y_3^1 & x_4^1 y_4^1 \end{pmatrix} = \det \begin{pmatrix} 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 \\ x_1 & x_2 & x_3 & x_4 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 \end{pmatrix}$$

(2,0)		
(1,0)	(1,1)	(1,2)
(0,0)	(0,1)	(0,2)



$$\Delta_{331}(X, Y) = \det \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 & y_5 & y_5 & y_7 \\ y_1^2 & y_2^2 & y_3^2 & y_4^2 & y_5^2 & y_6^2 & y_7^2 \\ x_1 & x_2 & x_3 & x_4 & x_5 & x_6 & x_7 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 & x_5 y_5 & x_6 y_6 & x_7 y_7 \\ x_1 y_1^2 & x_2 y_2^2 & x_3 y_3^2 & x_4 y_4^2 & x_5 y_5^2 & x_6 y_6^2 & x_7 y_7^2 \\ x_1^2 & x_2^2 & x_3^2 & x_4^2 & x_5^2 & x_6^2 & x_7^2 \end{pmatrix}$$

General definition

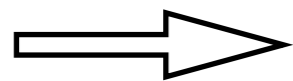
If $(p_1, q_1), (p_2, q_2), \dots, (p_n, q_n)$ are the cells of the Ferrers diagram of $\mu \vdash n$ then

$$\Delta_\mu(x, y) = \det \|x_j^{p_i} y_j^{q_i}\|_{i,j=1}^n$$

The linear span of all the partial derivatives of $\Delta_\mu(x, y)$ is denoted $M_\mu[X, Y]$

Some remarkable determinants

(1,0)	(1,1)
(0,0)	(0,1)



$$\Delta_{2,2}(X, Y) = \det \begin{pmatrix} x_1^0 y_1^0 & x_2^0 y_2^0 & x_3^0 y_3^0 & x_4^0 y_4^0 \\ x_1^0 y_1^1 & x_2^0 y_2^1 & x_3^0 y_3^1 & x_4^0 y_4^1 \\ x_1^1 y_1^0 & x_2^1 y_2^0 & x_3^1 y_3^0 & x_4^1 y_4^0 \\ x_1^1 y_1^1 & x_2^1 y_2^1 & x_3^1 y_3^1 & x_4^1 y_4^1 \end{pmatrix} = \det \begin{pmatrix} 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 \\ x_1 & x_2 & x_3 & x_4 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 \end{pmatrix}$$

(2,0)		
(1,0)	(1,1)	(1,2)
(0,0)	(0,1)	(0,2)



$$\Delta_{331}(X, Y) = \det \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 & y_5 & y_5 & y_7 \\ y_1^2 & y_2^2 & y_3^2 & y_4^2 & y_5^2 & y_6^2 & y_7^2 \\ x_1 & x_2 & x_3 & x_4 & x_5 & x_6 & x_7 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 & x_5 y_5 & x_6 y_6 & x_7 y_7 \\ x_1 y_1^2 & x_2 y_2^2 & x_3 y_3^2 & x_4 y_4^2 & x_5 y_5^2 & x_6 y_6^2 & x_7 y_7^2 \\ x_1^2 & x_2^2 & x_3^2 & x_4^2 & x_5^2 & x_6^2 & x_7^2 \end{pmatrix}$$

General definition

If $(p_1, q_1), (p_2, q_2), \dots, (p_n, q_n)$ are the cells of the Ferrers diagram of $\mu \vdash n$ then

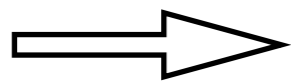
$$\Delta_\mu(x, y) = \det \|x_j^{p_i} y_j^{q_i}\|_{i,j=1}^n$$

The linear span of all the partial derivatives of $\Delta_\mu(x, y)$ is denoted $M_\mu[X, Y]$

$$M_\mu[X, Y] = \mathcal{L} [\partial_x^p \partial_y^q \Delta_\mu(x, y)]$$

Some remarkable determinants

(1,0)	(1,1)
(0,0)	(0,1)



$$\Delta_{2,2}(X, Y) = \det \begin{pmatrix} x_1^0 y_1^0 & x_2^0 y_2^0 & x_3^0 y_3^0 & x_4^0 y_4^0 \\ x_1^0 y_1^1 & x_2^0 y_2^1 & x_3^0 y_3^1 & x_4^0 y_4^1 \\ x_1^1 y_1^0 & x_2^1 y_2^0 & x_3^1 y_3^0 & x_4^1 y_4^0 \\ x_1^1 y_1^1 & x_2^1 y_2^1 & x_3^1 y_3^1 & x_4^1 y_4^1 \end{pmatrix} = \det \begin{pmatrix} 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 \\ x_1 & x_2 & x_3 & x_4 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 \end{pmatrix}$$

(2,0)		
(1,0)	(1,1)	(1,2)
(0,0)	(0,1)	(0,2)



$$\Delta_{331}(X, Y) = \det \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 & y_5 & y_5 & y_7 \\ y_1^2 & y_2^2 & y_3^2 & y_4^2 & y_5^2 & y_6^2 & y_7^2 \\ x_1 & x_2 & x_3 & x_4 & x_5 & x_6 & x_7 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 & x_5 y_5 & x_6 y_6 & x_7 y_7 \\ x_1 y_1^2 & x_2 y_2^2 & x_3 y_3^2 & x_4 y_4^2 & x_5 y_5^2 & x_6 y_6^2 & x_7 y_7^2 \\ x_1^2 & x_2^2 & x_3^2 & x_4^2 & x_5^2 & x_6^2 & x_7^2 \end{pmatrix}$$

General definition

If $(p_1, q_1), (p_2, q_2), \dots, (p_n, q_n)$ are the cells of the Ferrers diagram of $\mu \vdash n$ then

$$\Delta_\mu(x, y) = \det \|x_j^{p_i} y_j^{q_i}\|_{i,j=1}^n$$

The linear span of all the partial derivatives of $\Delta_\mu(x, y)$ is denoted $M_\mu[X, Y]$

In symbols

$$M_\mu[X, Y] = \mathcal{L} [\partial_x^p \partial_y^q \Delta_\mu(x, y)]$$

Some remarkable determinants

(1,0)	(1,1)
(0,0)	(0,1)

 $\longrightarrow \Delta_{2,2}(X, Y) = \det \begin{pmatrix} x_1^0 y_1^0 & x_2^0 y_2^0 & x_3^0 y_3^0 & x_4^0 y_4^0 \\ x_1^0 y_1^1 & x_2^0 y_2^1 & x_3^0 y_3^1 & x_4^0 y_4^1 \\ x_1^1 y_1^0 & x_2^1 y_2^0 & x_3^1 y_3^0 & x_4^1 y_4^0 \\ x_1^1 y_1^1 & x_2^1 y_2^1 & x_3^1 y_3^1 & x_4^1 y_4^1 \end{pmatrix} = \det \begin{pmatrix} 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 \\ x_1 & x_2 & x_3 & x_4 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 \end{pmatrix}$

(2,0)		
(1,0)	(1,1)	(1,2)
(0,0)	(0,1)	(0,2)

 $\longrightarrow \Delta_{331}(X, Y) = \det \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ y_1 & y_2 & y_3 & y_4 & y_5 & y_5 & y_7 \\ y_1^2 & y_2^2 & y_3^2 & y_4^2 & y_5^2 & y_6^2 & y_7^2 \\ x_1 & x_2 & x_3 & x_4 & x_5 & x_6 & x_7 \\ x_1 y_1 & x_2 y_2 & x_3 y_3 & x_4 y_4 & x_5 y_5 & x_6 y_6 & x_7 y_7 \\ x_1 y_1^2 & x_2 y_2^2 & x_3 y_3^2 & x_4 y_4^2 & x_5 y_5^2 & x_6 y_6^2 & x_7 y_7^2 \\ x_1^2 & x_2^2 & x_3^2 & x_4^2 & x_5^2 & x_6^2 & x_7^2 \end{pmatrix}$

General definition

If $(p_1, q_1), (p_2, q_2), \dots, (p_n, q_n)$ are the cells of the Ferrers diagram of $\mu \vdash n$ then

$$\Delta_\mu(x, y) = \det \|x_j^{p_i} y_j^{q_i}\|_{i,j=1}^n$$

The linear span of all the partial derivatives of $\Delta_\mu(x, y)$ is denoted $M_\mu[X, Y]$

In symbols

$$M_\mu[X, Y] = \mathcal{L} \left[\partial_x^p \partial_y^q \Delta_\mu(x, y) \right]$$

next

Brief review

Theorem

Brief review

Theorem (easy)

Brief review

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most n !

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq \mathbf{n}!$$

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq \mathbf{n}!$$

For example

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);
```

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

$$\mathbf{DDmu}([2, 1]); \quad \begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2,1]);
```

$$\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

```
D21:=det(");
```

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);
```

$$\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

```
D21:=det(");
```

$$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$$

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);
```

$$\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

```
D21:=det(");
```

$$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$$

```
diff(D21, x1);
```

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);
```

$$\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

```
D21:=det(");
```

$$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$$

```
diff(D21, x1);
```

$$y3 - y2$$

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);
```

$$\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

```
D21:=det(");
```

$$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$$

```
diff(D21, x1);
```

$$y3 - y2$$

```
diff(D21, x3);
```


Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);
```

$$\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

```
D21:=det(");
```

$$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$$

```
diff(D21, x1);
```

$$y3 - y2$$

```
diff(D21, x3);
```

$$y2 - y1$$

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);
      [ 1  1  1 ]
      [ y1 y2 y3 ]
      [ x1 x2 x3 ]
D21:=det("");
      D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2
diff(D21, x1);
      y3 - y2
diff(D21, x3);
      y2 - y1
diff(D21, y1);
```

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);
```

$$\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

```
D21:=det(");
```

$$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$$

```
diff(D21, x1);
```

$$y3 - y2$$

```
diff(D21, x3);
```

$$y2 - y1$$

```
diff(D21, y1);
```

$$-x3 + x2$$

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);
```

$$\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

```
D21:=det(");
```

$$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$$

```
diff(D21, x1);
```

$$y3 - y2$$

```
diff(D21, x3);
```

$$y2 - y1$$

```
diff(D21, y1);
```

$$-x3 + x2$$

```
diff(D21, y3);
```

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2,1]);           $\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$   
D21:=det("");        D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2  
diff(D21,x1);         y3 - y2  
diff(D21,x3);         y2 - y1  
diff(D21,y1);         -x3 + x2  
diff(D21,y3);         -x2 + x1
```

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);           $\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$   
D21:=det("");         D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2  
diff(D21, x1);        y3 - y2  
diff(D21, x3);        y2 - y1  
diff(D21, y1);        -x3 + x2  
diff(D21, y3);        -x2 + x1  
diff(D21, x3, y2);
```

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2,1]);           $\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$ 
D21:=det("");        D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2
diff(D21,x1);         y3 - y2
diff(D21,x3);         y2 - y1
diff(D21,y1);         -x3 + x2
diff(D21,y3);         -x2 + x1
diff(D21,x3,y2);     1
```

Brief review

Theorem (easy)


For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);  
           $\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$   
D21:=det("");  
           $D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$   
diff(D21, x1);  
           $y3 - y2$   
diff(D21, x3);  
           $y2 - y1$   
diff(D21, y1);  
           $-x3 + x2$   
diff(D21, y3);  
           $-x2 + x1$   
diff(D21, x3, y2);  
           $1$ 
```



Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);  
D21 := det(  
  [1 1 1  
   y1 y2 y3  
   x1 x2 x3  
  ]  
);  
diff(D21, x1);  
diff(D21, x3);  
diff(D21, y1);  
diff(D21, y3);  
diff(D21, x3, y2);  
1
```

$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$

$y3 - y2$

$y2 - y1$

$-x3 + x2$

$-x2 + x1$

1

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);  
D21 := det(  
  [ 1  1  1  
  y1 y2 y3  
  x1 x2 x3  
]);  
diff(D21, x1);  
diff(D21, x3);  
diff(D21, y1);  
diff(D21, y3);  
diff(D21, x3, y2);  
1
```

$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$

$y3 - y2$

$y2 - y1$

$-x3 + x2$

$-x2 + x1$

1

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);
```

$$\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

```
D21:=det("");
```

$$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$$

```
diff(D21, x1);
```

$$y3 - y2$$

```
diff(D21, x3);
```

$$y2 - y1$$

```
diff(D21, y1);
```

$$-x3 + x2$$

```
diff(D21, y3);
```

$$-x2 + x1$$

```
diff(D21, x3, y2);
```

$$1$$

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);
```

$$\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

```
D21:=det("");
```

$$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$$

```
diff(D21, x1);
```

$$y3 - y2$$

```
diff(D21, x3);
```

$$y2 - y1$$

```
diff(D21, y1);
```

$$-x3 + x2$$

```
diff(D21, y3);
```

$$-x2 + x1$$

```
diff(D21, x3, y2);
```

1

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);
```

$$\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

```
D21:=det("");
```

$$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$$

```
diff(D21, x1);
```

$$y3 - y2$$

```
diff(D21, x3);
```

$$y2 - y1$$

```
diff(D21, y1);
```

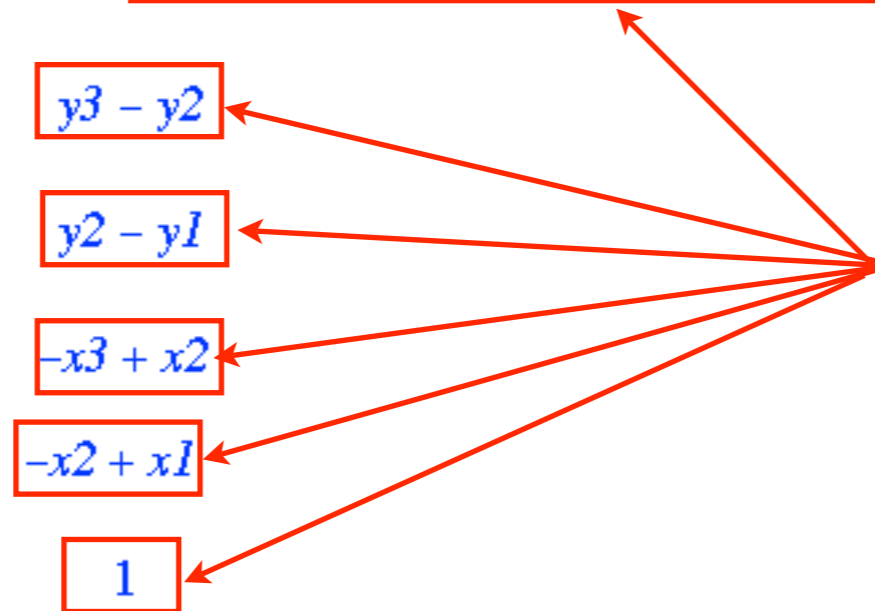
$$-x3 + x2$$

```
diff(D21, y3);
```

$$-x2 + x1$$

```
diff(D21, x3, y2);
```

$$1$$



Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);
```

$$\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

```
D21:=det(");
```

$$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$$

```
diff(D21, x1);
```

```
diff(D21, x3);
```

```
diff(D21, y1);
```

```
diff(D21, y3);
```

```
diff(D21, x3, y2);
```

$$y3 - y2$$

$$y2 - y1$$

$$-x3 + x2$$

$$-x2 + x1$$

$$1$$

6 independent derivatives!

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);
```

$$\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

```
D21:=det("");
```

$$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$$

```
diff(D21, x1);
```

$$y3 - y2$$

```
diff(D21, x3);
```

$$y2 - y1$$

```
diff(D21, y1);
```

$$-x3 + x2$$

```
diff(D21, y3);
```

$$-x2 + x1$$

```
diff(D21, x3, y2);
```

$$1$$

6 independent derivatives!

The $n!$ Conjecture

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);
```

$$\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

```
D21:=det(");
```

$$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$$

```
diff(D21, x1);
```

$$y3 - y2$$

```
diff(D21, x3);
```

$$y2 - y1$$

```
diff(D21, y1);
```

$$-x3 + x2$$

```
diff(D21, y3);
```

$$-x2 + x1$$

```
diff(D21, x3, y2);
```

$$1$$

6 independent derivatives!

The $n!$ Conjecture

(1990 - 2000)

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim \mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2, 1]);
```

$$\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

```
D21:=det(");
```

$$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$$

```
diff(D21, x1);
```

$$y3 - y2$$

```
diff(D21, x3);
```

$$y2 - y1$$

```
diff(D21, y1);
```

$$-x3 + x2$$

```
diff(D21, y3);
```

$$-x2 + x1$$

```
diff(D21, x3, y2);
```

$$1$$

6 independent derivatives!

The $n!$ Conjecture

(1990 - 2000)

For $\mu \vdash n$

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim M_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2,1]);
```

$$\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

```
D21:=det(");
```

$$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$$

```
diff(D21, x1);
```

$$y3 - y2$$

```
diff(D21, x3);
```

$$y2 - y1$$

```
diff(D21, y1);
```

$$-x3 + x2$$

```
diff(D21, y3);
```

$$-x2 + x1$$

```
diff(D21, x3, y2);
```

$$1$$

6 independent derivatives!

The $n!$ Conjecture

(1990 - 2000)

For $\mu \vdash n$ $\dim M_\mu[X, Y] = n!$

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim M_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2,1]);
```

$$\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

```
D21:=det(");
```

$$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$$

```
diff(D21, x1);
```

$$y3 - y2$$

```
diff(D21, x3);
```

$$y2 - y1$$

```
diff(D21, y1);
```

$$-x3 + x2$$

```
diff(D21, y3);
```

$$-x2 + x1$$

```
diff(D21, x3, y2);
```

$$1$$

6 independent derivatives!

The $n!$ Conjecture

(1990 - 2000)

$$\text{For } \mu \vdash n \quad \dim M_\mu[X, Y] = n!$$

Proved by Mark Haiman using algebraic geometry

Brief review

Theorem (easy)

For any $\mu \vdash n$ the dimension of the linear span of the derivatives of $\Delta_\mu(X, Y)$ is at most $n!$

In symbols

$$\dim M_\mu[\mathbf{X}, \mathbf{Y}] \leq n!$$

For example (using MAPLE)

```
DDmu([2,1]);
```

$$\begin{bmatrix} 1 & 1 & 1 \\ y1 & y2 & y3 \\ x1 & x2 & x3 \end{bmatrix}$$

```
D21:=det(");
```

$$D21 := y2 x3 - y3 x2 - y1 x3 + y1 x2 + x1 y3 - x1 y2$$

```
diff(D21, x1);
```

$$y3 - y2$$

```
diff(D21, x3);
```

$$y2 - y1$$

```
diff(D21, y1);
```

$$-x3 + x2$$

```
diff(D21, y3);
```

$$-x2 + x1$$

```
diff(D21, x3, y2);
```

$$1$$

6 independent derivatives!

The $n!$ Conjecture

(1990 - 2000)

$$\text{For } \mu \vdash n \quad \dim M_\mu[X, Y] = n!$$

Proved by Mark Haiman using algebraic geometry

next

Hilbert series

Hilbert series

A vector space V is called “*graded*” if and only if

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} *homogeneous component*” of V .

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} *homogeneous component*” of V .



its elements are called homogeneous of degree m

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} *homogeneous component*” of V .

its elements are called homogeneous of degree m

If $\dim H_m(V) < \infty$ for all m , we set

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} *homogeneous component*” of V .

its elements are called homogeneous of degree m

If $\dim H_m(V) < \infty$ for all m , we set

$$F_V(t) = \sum_{m \geq 0} t^m \dim H_m(V)$$

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} *homogeneous component*” of V .

its elements are called homogeneous of degree m

If $\dim H_m(V) < \infty$ for all m , we set

$$F_V(t) = \sum_{m \geq 0} t^m \dim H_m(V)$$

the “*Hilbert series*” of V

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} *homogeneous component*” of V .

its elements are called homogeneous of degree m

If $\dim H_m(V) < \infty$ for all m , we set

$$F_V(t) = \sum_{m \geq 0} t^m \dim H_m(V)$$

the “*Hilbert series*” of V

For instance for $R = \mathbb{Q}[x_1, x_2, \dots, x_n]$ we have

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} *homogeneous component*” of V .

its elements are called homogeneous of degree m

If $\dim H_m(V) < \infty$ for all m , we set

$$F_V(t) = \sum_{m \geq 0} t^m \dim H_m(V)$$

the “*Hilbert series*” of V

For instance for $R = \mathbb{Q}[x_1, x_2, \dots, x_n]$ we have $R = H_0(R) \oplus H_1(R) \oplus H_2(R) \oplus \cdots$

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} *homogeneous component*” of V .

its elements are called homogeneous of degree m

If $\dim H_m(V) < \infty$ for all m , we set

$$F_V(t) = \sum_{m \geq 0} t^m \dim H_m(V)$$

the “*Hilbert series*” of V

For instance for $R = \mathbb{Q}[x_1, x_2, \dots, x_n]$ we have $R = H_0(R) \oplus H_1(R) \oplus H_2(R) \oplus \cdots$ with

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} *homogeneous component*” of V .

its elements are called homogeneous of degree m

If $\dim H_m(V) < \infty$ for all m , we set

$$F_V(t) = \sum_{m \geq 0} t^m \dim H_m(V)$$

the “*Hilbert series*” of V

For instance for $R = \mathbb{Q}[x_1, x_2, \dots, x_n]$ we have $R = H_0(R) \oplus H_1(R) \oplus H_2(R) \oplus \cdots$ with

$$H_m(R) = L[x_1^{p_1} x_2^{p_2} \cdots x_n^{p_n} : p_1 + p_2 + \cdots + p_n = m]$$

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} *homogeneous component*” of V .

its elements are called homogeneous of degree m

If $\dim H_m(V) < \infty$ for all m , we set

$$F_V(t) = \sum_{m \geq 0} t^m \dim H_m(V)$$

the “*Hilbert series*” of V

For instance for $R = \mathbb{Q}[x_1, x_2, \dots, x_n]$ we have $R = H_0(R) \oplus H_1(R) \oplus H_2(R) \oplus \cdots$ with

$$H_m(R) = L[x_1^{p_1} x_2^{p_2} \cdots x_n^{p_n} : p_1 + p_2 + \cdots + p_n = m]$$

In this case

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} *homogeneous component*” of V .

its elements are called homogeneous of degree m

If $\dim H_m(V) < \infty$ for all m , we set

$$F_V(t) = \sum_{m \geq 0} t^m \dim H_m(V)$$

the “*Hilbert series*” of V

For instance for $R = \mathbb{Q}[x_1, x_2, \dots, x_n]$ we have $R = H_0(R) \oplus H_1(R) \oplus H_2(R) \oplus \cdots$ with

$$H_m(R) = L[x_1^{p_1} x_2^{p_2} \cdots x_n^{p_n} : p_1 + p_2 + \cdots + p_n = m]$$

In this case

$$\dim H_m(R) = \binom{m+n-1}{n-1}$$

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} *homogeneous component*” of V .

its elements are called homogeneous of degree m

If $\dim H_m(V) < \infty$ for all m , we set

$$F_V(t) = \sum_{m \geq 0} t^m \dim H_m(V)$$

the “*Hilbert series*” of V

For instance for $R = \mathbb{Q}[x_1, x_2, \dots, x_n]$ we have $R = H_0(R) \oplus H_1(R) \oplus H_2(R) \oplus \cdots$ with

$$H_m(R) = L[x_1^{p_1} x_2^{p_2} \cdots x_n^{p_n} : p_1 + p_2 + \cdots + p_n = m]$$

In this case

$$\dim H_m(R) = \binom{m+n-1}{n-1} \quad \text{and}$$

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} *homogeneous component*” of V .

its elements are called homogeneous of degree m

If $\dim H_m(V) < \infty$ for all m , we set

$$F_V(t) = \sum_{m \geq 0} t^m \dim H_m(V)$$

the “*Hilbert series*” of V

For instance for $R = \mathbb{Q}[x_1, x_2, \dots, x_n]$ we have $R = H_0(R) \oplus H_1(R) \oplus H_2(R) \oplus \cdots$ with

$$H_m(R) = L[x_1^{p_1} x_2^{p_2} \cdots x_n^{p_n} : p_1 + p_2 + \cdots + p_n = m]$$

In this case

$$\dim H_m(R) = \binom{m+n-1}{n-1} \quad \text{and} \quad F_R(t) = \frac{1}{(1-t)^n}$$

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} *homogeneous component*” of V .

its elements are called homogeneous of degree m

If $\dim H_m(V) < \infty$ for all m , we set

$$F_V(t) = \sum_{m>0} t^m \dim H_m(V)$$

the “*Hilbert series*” of V

For instance for $R = \mathbb{Q}[x_1, x_2, \dots, x_n]$ we have $R = H_0(R) \oplus H_1(R) \oplus H_2(R) \oplus \cdots$ with

$$H_m(R) = L[x_1^{p_1} x_2^{p_2} \cdots x_n^{p_n} : p_1 + p_2 + \cdots + p_n = m]$$

In this case

$$\dim H_m(R) = \binom{m+n-1}{n-1} \quad \text{and} \quad F_R(t) = \frac{1}{(1-t)^n}$$

Our spaces $M[X, Y]$ are “*bigraded*” that is we have the double decomposition

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} *homogeneous component*” of V .

its elements are called homogeneous of degree m

If $\dim H_m(V) < \infty$ for all m , we set

$$F_V(t) = \sum_{m>0} t^m \dim H_m(V)$$

the “*Hilbert series*” of V

For instance for $R = \mathbb{Q}[x_1, x_2, \dots, x_n]$ we have $R = H_0(R) \oplus H_1(R) \oplus H_2(R) \oplus \cdots$ with

$$H_m(R) = L[x_1^{p_1} x_2^{p_2} \cdots x_n^{p_n} : p_1 + p_2 + \cdots + p_n = m]$$

In this case

$$\dim H_m(R) = \binom{m+n-1}{n-1} \quad \text{and} \quad F_R(t) = \frac{1}{(1-t)^n}$$

Our spaces $M[X, Y]$ are “*bigraded*” that is we have the double decomposition

$$M_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} H_{r,s}(M_\mu[X, Y])$$

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} *homogeneous component*” of V .

its elements are called homogeneous of degree m

If $\dim H_m(V) < \infty$ for all m , we set

$$F_V(t) = \sum_{m>0} t^m \dim H_m(V)$$

the “*Hilbert series*” of V

For instance for $R = \mathbb{Q}[x_1, x_2, \dots, x_n]$ we have $R = H_0(R) \oplus H_1(R) \oplus H_2(R) \oplus \cdots$ with

$$H_m(R) = L[x_1^{p_1} x_2^{p_2} \cdots x_n^{p_n} : p_1 + p_2 + \cdots + p_n = m]$$

In this case

$$\dim H_m(R) = \binom{m+n-1}{n-1} \quad \text{and} \quad F_R(t) = \frac{1}{(1-t)^n}$$

Our spaces $M[X, Y]$ are “*bigraded*” that is we have the double decomposition

$$M_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} H_{r,s}(M_\mu[X, Y])$$

With $H_{r,s}(M_\mu[X, Y])$ the linear span of derivatives of $\Delta_\mu(x, y)$

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} *homogeneous component*” of V .

its elements are called homogeneous of degree m

If $\dim H_m(V) < \infty$ for all m , we set

$$F_V(t) = \sum_{m>0} t^m \dim H_m(V)$$

the “*Hilbert series*” of V

For instance for $R = \mathbb{Q}[x_1, x_2, \dots, x_n]$ we have $R = H_0(R) \oplus H_1(R) \oplus H_2(R) \oplus \cdots$ with

$$H_m(R) = L[x_1^{p_1} x_2^{p_2} \cdots x_n^{p_n} : p_1 + p_2 + \cdots + p_n = m]$$

In this case

$$\dim H_m(R) = \binom{m+n-1}{n-1} \quad \text{and} \quad F_R(t) = \frac{1}{(1-t)^n}$$

Our spaces $M[X, Y]$ are “*bigraded*” that is we have the double decomposition

$$M_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} H_{r,s}(M_\mu[X, Y])$$

With $H_{r,s}(M_\mu[X, Y])$ the linear span of derivatives of $\Delta_\mu(x, y)$

that are homogeneous of degree r in x_1, x_2, \dots, x_n and degree s in y_1, y_2, \dots, y_n

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} homogeneous component” of V .

its elements are called homogeneous of degree m

If $\dim H_m(V) < \infty$ for all m , we set

$$F_V(t) = \sum_{m>0} t^m \dim H_m(V)$$

the “Hilbert series” of V

For instance for $R = \mathbb{Q}[x_1, x_2, \dots, x_n]$ we have $R = H_0(R) \oplus H_1(R) \oplus H_2(R) \oplus \cdots$ with

$$H_m(R) = L[x_1^{p_1} x_2^{p_2} \cdots x_n^{p_n} : p_1 + p_2 + \cdots + p_n = m]$$

In this case

$$\dim H_m(R) = \binom{m+n-1}{n-1} \quad \text{and} \quad F_R(t) = \frac{1}{(1-t)^n}$$

Our spaces $M[X, Y]$ are “*bigraded*” that is we have the double decomposition

$$M_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} H_{r,s}(M_\mu[X, Y])$$

With $H_{r,s}(M_\mu[X, Y])$ the linear span of derivatives of $\Delta_\mu(x, y)$

that are homogeneous of degree r in x_1, x_2, \dots, x_n and degree s in y_1, y_2, \dots, y_n

Here and after we set

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \dots \oplus H_m(V) \oplus \dots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} homogeneous component” of V .

its elements are called homogeneous of degree m

If $\dim H_m(V) < \infty$ for all m , we set

$$F_V(t) = \sum_{m>0} t^m \dim H_m(V)$$

the “*Hilbert series*” of V

For instance for $R = \mathbb{Q}[x_1, x_2, \dots, x_n]$ we have $R = H_0(R) \oplus H_1(R) \oplus H_2(R) \oplus \dots$ with

$$H_m(R) = L[x_1^{p_1} x_2^{p_2} \dots x_n^{p_n} : p_1 + p_2 + \dots + p_n = m]$$

In this case

$$\dim H_m(R) = \binom{m+n-1}{n-1} \quad \text{and} \quad F_R(t) = \frac{1}{(1-t)^n}$$

Our spaces $M[X, Y]$ are “*bigraded*” that is we have the double decomposition

$$M_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} H_{r,s}(M_\mu[X, Y])$$

With $H_{r,s}(M_\mu[X, Y])$ the linear span of derivatives of $\Delta_\mu(x, y)$

that are homogeneous of degree r in x_1, x_2, \dots, x_n and degree s in y_1, y_2, \dots, y_n

Here and after we set

$$F_\mu(q, t) = \sum_{r=0}^{n(\mu)} \sum_{s=0}^{n(\mu')} t^r q^s \dim H_{r,s}(M_\mu[X, Y])$$

Hilbert series

A vector space V is called “*graded*” if and only if

$$V = H_0(V) \oplus H_1(V) \oplus H_2(V) \oplus \cdots \oplus H_m(V) \oplus \cdots$$

The subspace “ $H_m(V)$ ” is called the “ m^{th} homogeneous component” of V .

its elements are called homogeneous of degree m

If $\dim H_m(V) < \infty$ for all m , we set

$$F_V(t) = \sum_{m>0} t^m \dim H_m(V)$$

the “*Hilbert series*” of V

For instance for $R = \mathbb{Q}[x_1, x_2, \dots, x_n]$ we have $R = H_0(R) \oplus H_1(R) \oplus H_2(R) \oplus \cdots$ with

$$H_m(R) = L[x_1^{p_1} x_2^{p_2} \cdots x_n^{p_n} : p_1 + p_2 + \cdots + p_n = m]$$

In this case

$$\dim H_m(R) = \binom{m+n-1}{n-1} \quad \text{and} \quad F_R(t) = \frac{1}{(1-t)^n}$$

Our spaces $M[X, Y]$ are “*bigraded*” that is we have the double decomposition

$$M_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} H_{r,s}(M_\mu[X, Y])$$

With $H_{r,s}(M_\mu[X, Y])$ the linear span of derivatives of $\Delta_\mu(x, y)$

that are homogeneous of degree r in x_1, x_2, \dots, x_n and degree s in y_1, y_2, \dots, y_n

Here and after we set

$$F_\mu(q, t) = \sum_{r=0}^{n(\mu)} \sum_{s=0}^{n(\mu')} t^r q^s \dim H_{r,s}(M_\mu[X, Y])$$

next

The Macdonald Polynomials as Frobenius Characteristics

The Macdonald Polynomials as Frobenius Characteristics

$$\mathbf{M}_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

The Macdonald Polynomials as Frobenius Characteristics

$$\mathbf{M}_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

The Frobenius map

The Macdonald Polynomials as Frobenius Characteristics

$$\mathbf{M}_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

The Frobenius map

$$F\chi^\lambda = \mathbf{S}_\lambda[\mathbf{X}]$$

The Macdonald Polynomials as Frobenius Characteristics

$$\mathbf{M}_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

The Frobenius map $\mathbf{F}\chi^\lambda = \mathbf{S}_\lambda[\mathbf{X}]$

It follows from the $n!$ -Theorem that

The Macdonald Polynomials as Frobenius Characteristics

$$\mathbf{M}_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

The Frobenius map $\mathbf{F}\chi^\lambda = \mathbf{S}_\lambda[\mathbf{X}]$

It follows from the $n!$ -Theorem that

$$\tilde{H}_\mu[X; q, t] = \sum_{r=0}^{n(\mu)} \sum_{s=0}^{n(\mu')} t^r q^s \mathbf{F}char \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

The Macdonald Polynomials as Frobenius Characteristics

$$\mathbf{M}_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

The Frobenius map $\mathbf{F}\chi^\lambda = \mathbf{S}_\lambda[\mathbf{X}]$

It follows from the $n!$ -Theorem that

$$\tilde{H}_\mu[X; q, t] = \sum_{r=0}^{n(\mu)} \sum_{s=0}^{n(\mu')} t^r q^s \mathbf{F}char \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

Moreover the Frobenius characteristic of restriction of $\mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}]$ to \mathbf{S}_{n-1}

The Macdonald Polynomials as Frobenius Characteristics

$$\mathbf{M}_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

The Frobenius map $\mathbf{F}\chi^\lambda = \mathbf{S}_\lambda[\mathbf{X}]$

It follows from the $n!$ -Theorem that

$$\tilde{H}_\mu[X; q, t] = \sum_{r=0}^{n(\mu)} \sum_{s=0}^{n(\mu')} t^r q^s \mathbf{F}char \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

Moreover the Frobenius characteristic of restriction of $\mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}]$ to \mathbf{S}_{n-1} is given by the polynomial

The Macdonald Polynomials as Frobenius Characteristics

$$\mathbf{M}_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

The Frobenius map $\mathbf{F}\chi^\lambda = \mathbf{S}_\lambda[\mathbf{X}]$

It follows from the $n!$ -Theorem that

$$\tilde{H}_\mu[X; q, t] = \sum_{r=0}^{n(\mu)} \sum_{s=0}^{n(\mu')} t^r q^s \mathbf{F}char \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

Moreover the Frobenius characteristic of restriction of $\mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}]$ to \mathbf{S}_{n-1} is given by the polynomial

$$\partial_{p_1} \tilde{H}_\mu[X; q, t]$$

The Macdonald Polynomials as Frobenius Characteristics

$$\mathbf{M}_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

The Frobenius map $\mathbf{F}\chi^\lambda = \mathbf{S}_\lambda[\mathbf{X}]$

It follows from the $n!$ -Theorem that

$$\tilde{H}_\mu[X; q, t] = \sum_{r=0}^{n(\mu)} \sum_{s=0}^{n(\mu')} t^r q^s \mathbf{F}char \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

Moreover the Frobenius characteristic of restriction of $\mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}]$ to \mathbf{S}_{n-1} is given by the polynomial

$$\partial_{p_1} \tilde{H}_\mu[X; q, t]$$

$$\tilde{H}_{2,2}[X; q, t] = s_4 + s_{3,1}(q + t + qt) + s_{2,2}(q^2 + t^2) + s_{2,1,1}(qt^2 + q^2t + qt) + s_{1,1,1,1}t^2q^2$$

The Macdonald Polynomials as Frobenius Characteristics

$$\mathbf{M}_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

The Frobenius map $\mathbf{F}\chi^\lambda = \mathbf{S}_\lambda[\mathbf{X}]$

It follows from the $n!$ -Theorem that

$$\tilde{H}_\mu[X; q, t] = \sum_{r=0}^{n(\mu)} \sum_{s=0}^{n(\mu')} t^r q^s \mathbf{F}char \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

Moreover the Frobenius characteristic of restriction of $\mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}]$ to \mathbf{S}_{n-1} is given by the polynomial

$$\partial_{p_1} \tilde{H}_\mu[X; q, t]$$

$$\begin{aligned} \tilde{H}_{2,2}[X; q, t] &= s_4 + s_{3,1}(q+t+qt) + s_{2,2}(q^2+t^2) + s_{2,1,1}(qt^2+q^2t+qt) + s_{1,1,1,1}t^2q^2 \\ \partial_{p_1} \tilde{H}_{2,2}[X; q, t] &= (1+q+t+qt)s_3 + (q^2+t^2+qt^2+q^2t+q+t+2qt)s_{2,1} + qt(1+q+t+qt)s_{1,1,1} \end{aligned}$$

The Macdonald Polynomials as Frobenius Characteristics

$$\mathbf{M}_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

The Frobenius map $\mathbf{F}\chi^\lambda = \mathbf{S}_\lambda[\mathbf{X}]$

It follows from the $n!$ -Theorem that

$$\tilde{H}_\mu[X; q, t] = \sum_{r=0}^{n(\mu)} \sum_{s=0}^{n(\mu')} t^r q^s \mathbf{F}char \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

Moreover the Frobenius characteristic of restriction of $\mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}]$ to \mathbf{S}_{n-1} is given by the polynomial

$$\partial_{p_1} \tilde{H}_\mu[X; q, t]$$

$$\begin{aligned} \tilde{H}_{2,2}[X; q, t] &= s_4 + s_{3,1}(q+t+qt) + s_{2,2}(q^2+t^2) + s_{2,1,1}(qt^2+q^2t+qt) + s_{1,1,1,1}t^2q^2 \\ \partial_{p_1} \tilde{H}_{2,2}[X; q, t] &= (1+q+t+qt)s_3 + (q^2+t^2+qt^2+q^2t+q+t+2qt)s_{2,1} + qt(1+q+t+qt)s_{1,1,1} \\ &\quad \begin{bmatrix} s_{2,1} & s_{2,1} + s_{1,1,1} & s_{1,1,1} \\ s_3 + s_{2,1} & s_3 + 2s_{2,1} + s_{1,1,1} & s_{2,1} + s_{1,1,1} \\ s_3 & s_3 + s_{2,1} & s_{2,1} \end{bmatrix} \end{aligned}$$

The Macdonald Polynomials as Frobenius Characteristics

$$\mathbf{M}_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

The Frobenius map $\mathbf{F}\chi^\lambda = \mathbf{S}_\lambda[\mathbf{X}]$

It follows from the $n!$ -Theorem that

$$\tilde{H}_\mu[X; q, t] = \sum_{r=0}^{n(\mu)} \sum_{s=0}^{n(\mu')} t^r q^s \mathbf{F}char \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

Moreover the Frobenius characteristic of restriction of $\mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}]$ to \mathbf{S}_{n-1} is given by the polynomial

$$\partial_{p_1} \tilde{H}_\mu[X; q, t]$$

$$\begin{aligned} \tilde{H}_{2,2}[X; q, t] &= s_4 + s_{3,1}(q+t+qt) + s_{2,2}(q^2+t^2) + s_{2,1,1}(qt^2+q^2t+qt) + s_{1,1,1,1}t^2q^2 \\ \partial_{p_1} \tilde{H}_{2,2}[X; q, t] &= (1+q+t+qt)s_3 + (q^2+t^2+qt^2+q^2t+q+t+2qt)s_{2,1} + qt(1+q+t+qt)s_{1,1,1} \\ &\quad \begin{bmatrix} s_{2,1} & s_{2,1} + s_{1,1,1} & s_{1,1,1} \\ s_3 + s_{2,1} & s_3 + 2s_{2,1} + s_{1,1,1} & s_{2,1} + s_{1,1,1} \\ s_3 & s_3 + s_{2,1} & s_{2,1} \end{bmatrix} \longleftarrow \text{Restriction to } \mathcal{S}_3 \end{aligned}$$

The Macdonald Polynomials as Frobenius Characteristics

$$\mathbf{M}_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

The Frobenius map $\mathbf{F}\chi^\lambda = \mathbf{S}_\lambda[\mathbf{X}]$

It follows from the $n!$ -Theorem that

$$\tilde{H}_\mu[X; q, t] = \sum_{r=0}^{n(\mu)} \sum_{s=0}^{n(\mu')} t^r q^s \mathbf{F}char \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

Moreover the Frobenius characteristic of restriction of $\mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}]$ to \mathbf{S}_{n-1} is given by the polynomial

$$\partial_{p_1} \tilde{H}_\mu[X; q, t]$$

$$\begin{aligned} \tilde{H}_{2,2}[X; q, t] &= s_4 + s_{3,1}(q+t+qt) + s_{2,2}(q^2+t^2) + s_{2,1,1}(qt^2+q^2t+qt) + s_{1,1,1,1}t^2q^2 \\ \partial_{p_1} \tilde{H}_{2,2}[X; q, t] &= (1+q+t+qt)s_3 + (q^2+t^2+qt^2+q^2t+q+t+2qt)s_{2,1} + qt(1+q+t+qt)s_{1,1,1} \\ &\quad \begin{bmatrix} s_{2,1} & s_{2,1} + s_{1,1,1} & s_{1,1,1} \\ s_3 + s_{2,1} & s_3 + 2s_{2,1} + s_{1,1,1} & s_{2,1} + s_{1,1,1} \\ s_3 & s_3 + s_{2,1} & s_{2,1} \end{bmatrix} \longleftarrow \text{Restriction to } \mathcal{S}_3 \end{aligned}$$

How does this decompose in terms of the basis $\{\tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}]\}_{\mu \vdash 3}$

The Macdonald Polynomials as Frobenius Characteristics

$$\mathbf{M}_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

The Frobenius map $\mathbf{F}\chi^\lambda = \mathbf{S}_\lambda[\mathbf{X}]$

It follows from the $n!$ -Theorem that

$$\tilde{H}_\mu[X; q, t] = \sum_{r=0}^{n(\mu)} \sum_{s=0}^{n(\mu')} t^r q^s \mathbf{F}char \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

Moreover the Frobenius characteristic of restriction of $\mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}]$ to \mathbf{S}_{n-1} is given by the polynomial

$$\partial_{p_1} \tilde{H}_\mu[X; q, t]$$

$$\begin{aligned} \tilde{H}_{2,2}[X; q, t] &= s_4 + s_{3,1}(q+t+qt) + s_{2,2}(q^2+t^2) + s_{2,1,1}(qt^2+q^2t+qt) + s_{1,1,1,1}t^2q^2 \\ \partial_{p_1} \tilde{H}_{2,2}[X; q, t] &= (1+q+t+qt)s_3 + (q^2+t^2+qt^2+q^2t+q+t+2qt)s_{2,1} + qt(1+q+t+qt)s_{1,1,1} \\ &\begin{bmatrix} s_{2,1} & s_{2,1} + s_{1,1,1} & s_{1,1,1} \\ s_3 + s_{2,1} & s_3 + 2s_{2,1} + s_{1,1,1} & s_{2,1} + s_{1,1,1} \\ s_3 & s_3 + s_{2,1} & s_{2,1} \end{bmatrix} \longleftarrow \text{Restriction to } \mathcal{S}_3 \end{aligned}$$

How does this decompose in terms of the basis $\{\tilde{H}_\mu[\mathbf{X}; q, t]\}_{\mu \vdash 3}$?

The Macdonald Polynomials as Frobenius Characteristics

$$\mathbf{M}_\mu[X, Y] = \bigoplus_{r=0}^{n(\mu)} \bigoplus_{s=0}^{n(\mu')} \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

The Frobenius map $\mathbf{F}\chi^\lambda = \mathbf{S}_\lambda[\mathbf{X}]$

It follows from the $n!$ -Theorem that

$$\tilde{H}_\mu[X; q, t] = \sum_{r=0}^{n(\mu)} \sum_{s=0}^{n(\mu')} t^r q^s \mathbf{F}char \mathcal{H}_{r,s}(\mathbf{M}_\mu[X, Y])$$

Moreover the Frobenius characteristic of restriction of $\mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}]$ to \mathbf{S}_{n-1} is given by the polynomial

$$\partial_{p_1} \tilde{H}_\mu[X; q, t]$$

$$\tilde{H}_{2,2}[X; q, t] = s_4 + s_{3,1}(q+t+qt) + s_{2,2}(q^2+t^2) + s_{2,1,1}(qt^2+q^2t+qt) + s_{1,1,1,1}t^2q^2$$

$$\partial_{p_1} \tilde{H}_{2,2}[X; q, t] = (1+q+t+qt)s_3 + (q^2+t^2+qt^2+q^2t+q+t+2qt)s_{2,1} + qt(1+q+t+qt)s_{1,1,1}$$

$$\begin{bmatrix} s_{2,1} & s_{2,1} + s_{1,1,1} & s_{1,1,1} \\ s_3 + s_{2,1} & s_3 + 2s_{2,1} + s_{1,1,1} & s_{2,1} + s_{1,1,1} \\ s_3 & s_3 + s_{2,1} & s_{2,1} \end{bmatrix} \longleftarrow \text{Restriction to } \mathcal{S}_3$$

How does this decompose in terms of the basis $\{\tilde{H}_\mu[\mathbf{X}; q, t]\}_{\mu \vdash 3}$?

next

The Macdonald-Stanley (dual) Pieri Rules

The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{\mathbf{p}_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

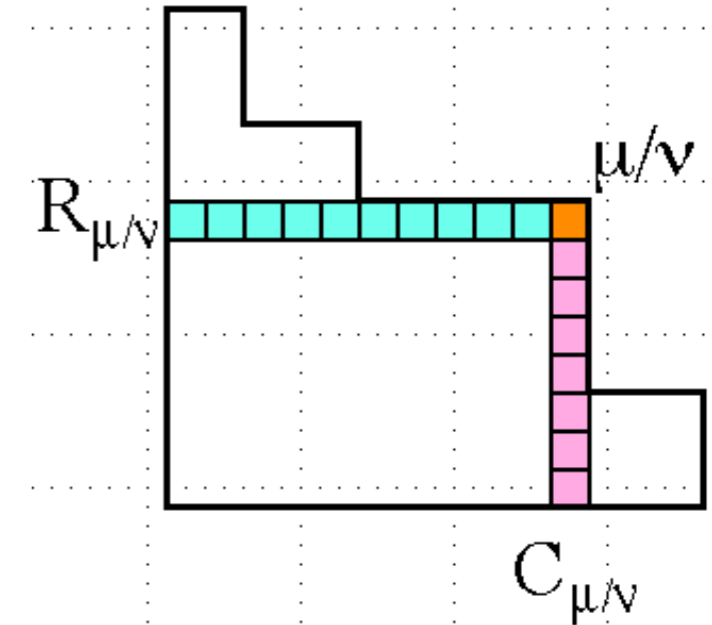
The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{\mathbf{p}_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$
$$c_{\mu\nu}(\mathbf{q}, \mathbf{t}) = \prod_{s \in \mathbf{R}_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in \mathbf{C}_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}} ,$$

The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{\mathbf{p}_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

$$c_{\mu\nu}(\mathbf{q}, \mathbf{t}) = \prod_{s \in \mathbf{R}_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in \mathbf{C}_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$

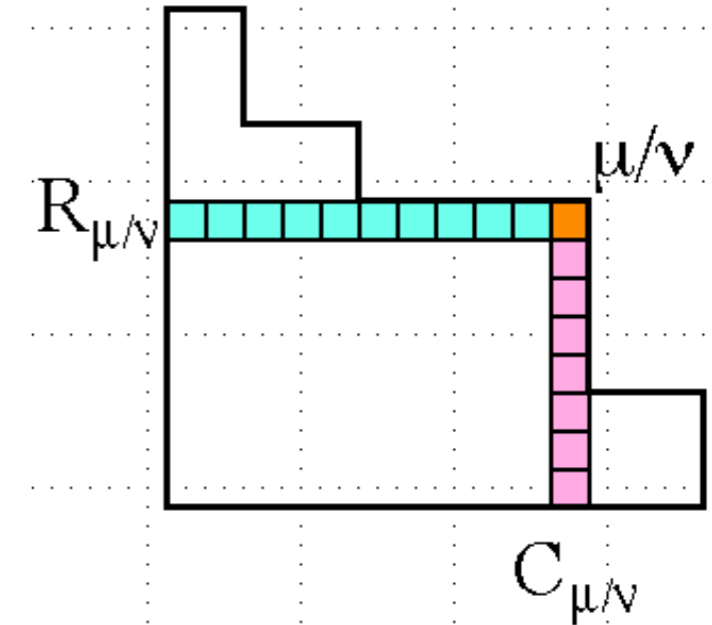


The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{p_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

$$c_{\mu\nu}(\mathbf{q}, \mathbf{t}) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$

where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote

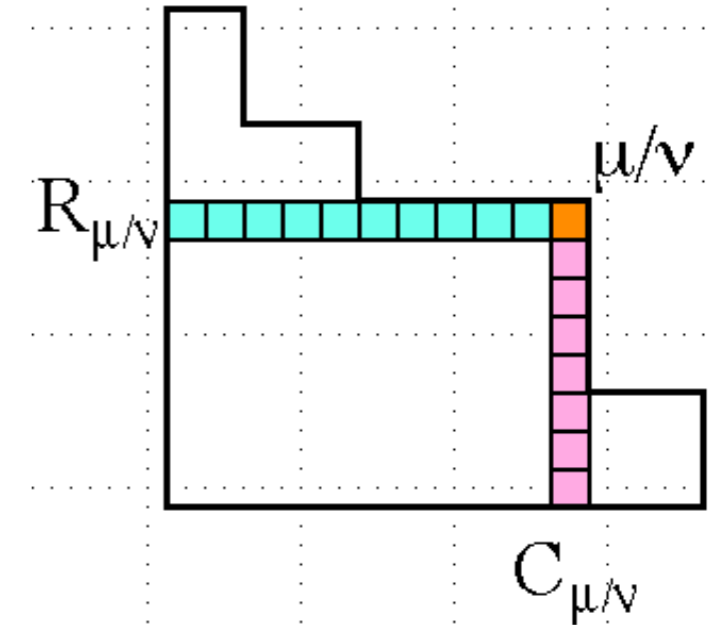


The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{\mathbf{p}_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

$$c_{\mu\nu}(\mathbf{q}, \mathbf{t}) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$

where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote
the collections of cells of ν

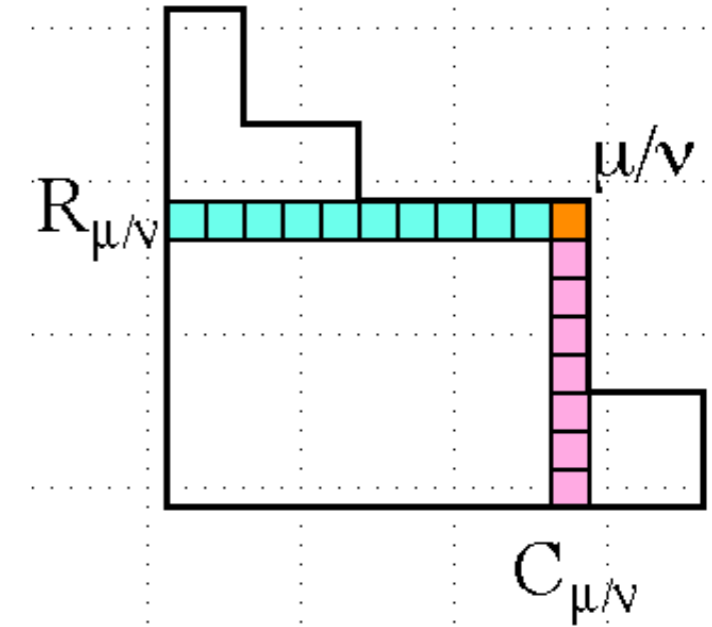


The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{p_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

$$c_{\mu\nu}(\mathbf{q}, \mathbf{t}) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$

where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote
 the collections of cells of ν
 that are respectively in the



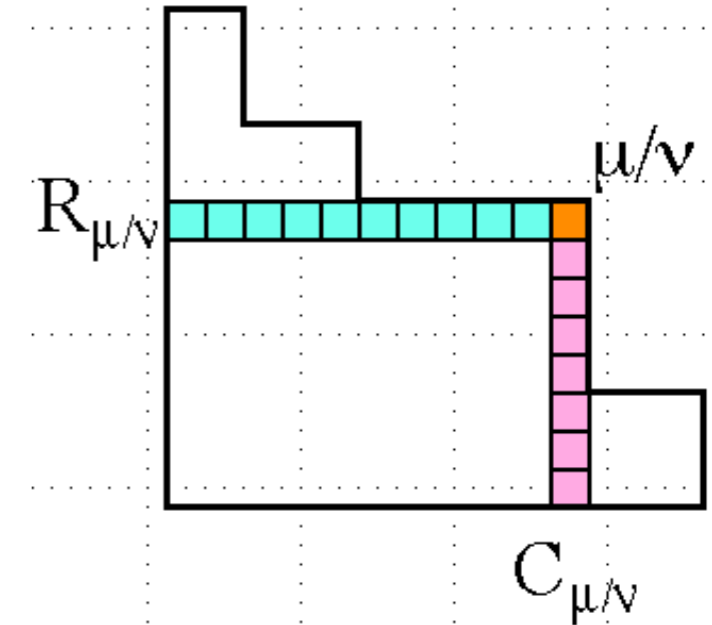
The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{\mathbf{p}_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

$$c_{\mu\nu}(\mathbf{q}, \mathbf{t}) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$

where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote
 the collections of cells of ν
 that are respectively in the

row and the column of the cell μ/ν .

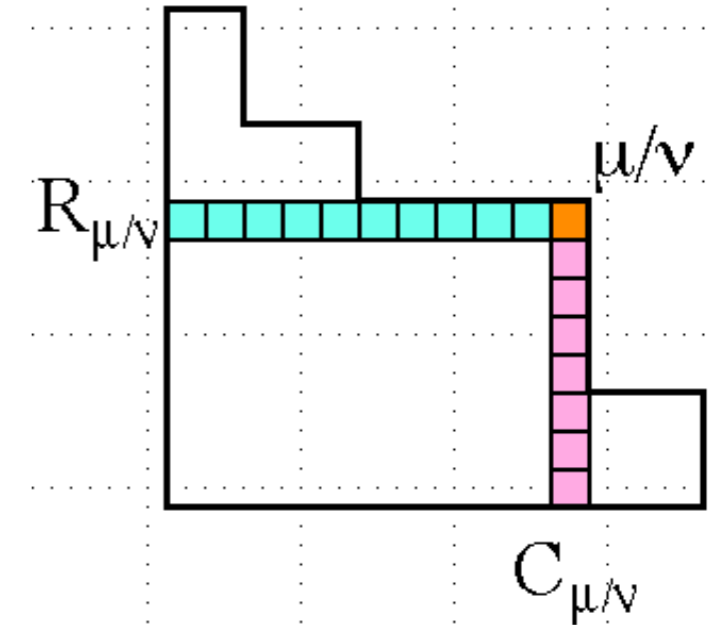


The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{\mathbf{p}_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

$$c_{\mu\nu}(\mathbf{q}, \mathbf{t}) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$

where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote
 the collections of cells of ν
 that are respectively in the



row and the column of the cell μ/ν .

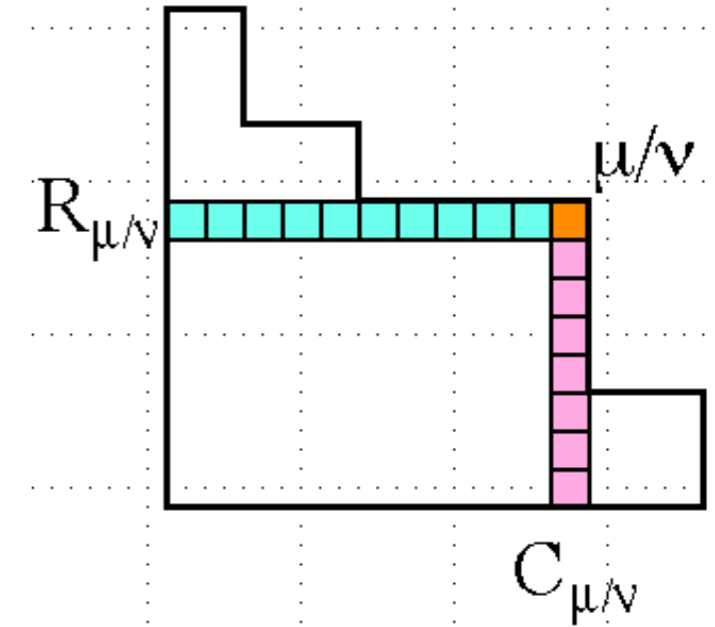
The Hilbert series

The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{\mathbf{p}_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

$$c_{\mu\nu}(\mathbf{q}, \mathbf{t}) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\nu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$

where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote
 the collections of cells of ν
 that are respectively in the



row and the column of the cell μ/ν .

The Hilbert series

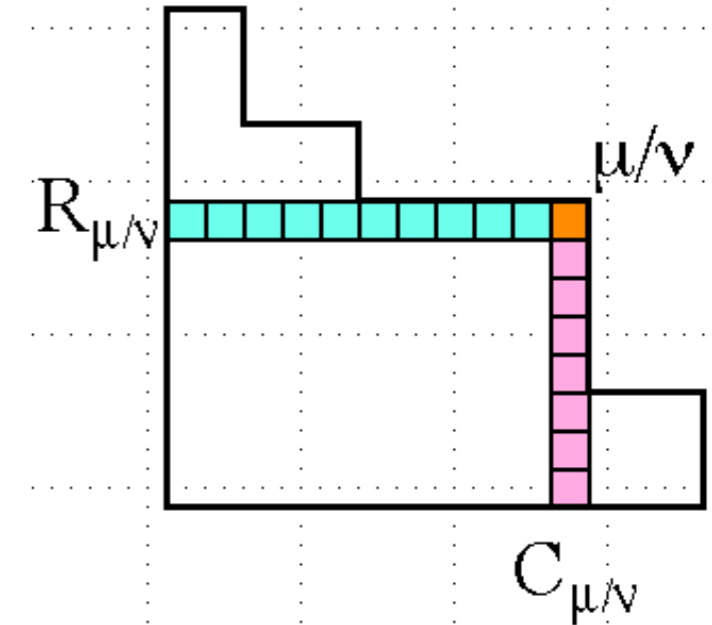
$$F_\mu(\mathbf{q}, \mathbf{t})$$

The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{\mathbf{p}_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

$$c_{\mu\nu}(\mathbf{q}, \mathbf{t}) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$

where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote
 the collections of cells of ν
 that are respectively in the



row and the column of the cell μ/ν .

The Hilbert series

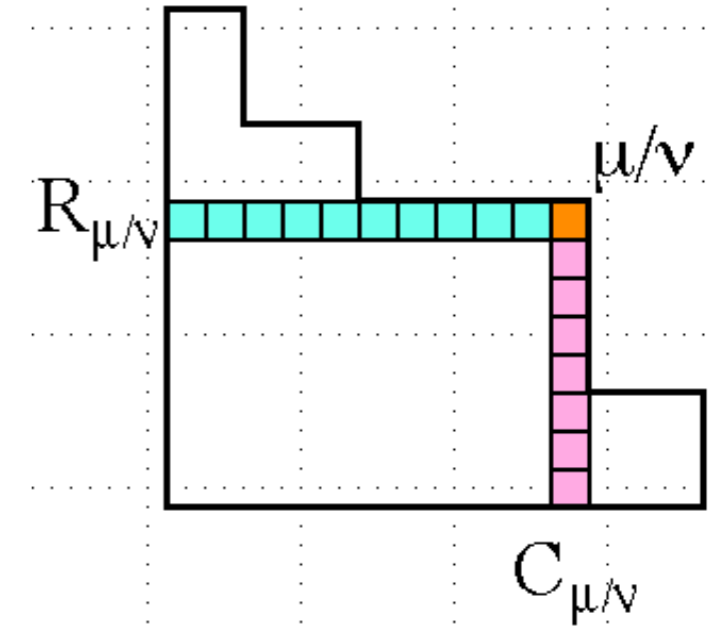
$$F_\mu(\mathbf{q}, \mathbf{t}) = \partial_{\mathbf{p}_1}^n \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{\mathbf{p}_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

$$c_{\mu\nu}(\mathbf{q}, \mathbf{t}) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$

where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote
the collections of cells of ν
that are respectively in the



row and the column of the cell μ/ν .

The Hilbert series

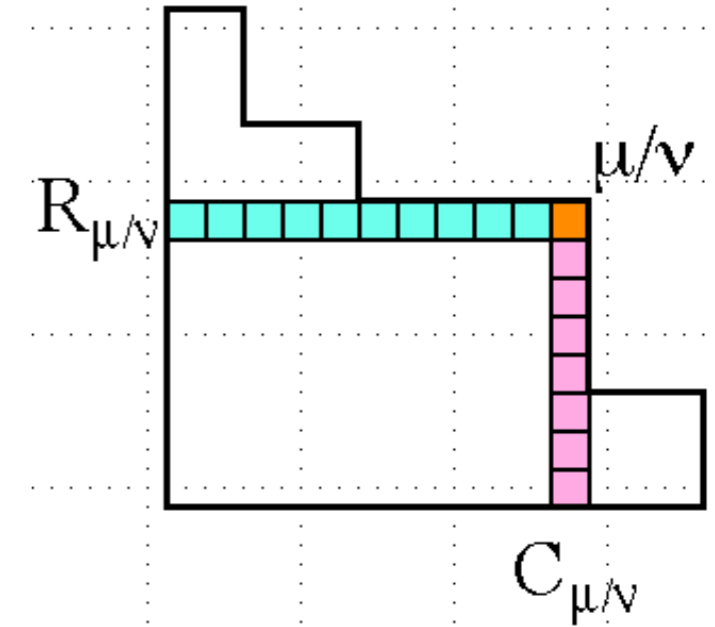
$$F_\mu(\mathbf{q}, \mathbf{t}) = \partial_{\mathbf{p}_1}^n \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(\mathbf{q}, \mathbf{t}) \partial_{\mathbf{p}_1}^{n-1} \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{\mathbf{p}_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

$$c_{\mu\nu}(\mathbf{q}, \mathbf{t}) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$

where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote
the collections of cells of ν
that are respectively in the



row and the column of the cell μ/ν .

The Hilbert series

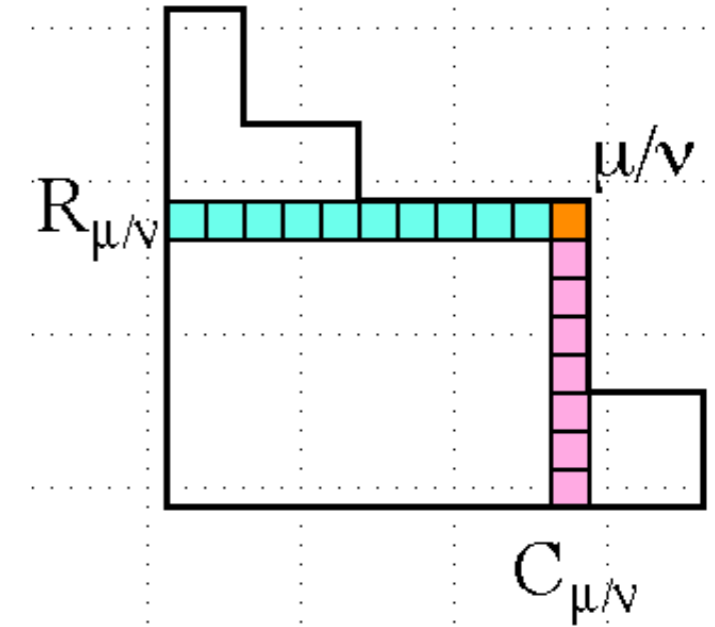
$$F_\mu(\mathbf{q}, \mathbf{t}) = \partial_{\mathbf{p}_1}^n \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(\mathbf{q}, \mathbf{t}) \partial_{\mathbf{p}_1}^{n-1} \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) F_\nu(\mathbf{q}, \mathbf{t})$$

The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{p_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, t) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, t]$$

$$c_{\mu\nu}(\mathbf{q}, t) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$

where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote
the collections of cells of ν
that are respectively in the



row and the column of the cell μ/ν .

The Hilbert series

$$F_\mu(\mathbf{q}, t) = \partial_{p_1}^n \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) \partial_{p_1}^{n-1} \tilde{H}_\nu[x; q, t] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(\mathbf{q}, t) F_\nu(\mathbf{q}, t)$$

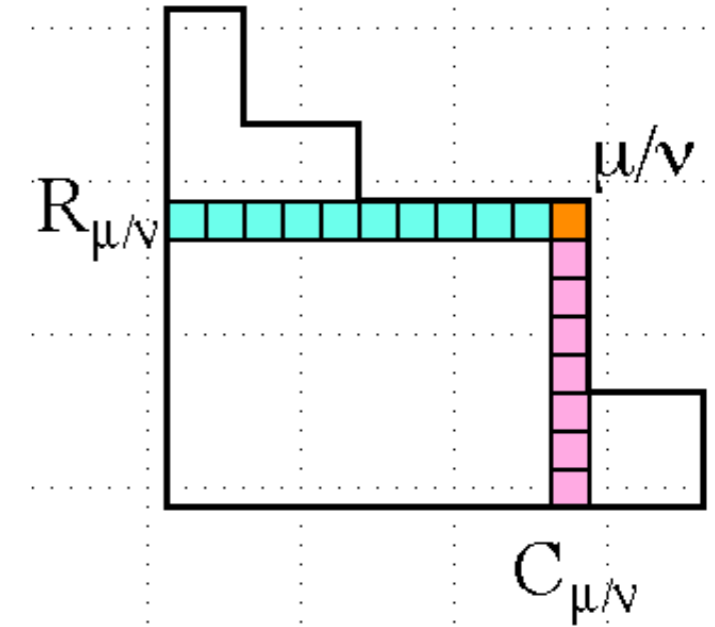
$$F_\mu(q, t) = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) F_\nu(q, t)$$

The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{\mathbf{p}_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

$$c_{\mu\nu}(\mathbf{q}, \mathbf{t}) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$

where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote
the collections of cells of ν
that are respectively in the



row and the column of the cell μ/ν .

The Hilbert series

$$F_\mu(\mathbf{q}, \mathbf{t}) = \partial_{\mathbf{p}_1}^n \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(\mathbf{q}, \mathbf{t}) \partial_{\mathbf{p}_1}^{n-1} \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(\mathbf{q}, \mathbf{t}) F_\nu(\mathbf{q}, \mathbf{t})$$

Using Maple

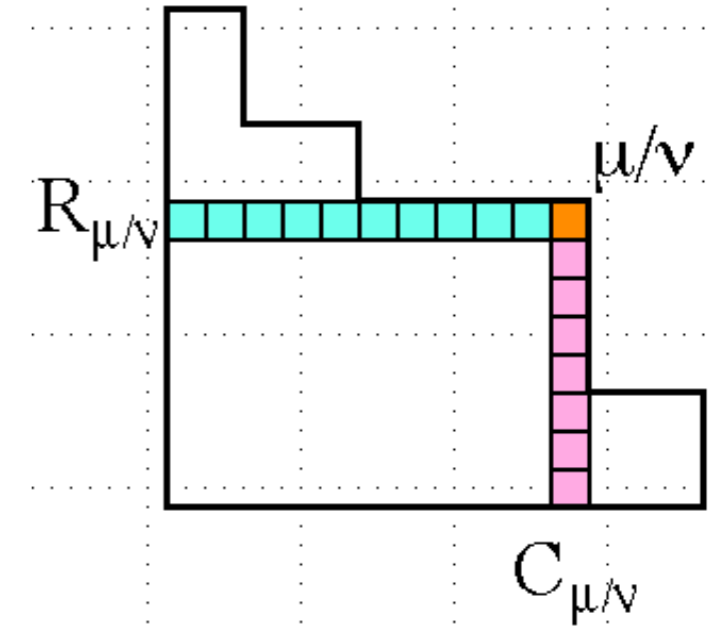
$$F_\mu(q, t) = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) F_\nu(q, t)$$

The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{p_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

$$c_{\mu\nu}(\mathbf{q}, \mathbf{t}) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$

where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote
the collections of cells of ν
that are respectively in the



row and the column of the cell μ/ν .

The Hilbert series

$$F_\mu(\mathbf{q}, \mathbf{t}) = \partial_{p_1}^n \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) \partial_{p_1}^{n-1} \tilde{H}_\nu[x; q, t] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) F_\nu(\mathbf{q}, \mathbf{t})$$

$$F_\mu(q, t) = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) F_\nu(q, t)$$

Using Maple

```
hilb([3,2]);
```

The Macdonald-Stanley (dual) Pieri Rules

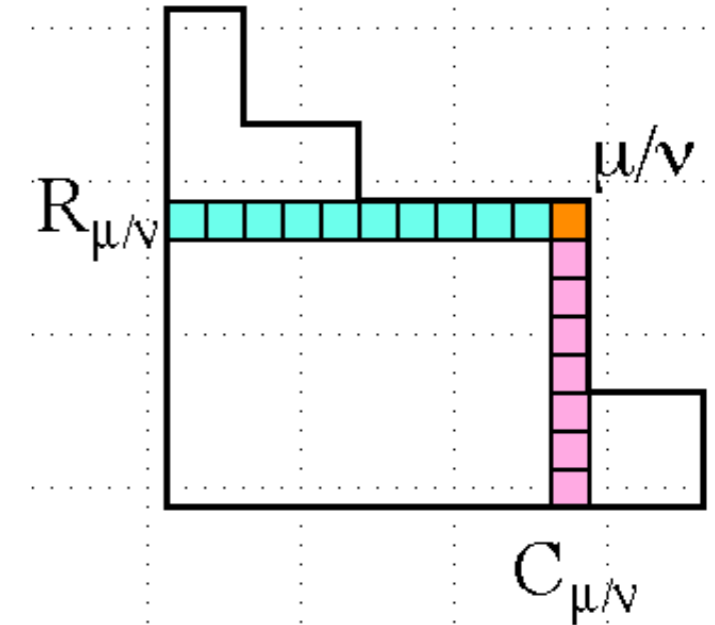
$$\partial_{\mathbf{p}_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

$$c_{\mu\nu}(\mathbf{q}, \mathbf{t}) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$

where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote

the collections of cells of ν

that are respectively in the



row and the column of the cell μ/ν .

The Hilbert series

$$F_\mu(\mathbf{q}, \mathbf{t}) = \partial_{\mathbf{p}_1}^n \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) \partial_{p_1}^{n-1} \tilde{H}_\nu[x; q, t] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) F_\nu(\mathbf{q}, \mathbf{t})$$

$$F_\mu(q, t) = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) F_\nu(q, t)$$

Using Maple

`hilb([3,2]);`

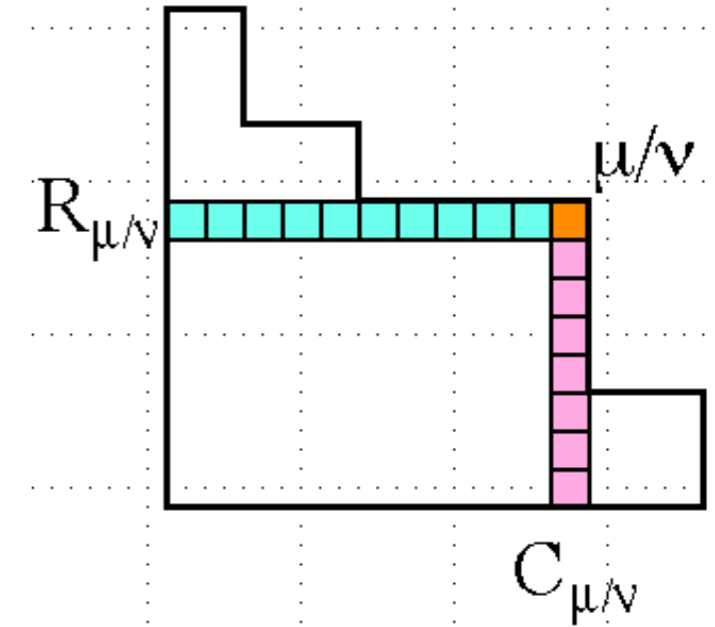
$$q^4 t^2 + 4 q^4 t + 4 q^3 t^2 + 5 q^4 + 15 q^3 t + 9 q^2 t^2 + 11 q^3 + 22 q^2 t + 11 q t^2 + 9 q^2 + 15 q t + 5 t^2 + 4 q + 4 t + 1$$

The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{\mathbf{p}_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

$$c_{\mu\nu}(\mathbf{q}, \mathbf{t}) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$

where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote
the collections of cells of ν
that are respectively in the



row and the column of the cell μ/ν .

The Hilbert series

$$F_\mu(\mathbf{q}, \mathbf{t}) = \partial_{\mathbf{p}_1}^n \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) \partial_{\mathbf{p}_1}^{n-1} \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(\mathbf{q}, \mathbf{t}) F_\nu(\mathbf{q}, \mathbf{t})$$

$$F_\mu(q, t) = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) F_\nu(q, t)$$

Using Maple

`hilb([3,2]);`

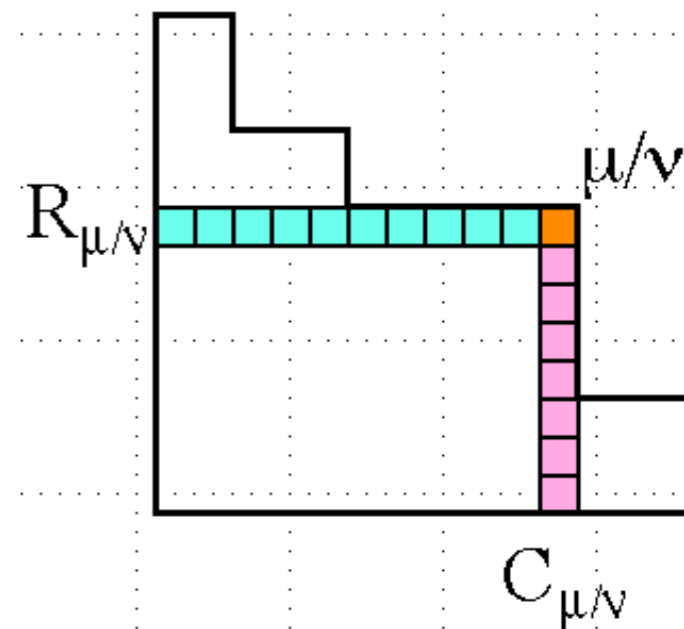
$$q^4 t^2 + 4 q^4 t + 4 q^3 t^2 + 5 q^4 + 15 q^3 t + 9 q^2 t^2 + 11 q^3 + 22 q^2 t + 11 q t^2 + 9 q^2 + 15 q t + 5 t^2 + 4 q + 4 t + 1$$

$$\begin{bmatrix} 5 & 11 & 9 & 4 & 1 \\ 4 & 15 & 22 & 15 & 4 \\ 1 & 4 & 9 & 11 & 5 \end{bmatrix}$$

The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{\mathbf{p}_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

$$c_{\mu\nu}(\mathbf{q}, \mathbf{t}) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$



where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote the collections of cells of ν that are respectively in the

row and the column of the cell μ/ν .

The Hilbert series

$$F_\mu(\mathbf{q}, \mathbf{t}) = \partial_{\mathbf{p}_1}^n \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) \partial_{\mathbf{p}_1}^{n-1} \tilde{H}_\nu[x; q, t] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(\mathbf{q}, \mathbf{t}) F_\nu(\mathbf{q}, \mathbf{t})$$

$$F_\mu(q, t) = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) F_\nu(q, t)$$

Using Maple

`hilb([3,2]);`

$$q^4 t^2 + 4 q^4 t + 4 q^3 t^2 + 5 q^4 + 15 q^3 t + 9 q^2 t^2 + 11 q^3 + 22 q^2 t + 11 q t^2 + 9 q^2 + 15 q t + 5 t^2 + 4 q + 4 t + 1$$

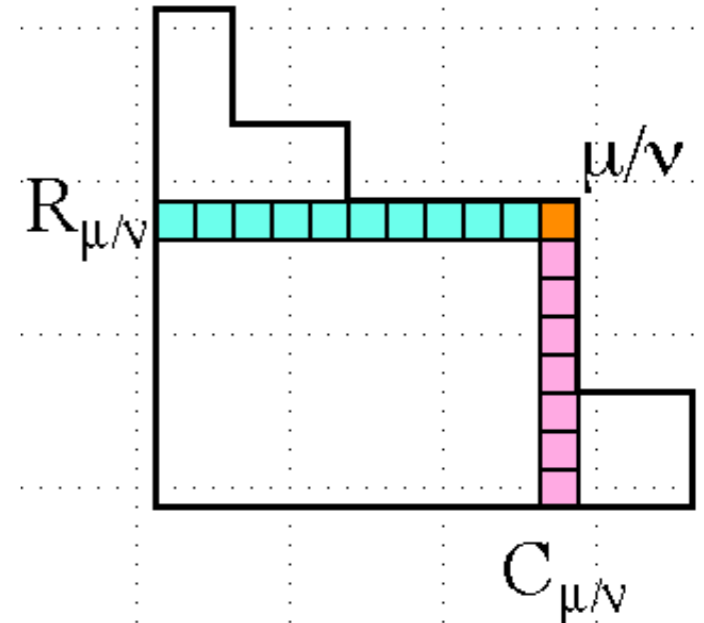
$$\begin{array}{r} 2 \rightarrow \\ 1 \rightarrow \\ 0 \rightarrow \end{array} \begin{bmatrix} 5 & 11 & 9 & 4 & 1 \\ 4 & 15 & 22 & 15 & 4 \\ 1 & 4 & 9 & 11 & 5 \end{bmatrix}$$

$$\begin{array}{c} \uparrow \\ \uparrow \\ \uparrow \\ \uparrow \\ \uparrow \end{array} \begin{array}{c} 0 \\ 1 \\ 2 \\ 3 \\ 4 \end{array}$$

The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{p_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, t) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, t]$$

$$c_{\mu\nu}(\mathbf{q}, t) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$



where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote the collections of cells of ν that are respectively in the

row and the column of the cell μ/ν .

The Hilbert series

$$F_\mu(\mathbf{q}, t) = \partial_{p_1}^n \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) \partial_{p_1}^{n-1} \tilde{H}_\nu[x; q, t] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(\mathbf{q}, t) F_\nu(\mathbf{q}, t)$$

$$F_\mu(q, t) = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) F_\nu(q, t)$$

Using Maple

`hilb([3,2]);`

$$q^4 t^2 + 4 q^4 t + 4 q^3 t^2 + 5 q^4 + 15 q^3 t + 9 q^2 t^2 + 11 q^3 + 22 q^2 t + 11 q t^2 + 9 q^2 + 15 q t + 5 t^2 + 4 q + 4 t + 1$$

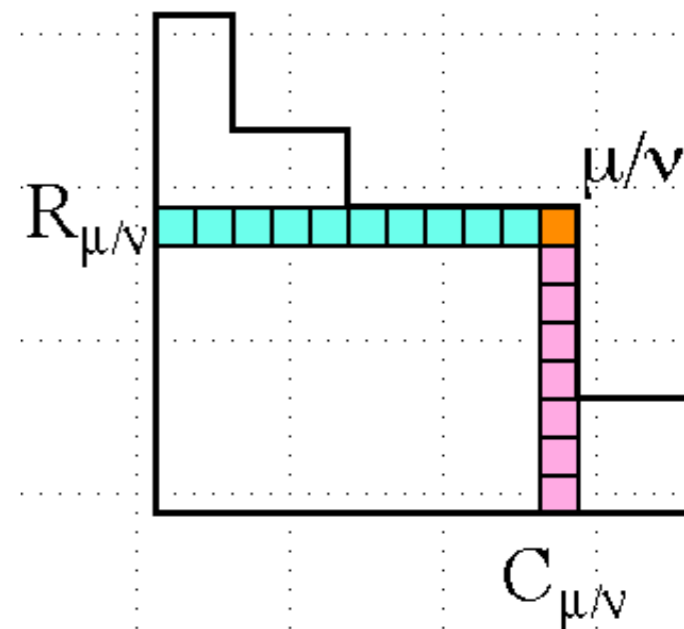
The dimension of $H_{2,1}(M_{3,2}[\mathbf{X}, \mathbf{Y}])$

	2	→	5	11	9	4	1
	1	→	4	15	22	15	4
	0	→	1	4	9	11	5
			↑	↑	↑	↑	↑
			0	1	2	3	4

The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{p_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, t) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, t]$$

$$c_{\mu\nu}(\mathbf{q}, t) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$



where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote the collections of cells of ν that are respectively in the

row and the column of the cell μ/ν .

The Hilbert series

$$F_\mu(\mathbf{q}, t) = \partial_{p_1}^n \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) \partial_{p_1}^{n-1} \tilde{H}_\nu[\mathbf{X}; q, t] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(\mathbf{q}, t) F_\nu(\mathbf{q}, t)$$

$$F_\mu(q, t) = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) F_\nu(q, t)$$

Using Maple

`hilb([3,2]);`

$$q^4 t^2 + 4 q^4 t + 4 q^3 t^2 + 5 q^4 + 15 q^3 t + 9 q^2 t^2 + 11 q^3 + 22 q^2 t + 11 q t^2 + 9 q^2 + 15 q t + 5 t^2 + 4 q + 4 t + 1$$

The dimension of $H_{2,1}(M_{3,2}[\mathbf{X}, \mathbf{Y}])$

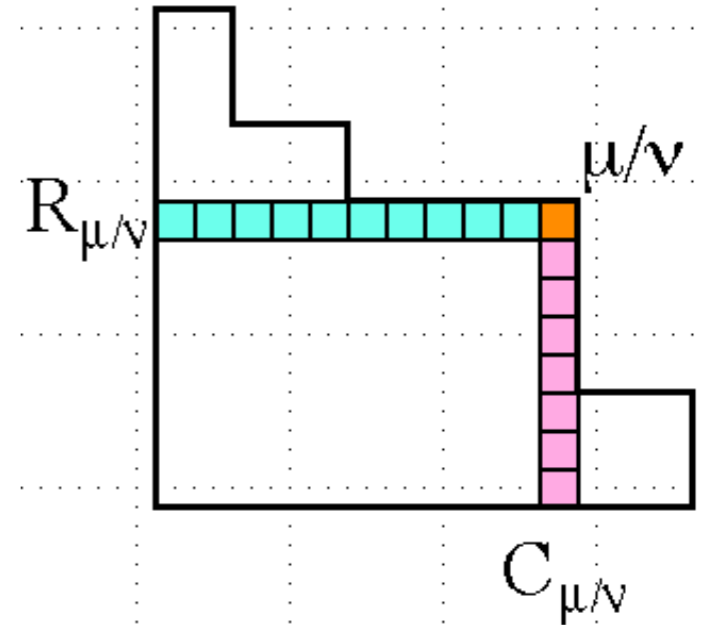
2 →	5	11	9	4	1
1 →	4	15	22	15	4
0 →	1	4	9	11	5
	↑	↑	↑	↑	↑
	0	1	2	3	4

The dimension of $H_{1,3}(M_{3,2}[\mathbf{X}, \mathbf{Y}])$

The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{\mathbf{p}_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, t) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, t]$$

$$c_{\mu\nu}(\mathbf{q}, t) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$



where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote the collections of cells of ν that are respectively in the

row and the column of the cell μ/ν .

The Hilbert series

$$F_\mu(\mathbf{q}, t) = \partial_{\mathbf{p}_1}^n \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) \partial_{\mathbf{p}_1}^{n-1} \tilde{H}_\nu[x; q, t] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(\mathbf{q}, t) F_\nu(\mathbf{q}, t)$$

$$F_\mu(q, t) = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) F_\nu(q, t)$$

Using Maple

`hilb([3,2]);`

$$q^4 t^2 + 4 q^4 t + 4 q^3 t^2 + 5 q^4 + 15 q^3 t + 9 q^2 t^2 + 11 q^3 + 22 q^2 t + 11 q t^2 + 9 q^2 + 15 q t + 5 t^2 + 4 q + 4 t + 1$$

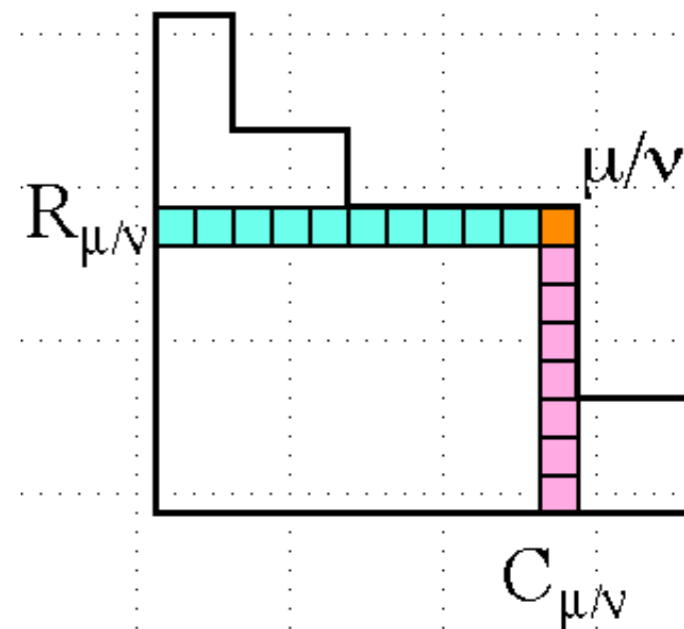
2 →	5	11	9	4	1
1 →	4	15	22	15	4
0 →	1	4	9	11	5
	↑	↑	↑	↑	↑
	0	1	2	3	4

The dimension of $H_{1,3}(M_{3,2}[\mathbf{X}, \mathbf{Y}])$

The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{p_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, t) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, t]$$

$$c_{\mu\nu}(\mathbf{q}, t) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$



where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote
the collections of cells of ν
that are respectively in the

row and the column of the cell μ/ν .

The Hilbert series

$$F_\mu(\mathbf{q}, t) = \partial_{p_1}^n \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, t] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) \partial_{p_1}^{n-1} \tilde{H}_\nu[x; q, t] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(\mathbf{q}, t) F_\nu(\mathbf{q}, t)$$

$$F_\mu(q, t) = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) F_\nu(q, t)$$

Using Maple

`hilb([3,2]);`

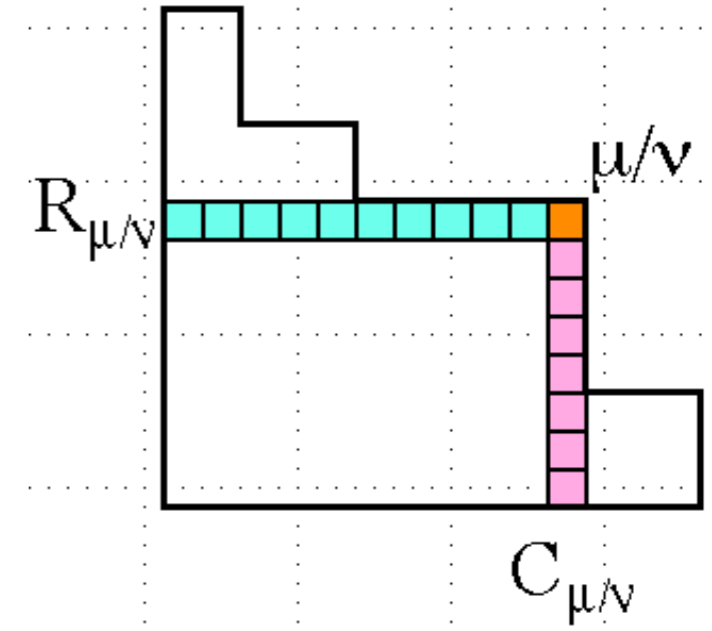
$$q^4 t^2 + 4 q^4 t + 4 q^3 t^2 + 5 q^4 + 15 q^3 t + 9 q^2 t^2 + 11 q^3 + 22 q^2 t + 11 q t^2 + 9 q^2 + 15 q t + 5 t^2 + 4 q + 4 t + 1$$

2	→	[5	11	9	4	1]
1	→	[4	15	22	15	4]
0	→	[1	4	9	11	5]
		↑	↑	↑	↑	↑		
		0	1	2	3	4		

The Macdonald-Stanley (dual) Pieri Rules

$$\partial_{\mathbf{p}_1} \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu, \nu}(\mathbf{q}, \mathbf{t}) \tilde{H}_\nu[\mathbf{X}; \mathbf{q}, \mathbf{t}]$$

$$c_{\mu\nu}(\mathbf{q}, \mathbf{t}) = \prod_{s \in R_{\mu\nu}} \frac{t^{l_\mu(s)} - q^{a_\mu(s)+1}}{t^{l_\nu(s)} - q^{a_\nu(s)+1}} \prod_{s \in C_{\mu\nu}} \frac{q^{a_\mu(s)} - t^{l_\mu(s)+1}}{q^{a_\nu(s)} - t^{l_\nu(s)+1}},$$



where $R_{\mu\nu}$ and $C_{\mu\nu}$ denote
the collections of cells of ν
that are respectively in the

row and the column of the cell μ/ν .

The Hilbert series

$$F_\mu(\mathbf{q}, \mathbf{t}) = \partial_{\mathbf{p}_1}^n \tilde{H}_\mu[\mathbf{X}; \mathbf{q}, \mathbf{t}] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) \partial_{\mathbf{p}_1}^{n-1} \tilde{H}_\nu[x; q, t] = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(\mathbf{q}, \mathbf{t}) F_\nu(\mathbf{q}, \mathbf{t})$$

$$F_\mu(q, t) = \sum_{\nu \rightarrow \mu} c_{\mu\nu}(q, t) F_\nu(q, t)$$

Using Maple

`hilb([3,2]);`

$$q^4 t^2 + 4 q^4 t + 4 q^3 t^2 + 5 q^4 + 15 q^3 t + 9 q^2 t^2 + 11 q^3 + 22 q^2 t + 11 q t^2 + 9 q^2 + 15 q t + 5 t^2 + 4 q + 4 t + 1$$

2 →	[5	11	9	4	1]
1 →	[4	15	22	15	4]
0 →	[1	4	9	11	5]
		↑	↑	↑	↑	↑
		0	1	2	3	4

next

How it all started

How it all started

Recall that from the Haglund-Haiman-Loehr result we now have statistics $a(T), b(T)$

How it all started

Recall that from the Haglund-Haiman-Loehr result we now have statistics $a(T), b(T)$

$$F_{\mu}(\mathbf{q}, t) = \sum_{T \in \text{INJ}(\mu)} t^{a(T)} \mathbf{q}^{b(T)}$$

How it all started

Recall that from the Haglund-Haiman-Loehr result we now have statistics $a(T), b(T)$

$$F_{\mu}(\mathbf{q}, t) = \sum_{T \in \text{INJ}(\mu)} t^{a(T)} \mathbf{q}^{b(T)}$$

This was established by means of original Macdonald identities

How it all started

Recall that from the Haglund-Haiman-Loehr result we now have statistics $a(T), b(T)$

$$F_{\mu}(\mathbf{q}, t) = \sum_{T \in \text{INJ}(\mu)} t^{a(T)} \mathbf{q}^{b(T)}$$

This was established by means of original Macdonald identities

Its relation to the corresponding S_n module M_{μ} is yet to be found.

How it all started

Recall that from the Haglund-Haiman-Loehr result we now have statistics $a(T), b(T)$

$$F_{\mu}(\mathbf{q}, t) = \sum_{T \in \text{INJ}(\mu)} t^{a(T)} \mathbf{q}^{b(T)}$$

This was established by means of original Macdonald identities

Its relation to the corresponding S_n module M_{μ} is yet to be found.

In a new burst of genius Jim conjectured that

How it all started

Recall that from the Haglund-Haiman-Loehr result we now have statistics $a(T), b(T)$

$$F_{\mu}(q, t) = \sum_{T \in \text{INJ}(\mu)} t^{a(T)} q^{b(T)}$$

This was established by means of original Macdonald identities

Its relation to the corresponding S_n module M_{μ} is yet to be found.

In a new burst of genius Jim conjectured that

$$F_{2^b 1^{a-b}}(q, t) =$$

How it all started

Recall that from the Haglund-Haiman-Loehr result we now have statistics $a(T), b(T)$

$$F_{\mu}(q, t) = \sum_{T \in \text{INJ}(\mu)} t^{a(T)} q^{b(T)}$$

This was established by means of original Macdonald identities

Its relation to the corresponding S_n module M_{μ} is yet to be found.

In a new burst of genius Jim conjectured that

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})}$$

How it all started

Recall that from the Haglund-Haiman-Loehr result we now have statistics $a(T), b(T)$

$$F_{\mu}(q, t) = \sum_{T \in \text{INJ}(\mu)} t^{a(T)} q^{b(T)}$$

This was established by means of original Macdonald identities

Its relation to the corresponding S_n module M_{μ} is yet to be found.

In a new burst of genius Jim conjectured that

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [\text{drop}_i(T)]_t$$

How it all started

Recall that from the Haglund-Haiman-Loehr result we now have statistics $a(T), b(T)$

$$F_{\mu}(q, t) = \sum_{T \in \text{INJ}(\mu)} t^{a(T)} q^{b(T)}$$

This was established by means of original Macdonald identities

Its relation to the corresponding S_n module M_{μ} is yet to be found.

In a new burst of genius Jim conjectured that

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [\text{drop}_i(T)]_t \prod_{i \in \text{col}_2(T)} (t^{NW(T) > i} + q)$$

How it all started

Recall that from the Haglund-Haiman-Loehr result we now have statistics $a(T), b(T)$

$$F_{\mu}(q, t) = \sum_{T \in \text{INJ}(\mu)} t^{a(T)} q^{b(T)}$$

This was established by means of original Macdonald identities

Its relation to the corresponding S_n module M_{μ} is yet to be found.

In a new burst of genius Jim conjectured that

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [\text{drop}_i(T)]_t \prod_{i \in \text{col}_2(T)} (t^{NW(T) > i} + q)$$

How it all started

Recall that from the Haglund-Haiman-Loehr result we now have statistics $a(T), b(T)$

$$F_{\mu}(q, t) = \sum_{T \in \text{INJ}(\mu)} t^{a(T)} q^{b(T)}$$

This was established by means of original Macdonald identities

Its relation to the corresponding S_n module M_{μ} is yet to be found.

In a new burst of genius Jim conjectured that

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [\text{drop}_i(T)]_t \prod_{i \in \text{col}_2(T)} (t^{NW(T) > i} + q)$$

With “ $\text{drop}_T(i)$ ” is the number of rows in $T_{\leq i}$ of the same length as the row that contains i ,

How it all started

Recall that from the Haglund-Haiman-Loehr result we now have statistics $a(T), b(T)$

$$F_{\mu}(q, t) = \sum_{T \in \text{INJ}(\mu)} t^{a(T)} q^{b(T)}$$

This was established by means of original Macdonald identities

Its relation to the corresponding S_n module M_{μ} is yet to be found.

In a new burst of genius Jim conjectured that

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [\text{drop}_i(T)]_t \prod_{i \in \text{col}_2(T)} (t^{\text{NW}(T) > i} + q)$$

With “ $\text{drop}_T(i)$ ” is the number of rows in $T_{\leq i}$ of the same length as the row that contains i ,

and “ $\text{NW}(T) > i$ ” gives the number of entries in T strictly NW of i that are larger than i .

How it all started

Recall that from the Haglund-Haiman-Loehr result we now have statistics $a(T), b(T)$

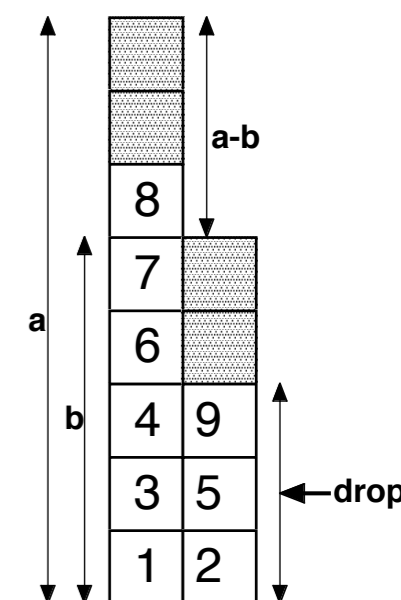
$$F_{\mu}(q, t) = \sum_{T \in \text{INJ}(\mu)} t^{a(T)} q^{b(T)}$$

This was established by means of original Macdonald identities

Its relation to the corresponding S_n module M_{μ} is yet to be found.

In a new burst of genius Jim conjectured that

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [\text{drop}_i(T)]_t \prod_{i \in \text{col}_2(T)} (t^{\text{NW}(T) > i} + q)$$



With “ $\text{drop}_T(i)$ ” is the number of rows in $T_{\leq i}$ of the same length as the row that contains i ,

and “ $\text{NW}(T) > i$ ” gives the number of entries in T strictly NW of i that are larger than i .

How it all started

Recall that from the Haglund-Haiman-Loehr result we now have statistics $a(T), b(T)$

$$F_{\mu}(q, t) = \sum_{T \in \text{INJ}(\mu)} t^{a(T)} q^{b(T)}$$

This was established by means of original Macdonald identities

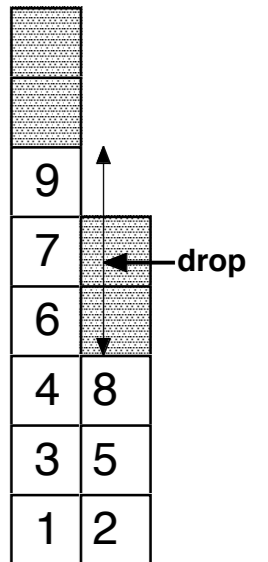
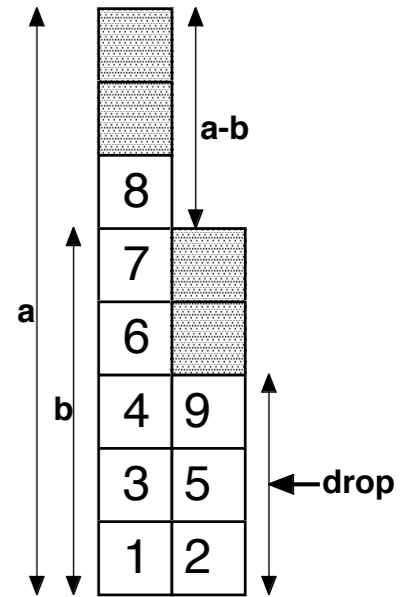
Its relation to the corresponding S_n module M_{μ} is yet to be found.

In a new burst of genius Jim conjectured that

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [\text{drop}_i(T)]_t \prod_{i \in \text{col}_2(T)} (t^{\text{NW}(T) > i} + q)$$

With “ $\text{drop}_T(i)$ ” is the number of rows in $T_{\leq i}$ of the same length as the row that contains i ,

and “ $\text{NW}(T) > i$ ” gives the number of entries in T strictly NW of i that are larger than i .



How it all started

Recall that from the Haglund-Haiman-Loehr result we now have statistics $a(T), b(T)$

$$F_{\mu}(q, t) = \sum_{T \in \text{INJ}(\mu)} t^{a(T)} q^{b(T)}$$

This was established by means of original Macdonald identities

Its relation to the corresponding S_n module M_{μ} is yet to be found.

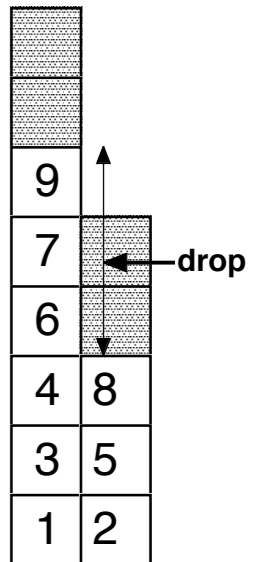
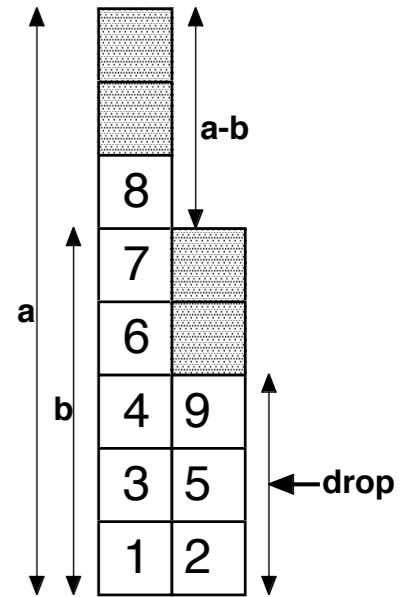
In a new burst of genius Jim conjectured that

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [\text{drop}_i(T)]_t \prod_{i \in \text{col}_2(T)} (t^{\text{NW}(T) > i} + q)$$

With “ $\text{drop}_T(i)$ ” is the number of rows in $T_{\leq i}$ of the same length as the row that contains i ,

and “ $\text{NW}(T) > i$ ” gives the number of entries in T strictly NW of i that are larger than i .

and posed me the problem to prove it



How it all started

Recall that from the Haglund-Haiman-Loehr result we now have statistics $a(T), b(T)$

$$F_{\mu}(q, t) = \sum_{T \in \text{INJ}(\mu)} t^{a(T)} q^{b(T)}$$

This was established by means of original Macdonald identities

Its relation to the corresponding S_n module M_{μ} is yet to be found.

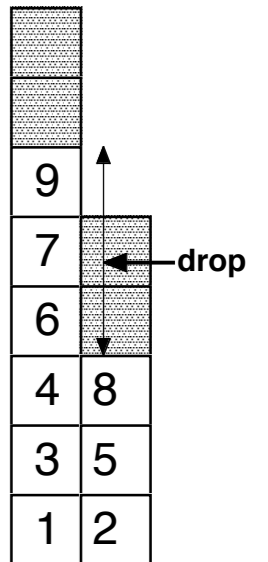
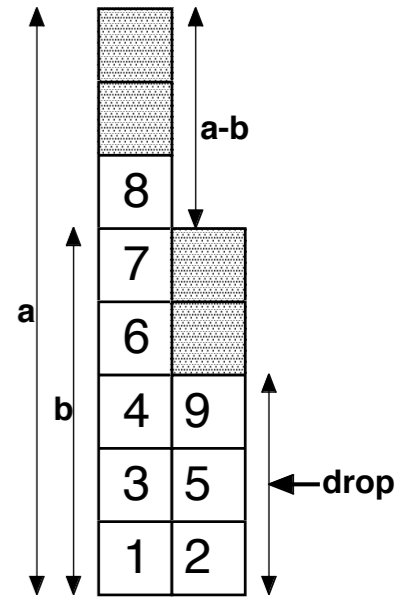
In a new burst of genius Jim conjectured that

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [\text{drop}_i(T)]_t \prod_{i \in \text{col}_2(T)} (t^{\text{NW}(T) > i} + q)$$

With “ $\text{drop}_T(i)$ ” is the number of rows in $T_{\leq i}$ of the same length as the row that contains i ,

and “ $\text{NW}(T) > i$ ” gives the number of entries in T strictly NW of i that are larger than i .

and posed me the problem to prove it



next

The recursion underlying the formula

The recursion underlying the formula

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [drop_i(T)]_t \prod_{i \in col_2(T)} (t^{NW(T) > i} + q)$$

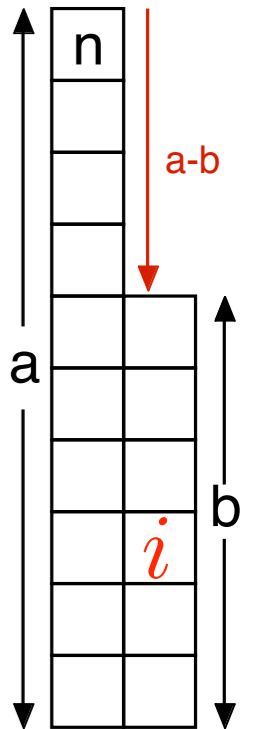
The recursion underlying the formula

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [\text{drop}_i(T)]_t \prod_{i \in \text{col}_2(T)} (t^{NW(T) > i} + q)$$

$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

The recursion underlying the formula

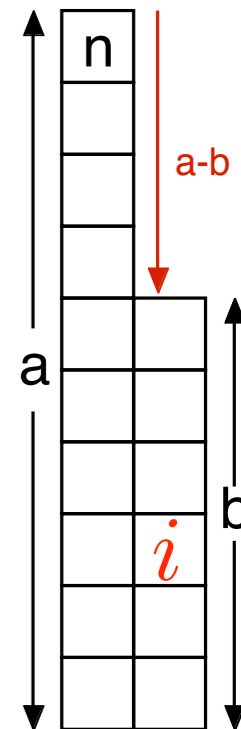
$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [drop_i(T)]_t \prod_{i \in col_2(T)} (t^{NW(T) > i} + q)$$



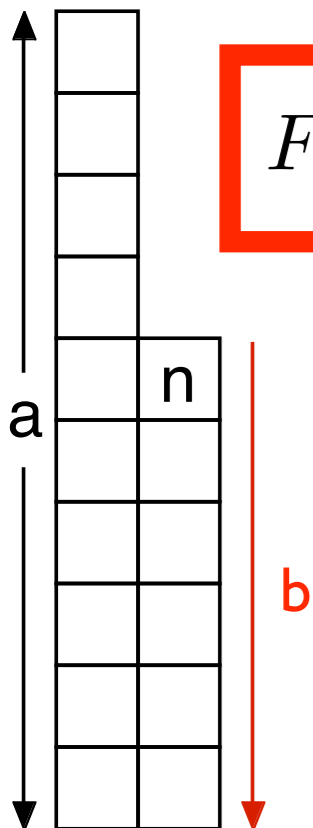
$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

The recursion underlying the formula

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [\text{drop}_i(T)]_t \prod_{i \in \text{col}_2(T)} (t^{\text{NW}(T) > i} + q)$$

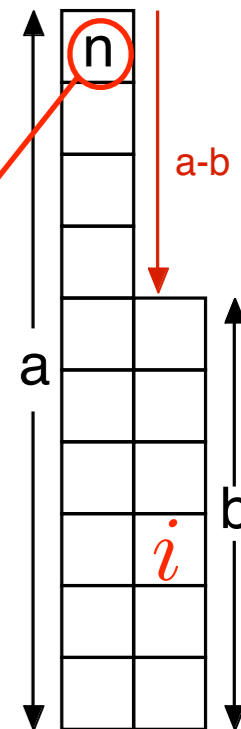


$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

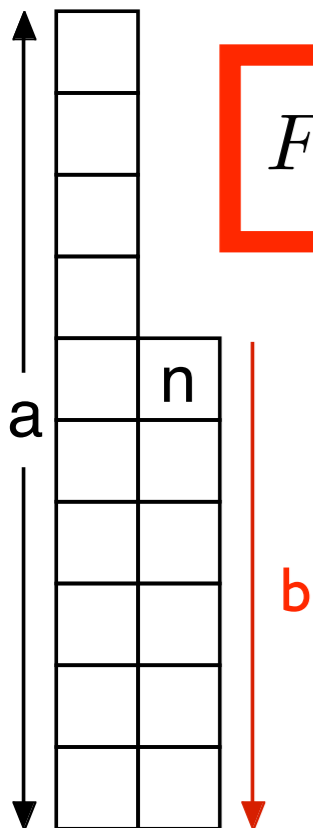


The recursion underlying the formula

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [\text{drop}_i(T)]_t \prod_{i \in \text{col}_2(T)} (t^{\text{NW}(T) > i} + q)$$

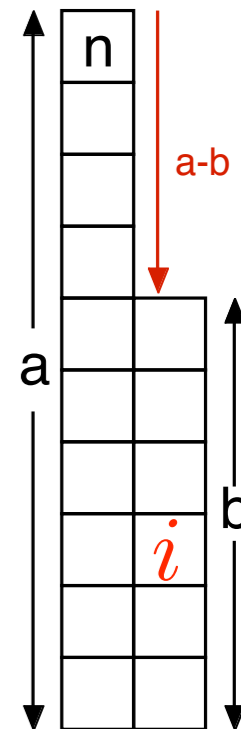


$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a-b]_t F_{a-1,b}(q/t, t)$$

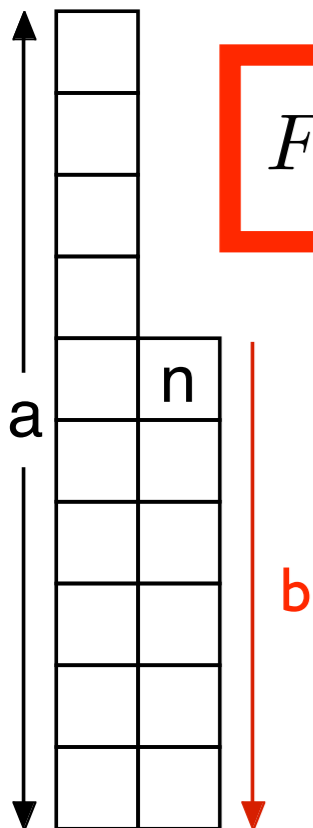


The recursion underlying the formula

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [\text{drop}_i(T)]_t \prod_{i \in \text{col}_2(T)} (t^{\text{NW}(T) > i} + q)$$

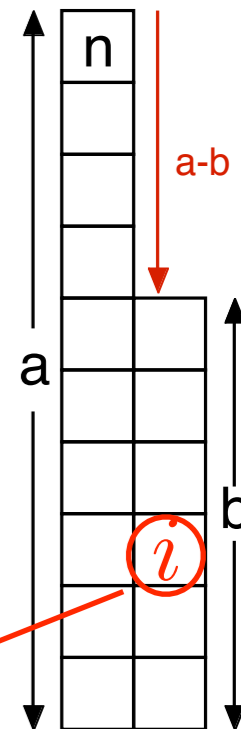


$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

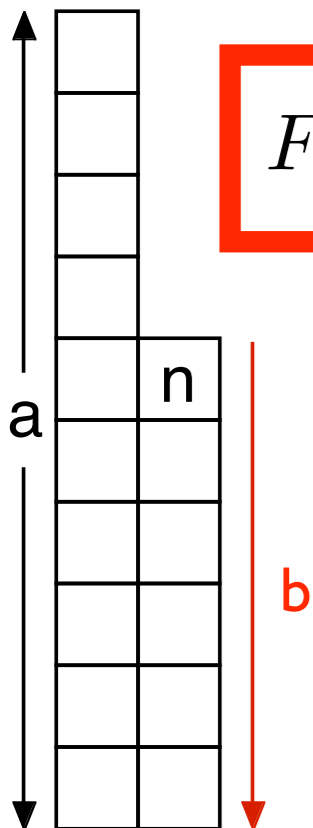


The recursion underlying the formula

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [drop_i(T)]_t \prod_{i \in col_2(T)} (t^{NW(T) > i} + q)$$

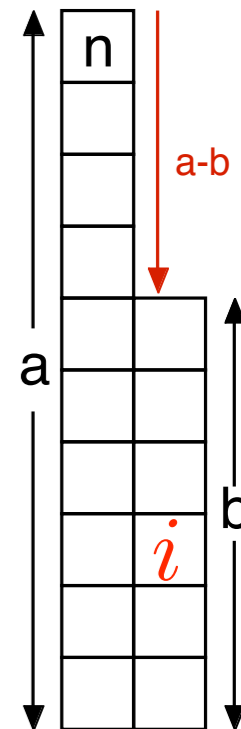


$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a-b]_t F_{a-1,b}(q/t, t)$$

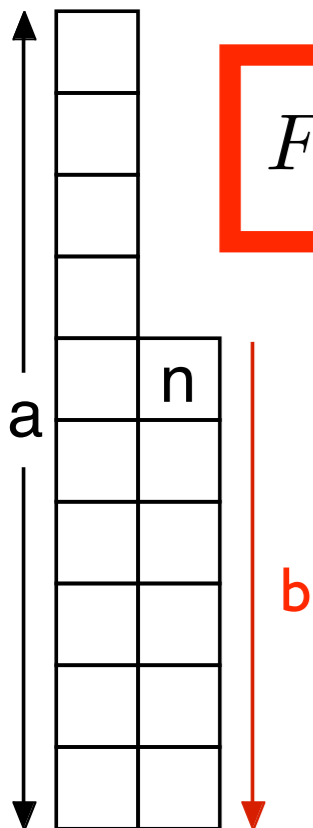


The recursion underlying the formula

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [\text{drop}_i(T)]_t \prod_{i \in \text{col}_2(T)} (t^{\text{NW}(T) > i} + q)$$

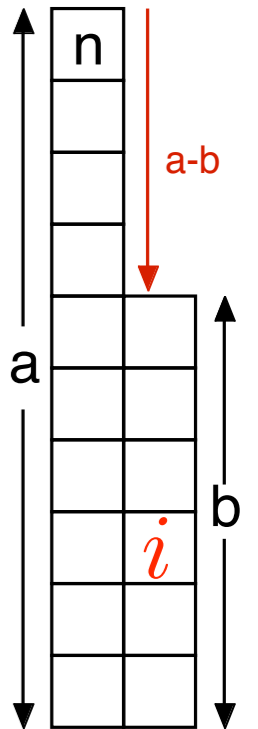


$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

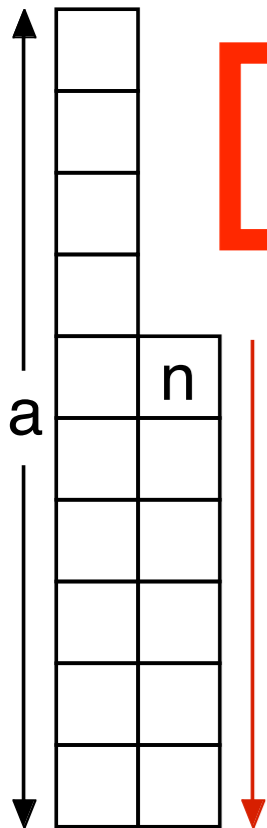


The recursion underlying the formula

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [drop_i(T)]_t \prod_{i \in col_2(T)} (t^{NW(T) > i} + q)$$

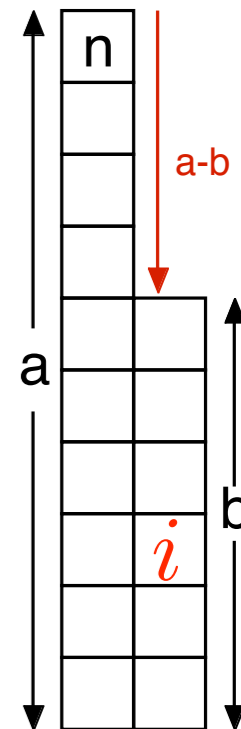


$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

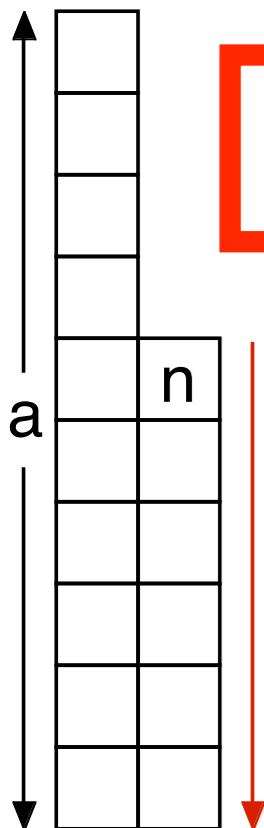


The recursion underlying the formula

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [drop_i(T)]_t \prod_{i \in col_2(T)} (t^{NW(T) > i} + q)$$

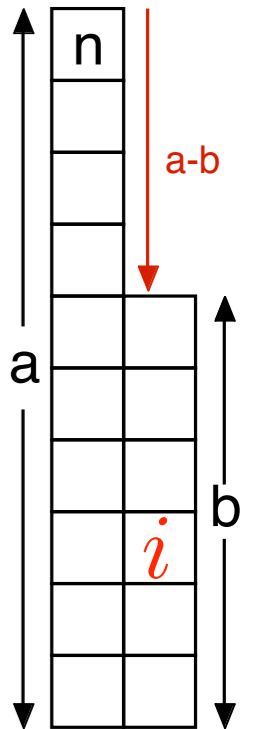


$$F_{a,b}(q, t) = (1+q) [b]_t F_{a,b-1}(q, t) + t^b [a-b]_t F_{a-1,b}(q/t, t)$$

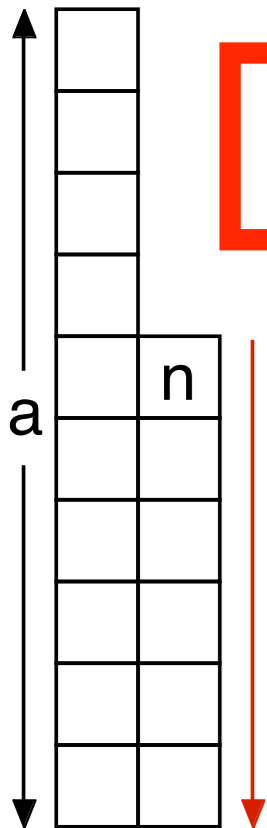


The recursion underlying the formula

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [\text{drop}_i(T)]_t \prod_{i \in \text{col}_2(T)} (t^{\text{NW}(T) > i} + q)$$

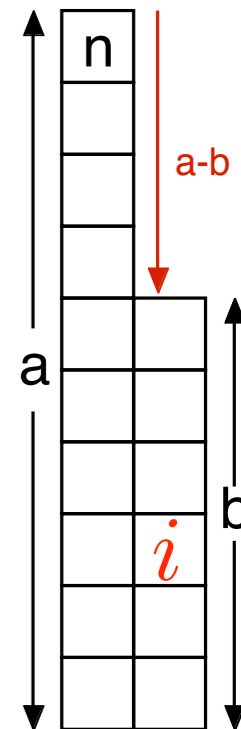


$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

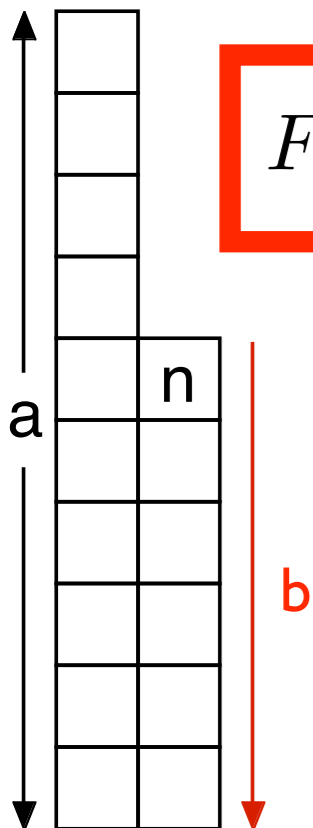


The recursion underlying the formula

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [\text{drop}_i(T)]_t \prod_{i \in \text{col}_2(T)} (t^{\text{NW}(T) > i} + q)$$

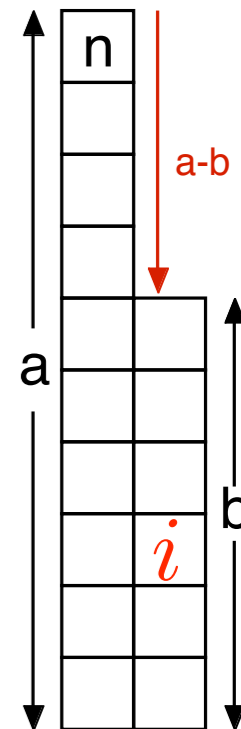


$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

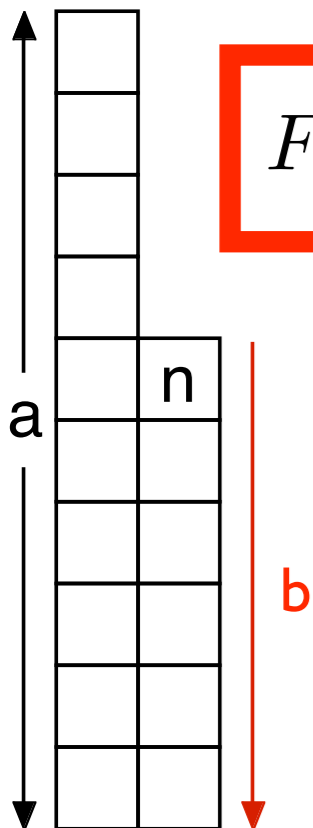


The recursion underlying the formula

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [drop_i(T)]_t \prod_{i \in col_2(T)} (t^{NW(T) > i} + q)$$

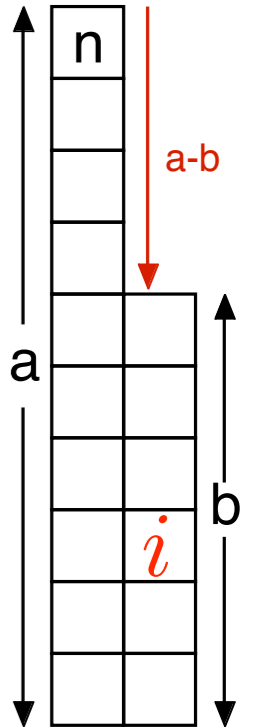


$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$



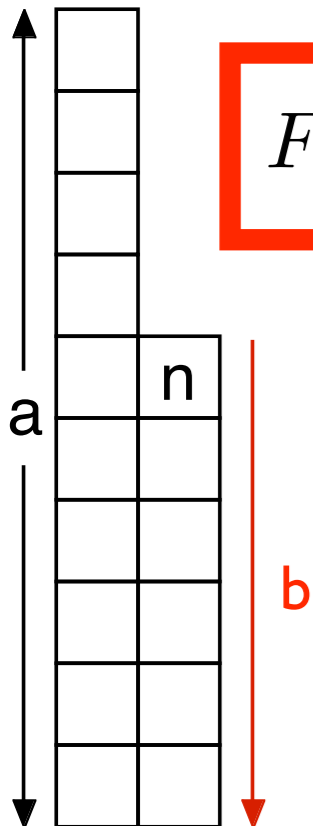
The recursion underlying the formula

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [drop_i(T)]_t \prod_{i \in col_2(T)} (t^{NW(T) > i} + q)$$



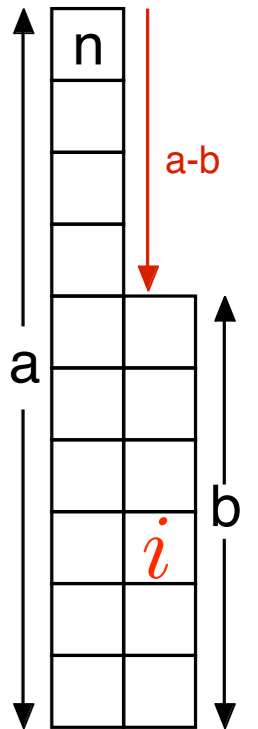
$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

This is quite remarkable



The recursion underlying the formula

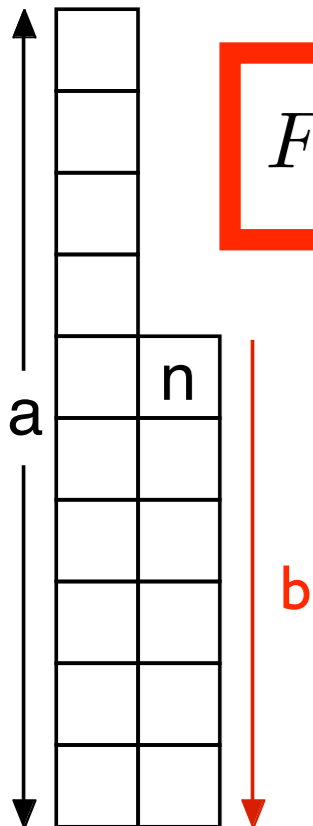
$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [drop_i(T)]_t \prod_{i \in col_2(T)} (t^{NW(T) > i} + q)$$



$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

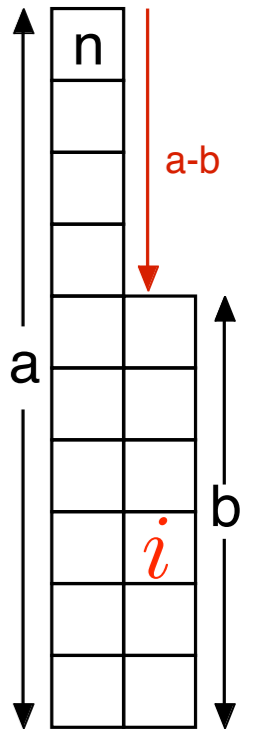
This is quite remarkable

in the 20 years since the Macdonald conjectures



The recursion underlying the formula

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [drop_i(T)]_t \prod_{i \in col_2(T)} (t^{NW(T) > i} + q)$$

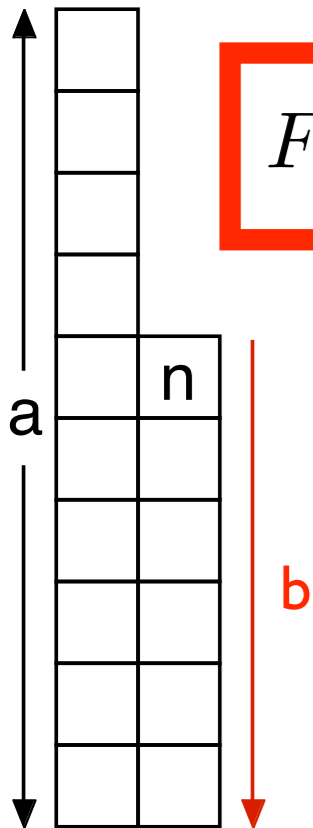


$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

This is quite remarkable

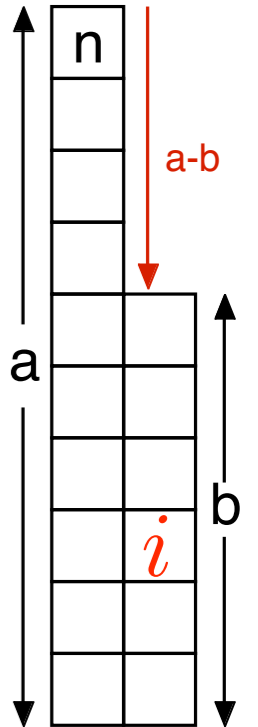
in the 20 years since the Macdonald conjectures

we never suspected that we could have



The recursion underlying the formula

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [drop_i(T)]_t \prod_{i \in col_2(T)} (t^{NW(T) > i} + q)$$



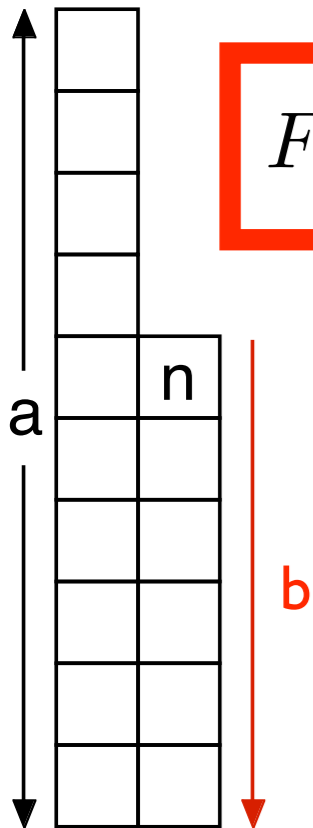
$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

This is quite remarkable

in the 20 years since the Macdonald conjectures

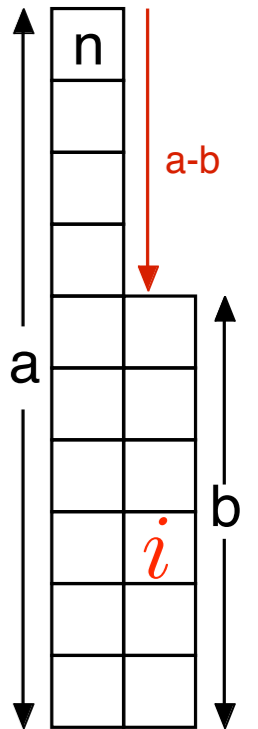
we never suspected that we could have

a purely combinatorial recursion for $F_{\mu}(q, t)$



The recursion underlying the formula

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [drop_i(T)]_t \prod_{i \in col_2(T)} (t^{NW(T) > i} + q)$$



$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

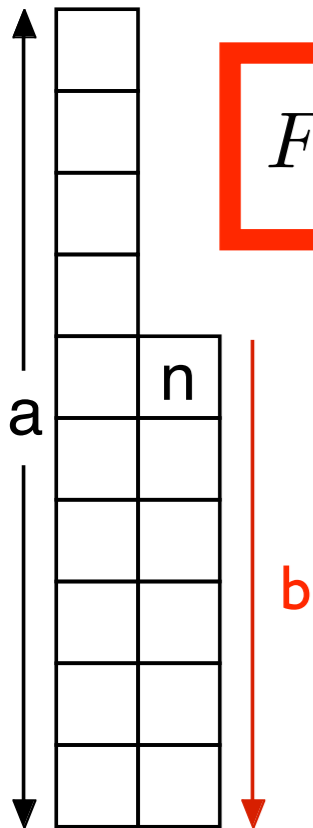
This is quite remarkable

in the 20 years since the Macdonald conjectures

we never suspected that we could have

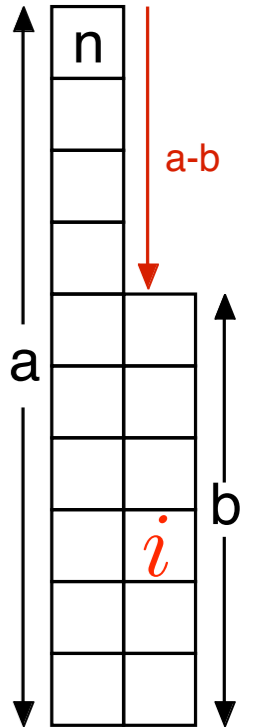
a purely combinatorial recursion for $F_{\mu}(q, t)$

We will see that this recursion stems right out of



The recursion underlying the formula

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [drop_i(T)]_t \prod_{i \in col_2(T)} (t^{NW(T) > i} + q)$$



$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

This is quite remarkable

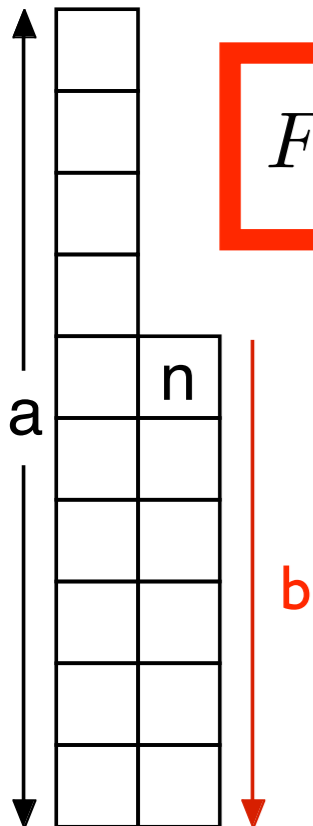
in the 20 years since the Macdonald conjectures

we never suspected that we could have

a purely combinatorial recursion for $F_\mu(q, t)$

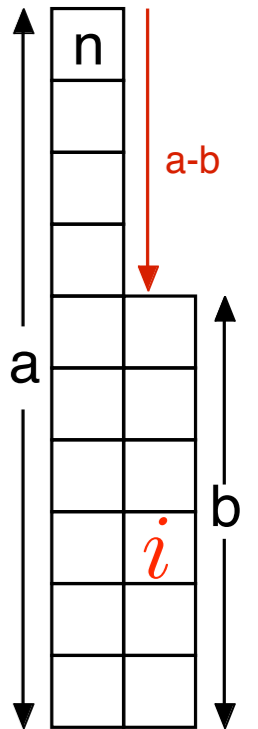
We will see that this recursion stems right out of

the Representation Theory of the modules M_μ



The recursion underlying the formula

$$F_{2^b 1^{a-b}}(q, t) = \sum_{T \in ST(2^b 1^{a-b})} \prod_{i \in T} [drop_i(T)]_t \prod_{i \in col_2(T)} (t^{NW(T) > i} + q)$$



$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

This is quite remarkable

in the 20 years since the Macdonald conjectures

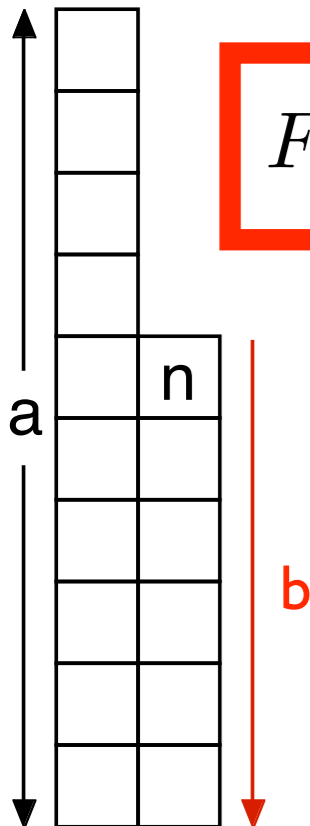
we never suspected that we could have

a purely combinatorial recursion for $F_{\mu}(q, t)$

We will see that this recursion stems right out of

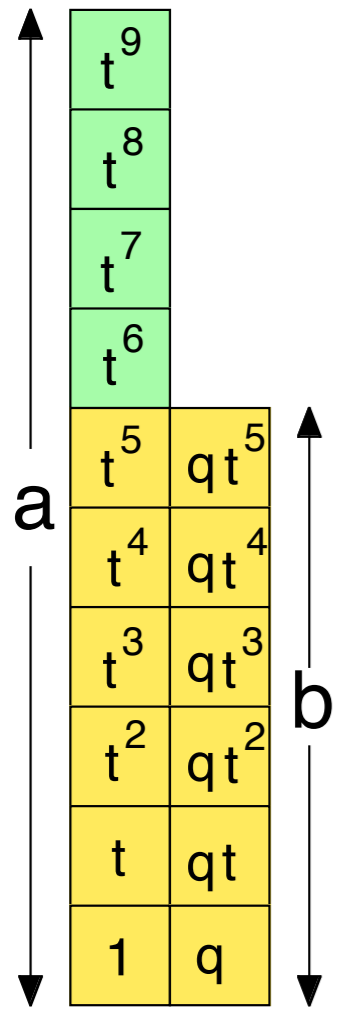
the Representation Theory of the modules M_{μ}

next

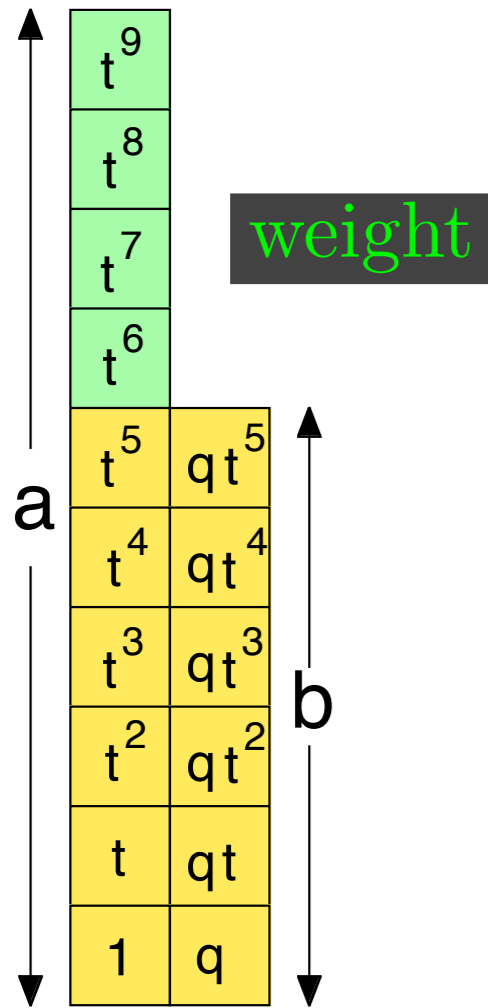


The underlying representation theoretical identity

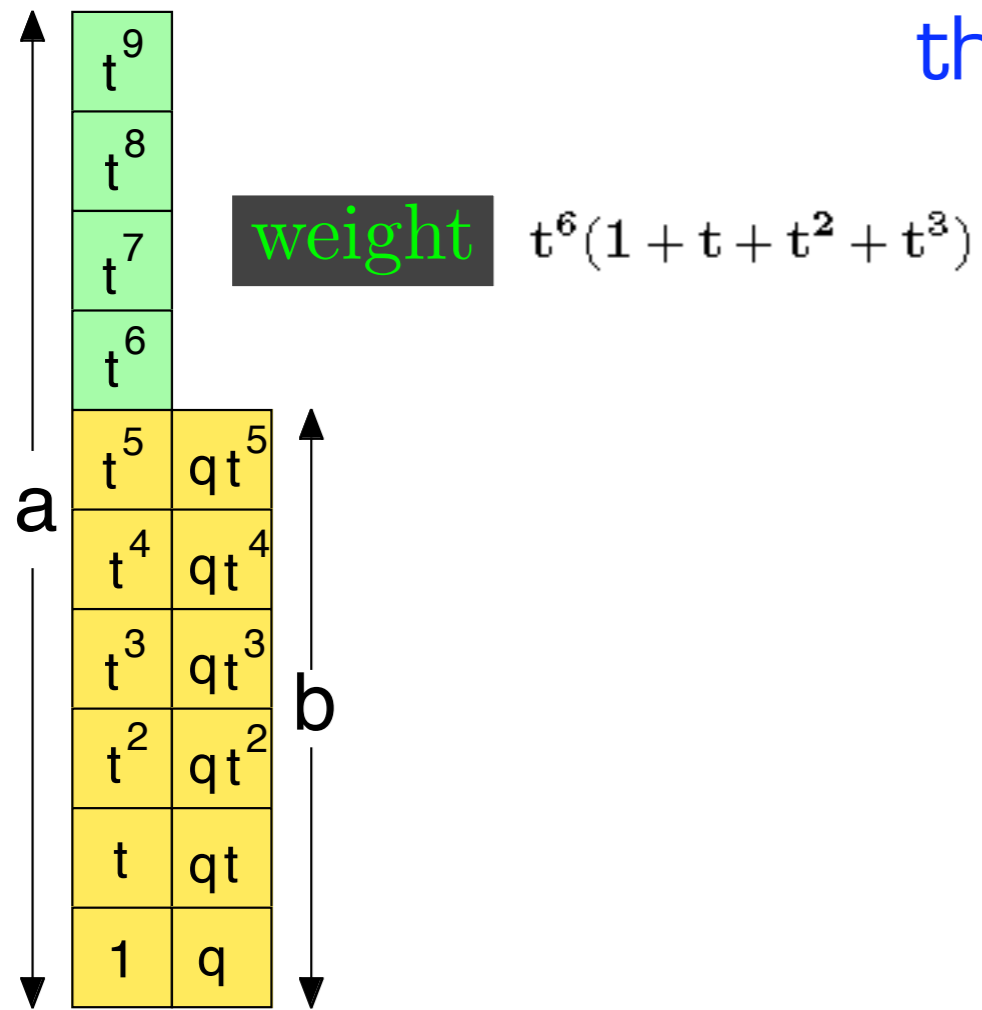
The underlying representation theoretical identity



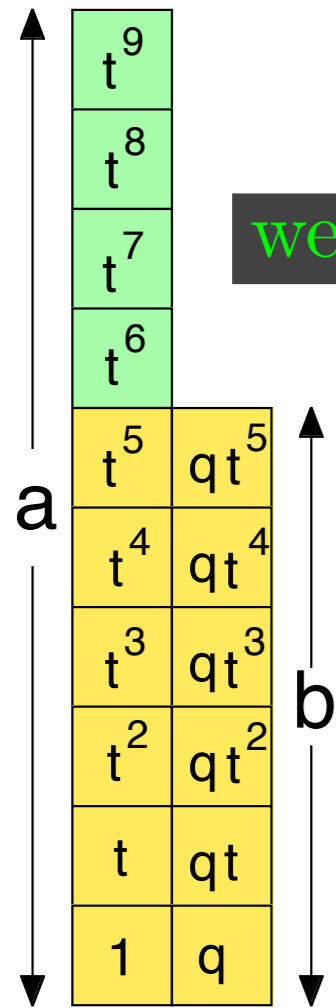
The underlying representation theoretical identity



The underlying representation theoretical identity

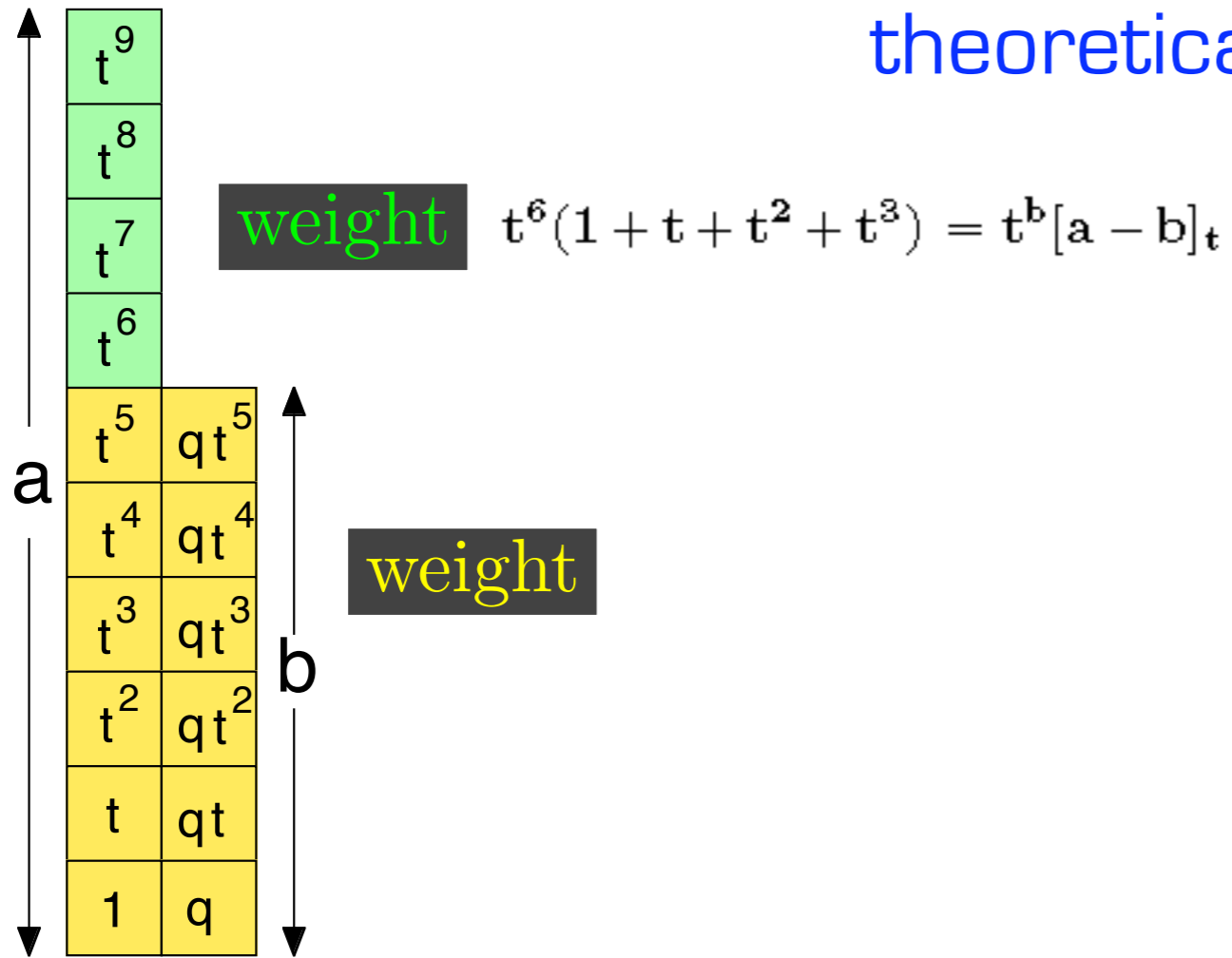


The underlying representation theoretical identity

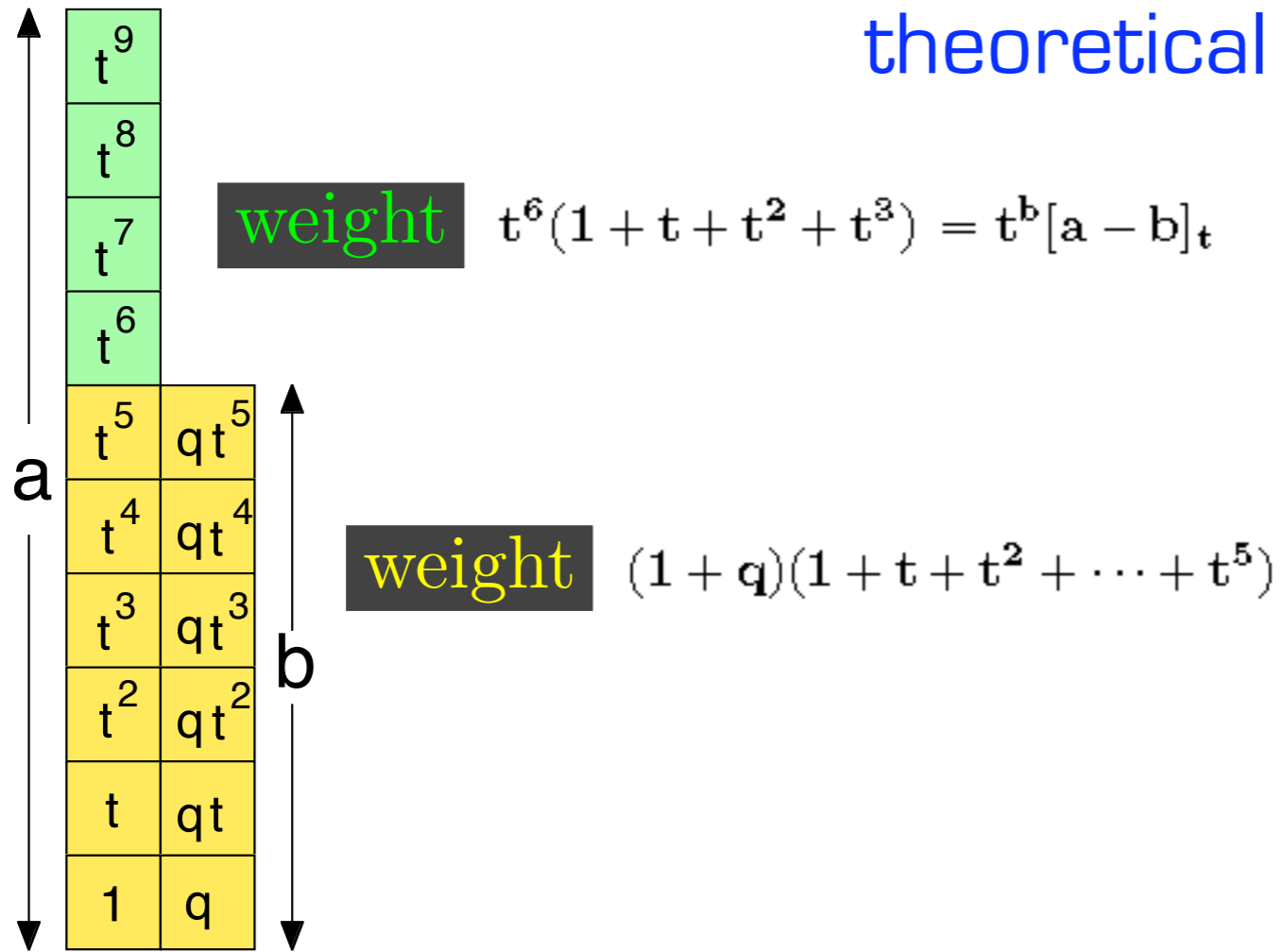


weight $t^6(1 + t + t^2 + t^3) = t^b[a - b]_t$

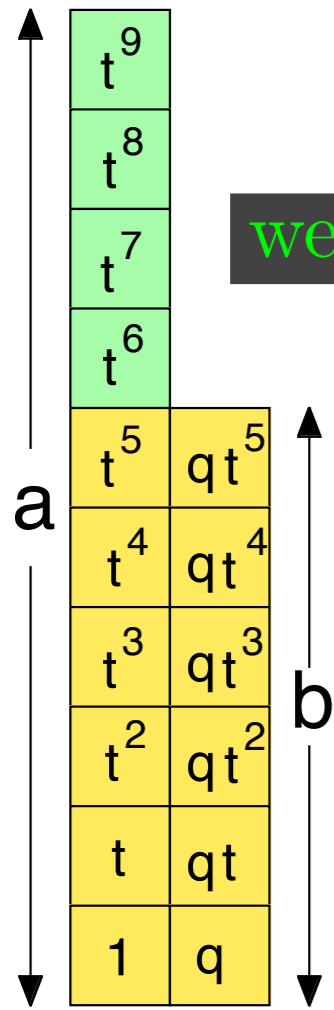
The underlying representation theoretical identity



The underlying representation theoretical identity



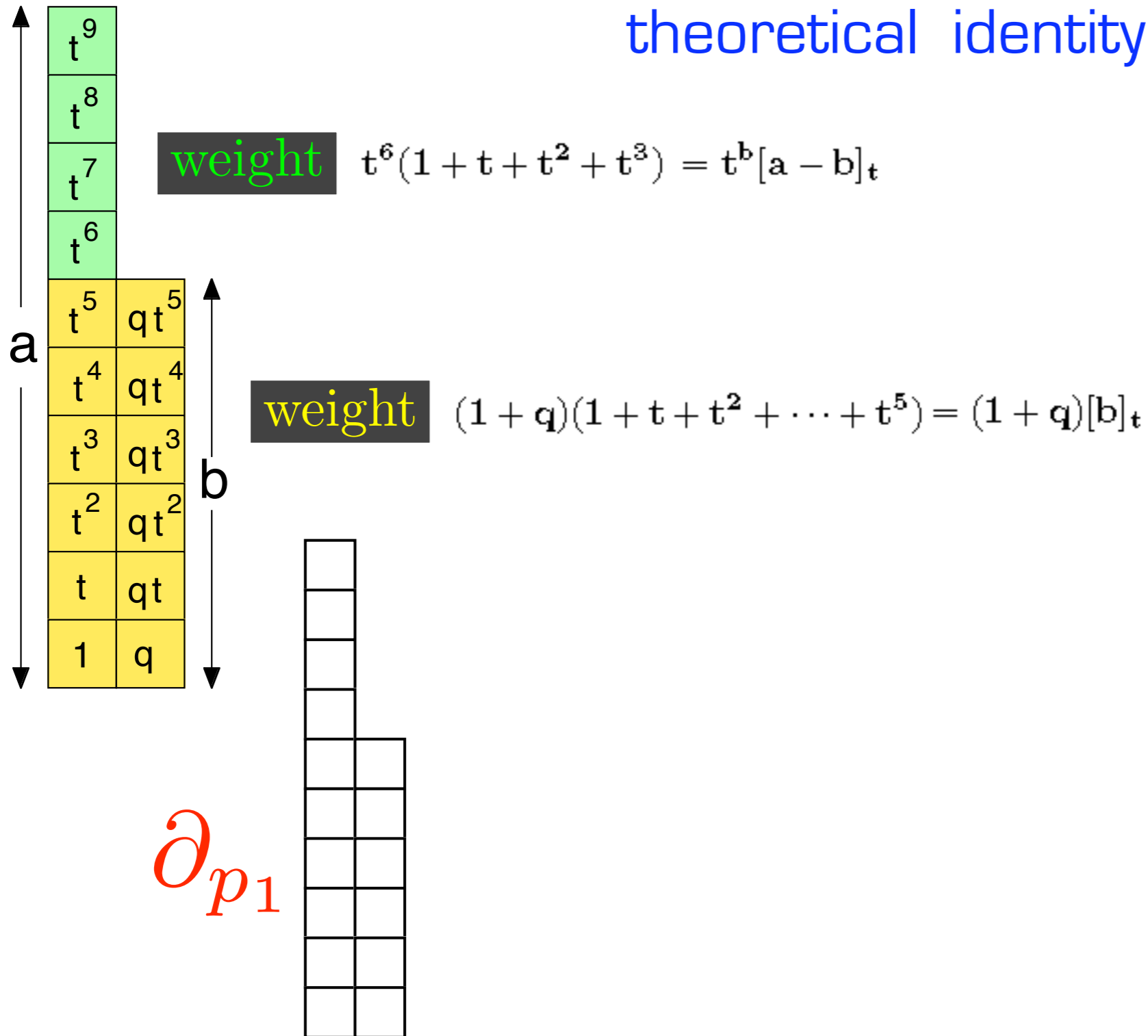
The underlying representation theoretical identity



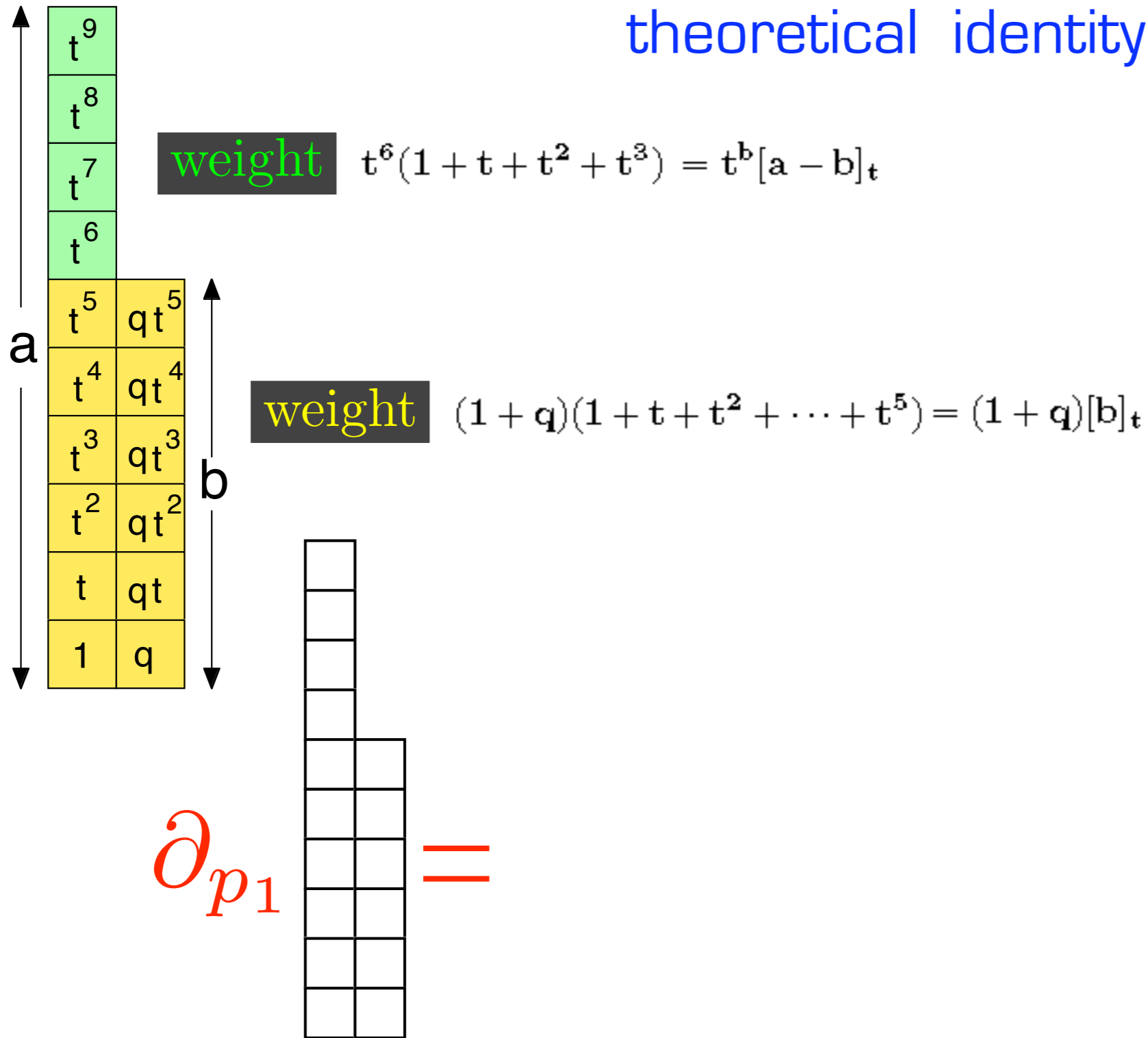
weight $t^6(1 + t + t^2 + t^3) = t^b[a - b]_t$

weight $(1 + q)(1 + t + t^2 + \dots + t^5) = (1 + q)[b]_t$

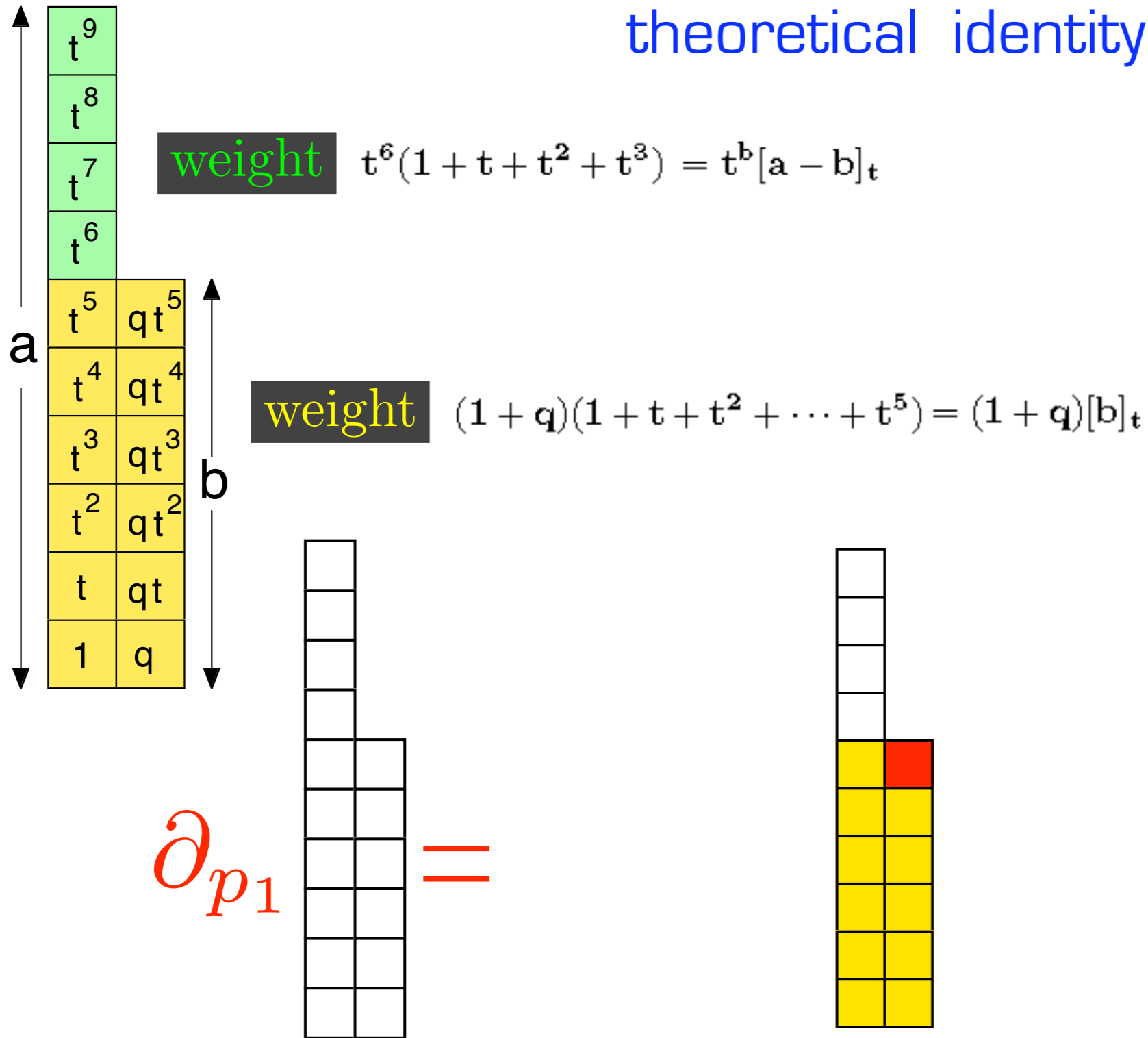
The underlying representation theoretical identity



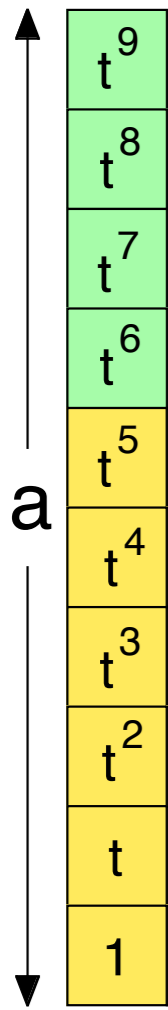
The underlying representation theoretical identity



The underlying representation theoretical identity



The underlying representation theoretical identity



weight

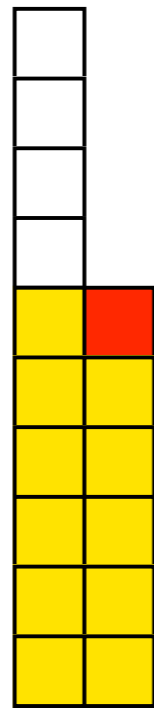
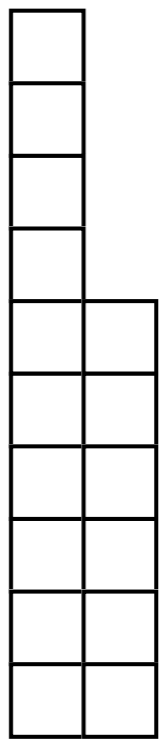
$$t^6(1 + t + t^2 + t^3) = t^b[a - b]_t$$

weight

$$(1 + q)(1 + t + t^2 + \dots + t^5) = (1 + q)[b]_t$$

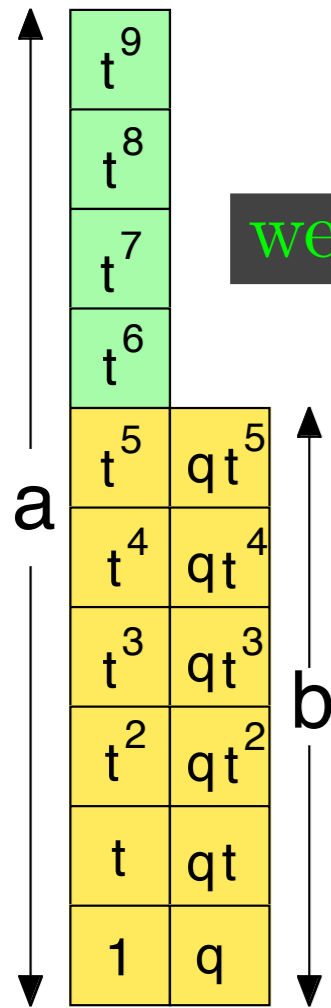
∂_{p_1}

$= (1 + q) [b]_t$



$+$

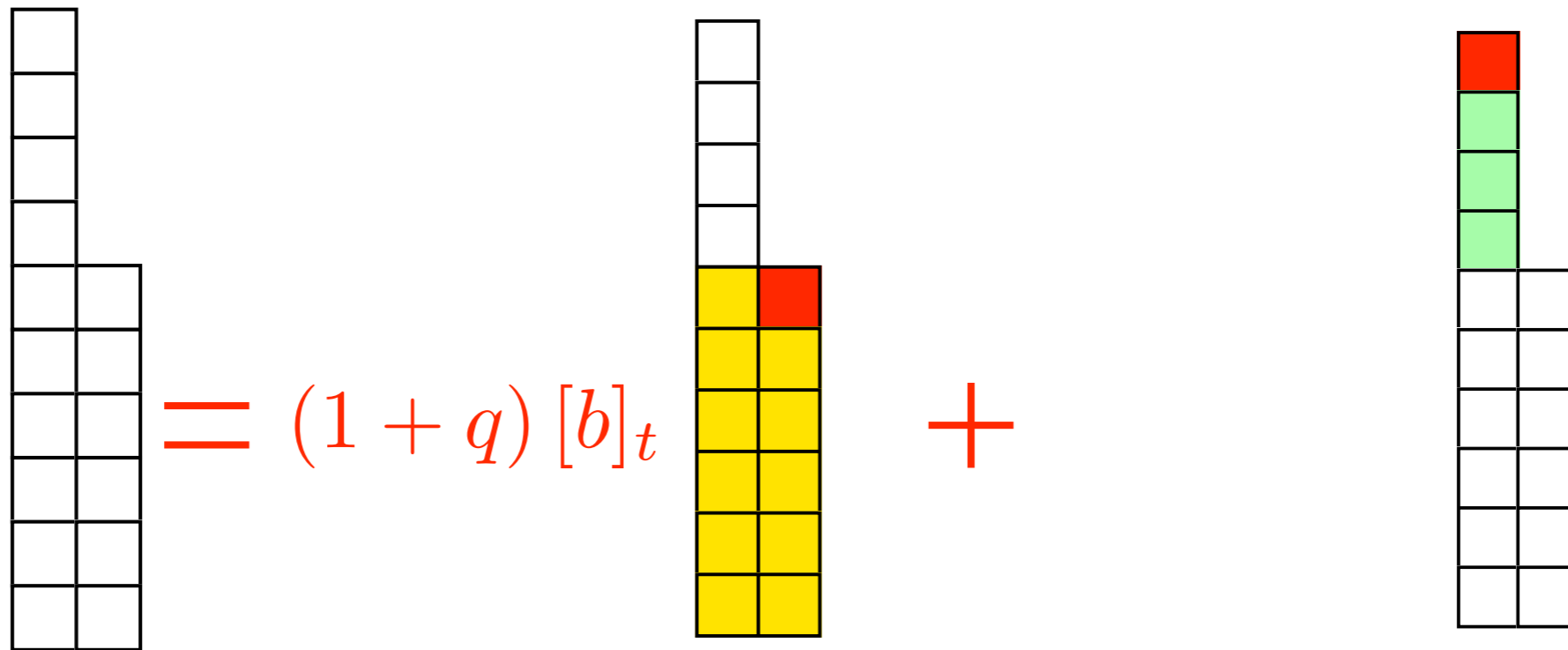
The underlying representation theoretical identity



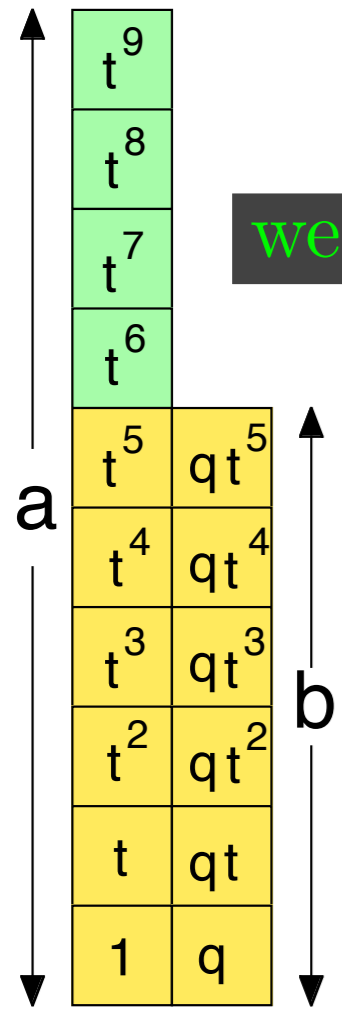
weight $t^6(1 + t + t^2 + t^3) = t^b[a - b]_t$

weight $(1 + q)(1 + t + t^2 + \dots + t^5) = (1 + q)[b]_t$

∂_{p_1} $= (1 + q)[b]_t$



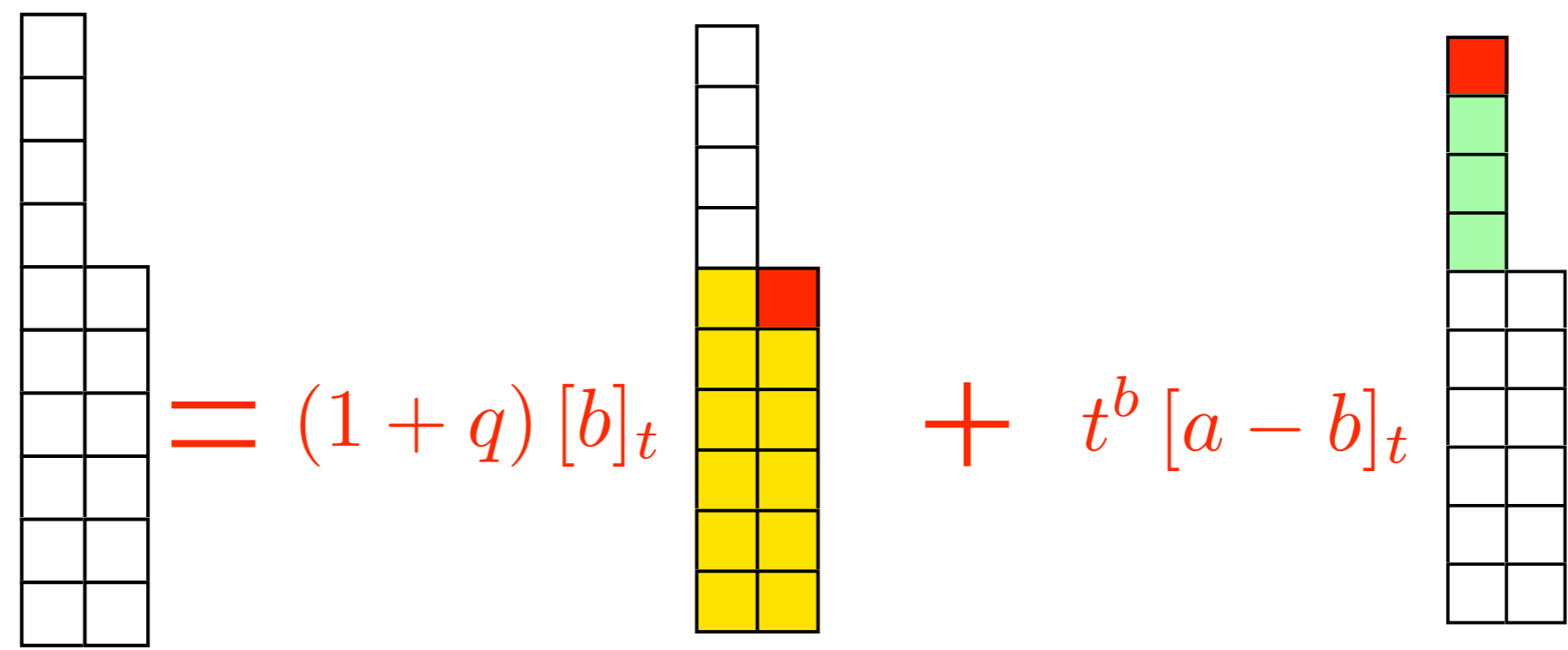
The underlying representation theoretical identity



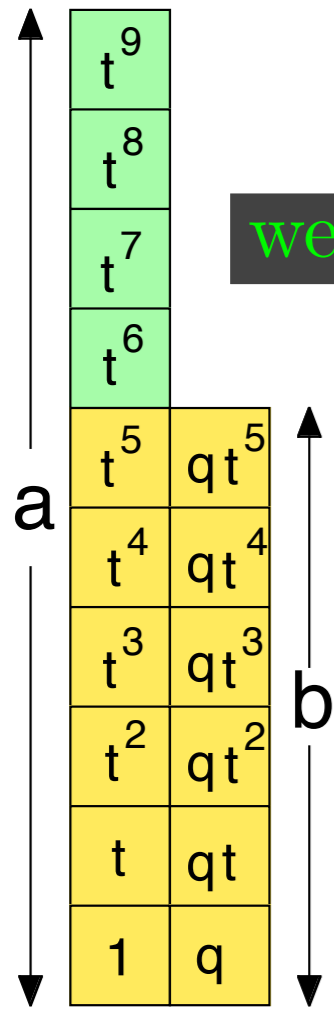
weight $t^6(1 + t + t^2 + t^3) = t^b[a - b]_t$

weight $(1 + q)(1 + t + t^2 + \dots + t^5) = (1 + q)[b]_t$

$\partial_{p_1} = (1 + q)[b]_t + t^b[a - b]_t$



The underlying representation theoretical identity



weight $t^6(1 + t + t^2 + t^3) = t^b[a - b]_t$

weight $(1 + q)(1 + t + t^2 + \dots + t^5) = (1 + q)[b]_t$

$$\partial_{p_1} = (1 + q)[b]_t + t^b[a - b]_t (q/t, t)$$

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q)[b]_t \phi_{a,b-1}(x; q, t) + t^b[a - b]_t \phi_{a-1,b}(x; q/t, t)$$

next

Rationale

Rationale

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q) [b]_t \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \phi_{a-1,b}(x; q/t, t)$$

Rationale

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q) [b]_t \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \phi_{a-1,b}(x; q/t, t)$$

Differentiate both sides by $\partial_{p_1}^{n-1}$

Rationale

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q) [b]_t \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \phi_{a-1,b}(x; q/t, t)$$

Differentiate both sides by $\partial_{p_1}^{n-1}$

$$\partial_{p_1}^n \phi_{ab}(x; q, t) = (1 + q) [b]_t \partial_{p_1}^{n-1} \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \partial_{p_1}^{n-1} \phi_{a-1,b}(x; q/t, t)$$

Rationale

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q) [b]_t \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \phi_{a-1,b}(x; q/t, t)$$

Differentiate both sides by $\partial_{p_1}^{n-1}$

$$\partial_{p_1}^n \phi_{a,b}(x; q, t) = (1 + q) [b]_t \partial_{p_1}^{n-1} \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \partial_{p_1}^{n-1} \phi_{a-1,b}(x; q/t, t)$$

$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

Rationale

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q) [b]_t \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \phi_{a-1,b}(x; q/t, t)$$

Differentiate both sides by $\partial_{p_1}^{n-1}$

$$\partial_{p_1}^n \phi_{a,b}(x; q, t) = (1 + q) [b]_t \partial_{p_1}^{n-1} \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \partial_{p_1}^{n-1} \phi_{a-1,b}(x; q/t, t)$$

$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

Rationale

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q) [b]_t \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \phi_{a-1,b}(x; q/t, t)$$

Differentiate both sides by $\partial_{p_1}^{n-1}$

$$\partial_{p_1}^n \phi_{a,b}(x; q, t) = (1 + q) [b]_t \partial_{p_1}^{n-1} \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \partial_{p_1}^{n-1} \phi_{a-1,b}(x; q/t, t)$$

$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

Rationale

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q) [b]_t \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \phi_{a-1,b}(x; q/t, t)$$

Differentiate both sides by $\partial_{p_1}^{n-1}$

$$\partial_{p_1}^n \phi_{a,b}(x; q, t) = (1 + q) [b]_t \partial_{p_1}^{n-1} \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \partial_{p_1}^{n-1} \phi_{a-1,b}(x; q/t, t)$$

$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

Rationale

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q) [b]_t \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \phi_{a-1,b}(x; q/t, t)$$

Differentiate both sides by $\partial_{p_1}^{n-1}$

$$\partial_{p_1}^n \phi_{a,b}(x; q, t) = (1 + q) [b]_t \partial_{p_1}^{n-1} \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \partial_{p_1}^{n-1} \phi_{a-1,b}(x; q/t, t)$$

$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

Some times it is easier to prove more
than
to prove less

Rationale

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q) [b]_t \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \phi_{a-1,b}(x; q/t, t)$$

Differentiate both sides by $\partial_{p_1}^{n-1}$

$$\partial_{p_1}^n \phi_{a,b}(x; q, t) = (1 + q) [b]_t \partial_{p_1}^{n-1} \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \partial_{p_1}^{n-1} \phi_{a-1,b}(x; q/t, t)$$

$$F_{a,b}(q, t) = (1 + q) [b]_t F_{a,b-1}(q, t) + t^b [a - b]_t F_{a-1,b}(q/t, t)$$

Some times it is easier to prove more
than
to prove less

next

The proof of

The proof of

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q) [b]_t \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \phi_{a-1,b}(x; q/t, t)$$

The proof of

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q) [b]_t \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \phi_{a-1,b}(x; q/t, t)$$

Was guided by

The proof of

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q) [b]_t \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \phi_{a-1,b}(x; q/t, t)$$

Was guided by
Heuristics and conjectures

The proof of

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q) [b]_t \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \phi_{a-1,b}(x; q/t, t)$$

Was guided by
Heuristics and conjectures
gathered during 20 years

The proof of

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q) [b]_t \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \phi_{a-1,b}(x; q/t, t)$$

Was guided by
Heuristics and conjectures
gathered during 20 years
of explorations

The proof of

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q) [b]_t \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \phi_{a-1,b}(x; q/t, t)$$

Was guided by
Heuristics and conjectures
gathered during 20 years
of explorations
in the representation theory of

The proof of

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q) [b]_t \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \phi_{a-1,b}(x; q/t, t)$$

Was guided by
Heuristics and conjectures
gathered during 20 years
of explorations
in the representation theory of
the modules

The proof of

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q) [b]_t \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \phi_{a-1,b}(x; q/t, t)$$

Was guided by
Heuristics and conjectures
gathered during 20 years
of explorations
in the representation theory of
the modules
 $\mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}]$

The proof of

$$\partial_{p_1} \phi_{a,b}(x; q, t) = (1 + q) [b]_t \phi_{a,b-1}(x; q, t) + t^b [a - b]_t \phi_{a-1,b}(x; q/t, t)$$

Was guided by
Heuristics and conjectures
gathered during 20 years
of explorations
in the representation theory of
the modules
 $\mathbf{M}_\mu[\mathbf{X}, \mathbf{Y}]$

next

First “Flip”

Definition

First “Flip”

Definition

We say that a vector space V of polynomials is a “cone ” if it is the linear span

First “Flip”

Definition

We say that a vector space V of polynomials is a “cone ” if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

First “Flip”

Definition

We say that a vector space V of polynomials is a “cone ” if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism “ Flip ” defined by

First “Flip”

Definition

We say that a vector space V of polynomials is a “cone ” if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism “Flip ” defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

First “Flip”

Definition

We say that a vector space V of polynomials is a “cone ” if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism “Flip ” defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

First “Flip”

Definition

We say that a vector space V of polynomials is a “cone ” if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism “Flip ” defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

First “Flip”

Definition

We say that a vector space V of polynomials is a “cone ” if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism “ Flip ” defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and}$$

First “Flip”

Definition

We say that a vector space V of polynomials is a “cone ” if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism “Flip ” defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

First “Flip”

Definition

We say that a vector space V of polynomials is a “cone ” if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism “Flip ” defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

First "Flip"

Definition

We say that a vector space V of polynomials is a "cone" if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism "Flip" defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x})$$

First “Flip”

Definition

We say that a vector space V of polynomials is a “cone” if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism “Flip” defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

First “Flip”

Definition

We say that a vector space V of polynomials is a “cone” if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism “Flip” defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

First “Flip”

Definition

We say that a vector space V of polynomials is a “cone” if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism “Flip” defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

First "Flip"

Definition

We say that a vector space V of polynomials is a "cone" if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism "Flip" defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

First “Flip”

Definition

We say that a vector space V of polynomials is a “cone” if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism “Flip” defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

$$\text{flip } P(\mathbf{x}) = 0$$

First "Flip"

Definition

We say that a vector space V of polynomials is a "cone" if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism "Flip" defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

$$\text{flip } P(\mathbf{x}) = 0 \implies P(\partial_{\mathbf{x}})P(\mathbf{x}) = 0$$

First “Flip”

Definition

We say that a vector space V of polynomials is a “cone” if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism “Flip” defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

$$\text{flip } P(\mathbf{x}) = 0 \implies P(\partial_{\mathbf{x}})P(\mathbf{x}) = 0 \implies P(\mathbf{x}) = 0$$

First "Flip"

Definition

We say that a vector space V of polynomials is a "cone" if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism "Flip" defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

$$\text{flip } P(\mathbf{x}) = 0 \implies P(\partial_{\mathbf{x}})P(\mathbf{x}) = 0 \implies P(\mathbf{x}) = 0$$

Note that this implies that if $\text{degree } \Delta(\mathbf{x}) = n_0$ then

First "Flip"

Definition

We say that a vector space V of polynomials is a "cone" if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism "Flip" defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

$$\text{flip } P(\mathbf{x}) = 0 \implies P(\partial_{\mathbf{x}})P(\mathbf{x}) = 0 \implies P(\mathbf{x}) = 0$$

Note that this implies that if $\text{degree } \Delta(\mathbf{x}) = n_0$ then

$$F_V(t) = t^{n_0} F_V(1/t)$$

First "Flip"

Definition

We say that a vector space V of polynomials is a "cone" if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism "Flip" defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

$$\text{flip } P(\mathbf{x}) = 0 \implies P(\partial_{\mathbf{x}})P(\mathbf{x}) = 0 \implies P(\mathbf{x}) = 0$$

Note that this implies that if $\text{degree } \Delta(\mathbf{x}) = n_0$ then

$$F_V(t) = t^{n_0} F_V(1/t)$$

The same is true if V is a cone with summit a bihomogeneous polynomial $\Delta(\mathbf{x}, \mathbf{y})$

First "Flip"

Definition

We say that a vector space V of polynomials is a "cone" if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism "Flip" defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

$$\text{flip } P(\mathbf{x}) = 0 \implies P(\partial_{\mathbf{x}})P(\mathbf{x}) = 0 \implies P(\mathbf{x}) = 0$$

Note that this implies that if $\text{degree } \Delta(\mathbf{x}) = n_0$ then

$$F_V(t) = t^{n_0} F_V(1/t)$$

The same is true if V is a cone with summit a bihomogeneous polynomial $\Delta(\mathbf{x}, \mathbf{y})$ of bi-degree n_x, n_y

First "Flip"

Definition

We say that a vector space V of polynomials is a "cone" if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism "Flip" defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

$$\text{flip } P(\mathbf{x}) = 0 \implies P(\partial_{\mathbf{x}})P(\mathbf{x}) = 0 \implies P(\mathbf{x}) = 0$$

Note that this implies that if $\text{degree } \Delta(\mathbf{x}) = n_0$ then

$$F_V(t) = t^{n_0} F_V(1/t)$$

The same is true if V is a cone with summit a bihomogeneous polynomial $\Delta(\mathbf{x}, \mathbf{y})$ of bi-degree n_x, n_y . In this case

First "Flip"

Definition

We say that a vector space V of polynomials is a "cone" if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism "Flip" defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

$$\text{flip } P(\mathbf{x}) = 0 \implies P(\partial_{\mathbf{x}})P(\mathbf{x}) = 0 \implies P(\mathbf{x}) = 0$$

Note that this implies that if $\text{degree } \Delta(\mathbf{x}) = n_0$ then

$$F_V(t) = t^{n_0} F_V(1/t)$$

The same is true if V is a cone with summit a bihomogeneous polynomial $\Delta(\mathbf{x}, \mathbf{y})$ of bi-degree n_x, n_y . In this case

$$F_V(\mathbf{q}, t) = t^{n_x} \mathbf{q}^{n_y} F_V(1/\mathbf{q}, 1/t)$$

First "Flip"

Definition

We say that a vector space V of polynomials is a "cone" if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism "Flip" defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

$$\text{flip } P(\mathbf{x}) = 0 \implies P(\partial_{\mathbf{x}})P(\mathbf{x}) = 0 \implies P(\mathbf{x}) = 0$$

Note that this implies that if $\text{degree } \Delta(\mathbf{x}) = n_0$ then

$$F_V(t) = t^{n_0} F_V(1/t)$$

The same is true if V is a cone with summit a bihomogeneous polynomial $\Delta(\mathbf{x}, \mathbf{y})$ of bi-degree n_x, n_y . In this case

$$F_V(\mathbf{q}, t) = t^{n_x} \mathbf{q}^{n_y} F_V(1/\mathbf{q}, 1/t)$$

This explains the symmetry

First "Flip"

Definition

We say that a vector space V of polynomials is a "cone" if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism "Flip" defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

$$\text{flip } P(\mathbf{x}) = 0 \implies P(\partial_{\mathbf{x}})P(\mathbf{x}) = 0 \implies P(\mathbf{x}) = 0$$

Note that this implies that if $\text{degree } \Delta(\mathbf{x}) = n_0$ then

$$F_V(t) = t^{n_0} F_V(1/t)$$

The same is true if V is a cone with summit a bihomogeneous polynomial $\Delta(\mathbf{x}, \mathbf{y})$ of bi-degree n_x, n_y . In this case

$$F_V(\mathbf{q}, t) = t^{n_x} \mathbf{q}^{n_y} F_V(1/\mathbf{q}, 1/t)$$

This explains the symmetry

$$F_{32}(\mathbf{q}, t) = \begin{bmatrix} 5 & 11 & 9 & 4 & 1 \\ 4 & 15 & 22 & 15 & 4 \\ 1 & 4 & 9 & 11 & 5 \end{bmatrix}$$

First "Flip"

Definition

We say that a vector space V of polynomials is a "cone" if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism "Flip" defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

$$\text{flip } P(\mathbf{x}) = 0 \implies P(\partial_{\mathbf{x}})P(\mathbf{x}) = 0 \implies P(\mathbf{x}) = 0$$

Note that this implies that if $\text{degree } \Delta(\mathbf{x}) = n_0$ then

$$F_V(t) = t^{n_0} F_V(1/t)$$

The same is true if V is a cone with summit a bihomogeneous polynomial $\Delta(\mathbf{x}, \mathbf{y})$ of bi-degree n_x, n_y . In this case

$$F_V(\mathbf{q}, t) = t^{n_x} \mathbf{q}^{n_y} F_V(1/\mathbf{q}, 1/t)$$

This explains the symmetry

$$F_{32}(\mathbf{q}, t) = \begin{bmatrix} 5 & 11 & 9 & 4 & 1 \\ 4 & 15 & 22 & 15 & 4 \\ 1 & 4 & 9 & 11 & 5 \end{bmatrix}$$

First "Flip"

Definition

We say that a vector space V of polynomials is a "cone" if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism "Flip" defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

$$\text{flip } P(\mathbf{x}) = 0 \implies P(\partial_{\mathbf{x}})P(\mathbf{x}) = 0 \implies P(\mathbf{x}) = 0$$

Note that this implies that if $\text{degree } \Delta(\mathbf{x}) = n_0$ then

$$F_V(t) = t^{n_0} F_V(1/t)$$

The same is true if V is a cone with summit a bihomogeneous polynomial $\Delta(\mathbf{x}, \mathbf{y})$ of bi-degree n_x, n_y . In this case

$$F_V(\mathbf{q}, t) = t^{n_x} \mathbf{q}^{n_y} F_V(1/\mathbf{q}, 1/t)$$

This explains the symmetry

$$F_{32}(\mathbf{q}, t) = \begin{bmatrix} 5 & 11 & 9 & 4 & 1 \\ 4 & 15 & 22 & 15 & 4 \\ 1 & 4 & 9 & 11 & 5 \end{bmatrix}$$

First "Flip"

Definition

We say that a vector space V of polynomials is a "cone" if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism "Flip" defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

$$\text{flip } P(\mathbf{x}) = 0 \implies P(\partial_{\mathbf{x}})P(\mathbf{x}) = 0 \implies P(\mathbf{x}) = 0$$

Note that this implies that if $\text{degree } \Delta(\mathbf{x}) = n_0$ then

$$F_V(t) = t^{n_0} F_V(1/t)$$

The same is true if V is a cone with summit a bihomogeneous polynomial $\Delta(\mathbf{x}, \mathbf{y})$ of bi-degree n_x, n_y . In this case

$$F_V(\mathbf{q}, t) = t^{n_x} \mathbf{q}^{n_y} F_V(1/\mathbf{q}, 1/t)$$

This explains the symmetry

$$F_{32}(\mathbf{q}, t) = \begin{bmatrix} 5 & 11 & 9 & 4 & 1 \\ 4 & 15 & 22 & 15 & 4 \\ 1 & 4 & 9 & 11 & 5 \end{bmatrix}$$

First "Flip"

Definition

We say that a vector space V of polynomials is a "cone" if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism "Flip" defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

$$\text{flip } P(\mathbf{x}) = 0 \implies P(\partial_{\mathbf{x}})P(\mathbf{x}) = 0 \implies P(\mathbf{x}) = 0$$

Note that this implies that if $\text{degree } \Delta(\mathbf{x}) = n_0$ then

$$F_V(t) = t^{n_0} F_V(1/t)$$

The same is true if V is a cone with summit a bihomogeneous polynomial $\Delta(\mathbf{x}, \mathbf{y})$ of bi-degree n_x, n_y . In this case

$$F_V(\mathbf{q}, t) = t^{n_x} \mathbf{q}^{n_y} F_V(1/\mathbf{q}, 1/t)$$

This explains the symmetry

$$F_{32}(\mathbf{q}, t) = \begin{bmatrix} 5 & 11 & 9 & 4 & 1 \\ 4 & 15 & 22 & 15 & 4 \\ 1 & 4 & 9 & 11 & 5 \end{bmatrix}$$

First "Flip"

Definition

We say that a vector space V of polynomials is a "cone" if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism "Flip" defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

$$\text{flip } P(\mathbf{x}) = 0 \implies P(\partial_{\mathbf{x}})P(\mathbf{x}) = 0 \implies P(\mathbf{x}) = 0$$

Note that this implies that if $\text{degree } \Delta(\mathbf{x}) = n_0$ then

$$F_V(t) = t^{n_0} F_V(1/t)$$

The same is true if V is a cone with summit a bihomogeneous polynomial $\Delta(\mathbf{x}, \mathbf{y})$ of bi-degree n_x, n_y . In this case

$$F_V(\mathbf{q}, t) = t^{n_x} \mathbf{q}^{n_y} F_V(1/\mathbf{q}, 1/t)$$

This explains the symmetry

$$F_{32}(\mathbf{q}, t) = \begin{bmatrix} 5 & 11 & 9 & 4 & 1 \\ 4 & 15 & 22 & 15 & 4 \\ 1 & 4 & 9 & 11 & 5 \end{bmatrix}$$

First "Flip"

Definition

We say that a vector space V of polynomials is a "cone" if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism "Flip" defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

$$\text{flip } P(\mathbf{x}) = 0 \implies P(\partial_{\mathbf{x}})P(\mathbf{x}) = 0 \implies P(\mathbf{x}) = 0$$

Note that this implies that if $\text{degree } \Delta(\mathbf{x}) = n_0$ then

$$F_V(t) = t^{n_0} F_V(1/t)$$

The same is true if V is a cone with summit a bihomogeneous polynomial $\Delta(\mathbf{x}, \mathbf{y})$ of bi-degree n_x, n_y . In this case

$$F_V(\mathbf{q}, t) = t^{n_x} \mathbf{q}^{n_y} F_V(1/\mathbf{q}, 1/t)$$

This explains the symmetry

$$F_{32}(\mathbf{q}, t) = \begin{bmatrix} 5 & 11 & 9 & 4 & 1 \\ 4 & 15 & 22 & 15 & 4 \\ 1 & 4 & 9 & 11 & 5 \end{bmatrix}$$

First "Flip"

Definition

We say that a vector space V of polynomials is a "cone" if it is the linear span of derivatives of a single homogeneous polynomial $\Delta(\mathbf{x})$.

In this case V has an automorphism "Flip" defined by

$$\text{flip } P(\mathbf{x}) = P(\partial_{\mathbf{x}})\Delta(\mathbf{x})$$

Note this is a non-singular linear map of V onto V since if

$$P(\mathbf{x}) = Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) \quad \text{and} \quad P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

then

$$P(\partial_{\mathbf{x}})P(\mathbf{x}) = P(\partial_{\mathbf{x}})Q(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = Q(\partial_{\mathbf{x}})P(\partial_{\mathbf{x}})\Delta(\mathbf{x}) = 0$$

Thus

$$\text{flip } P(\mathbf{x}) = 0 \implies P(\partial_{\mathbf{x}})P(\mathbf{x}) = 0 \implies P(\mathbf{x}) = 0$$

Note that this implies that if $\text{degree } \Delta(\mathbf{x}) = n_0$ then

$$F_V(t) = t^{n_0} F_V(1/t)$$

The same is true if V is a cone with summit a bihomogeneous polynomial $\Delta(\mathbf{x}, \mathbf{y})$ of bi-degree n_x, n_y . In this case

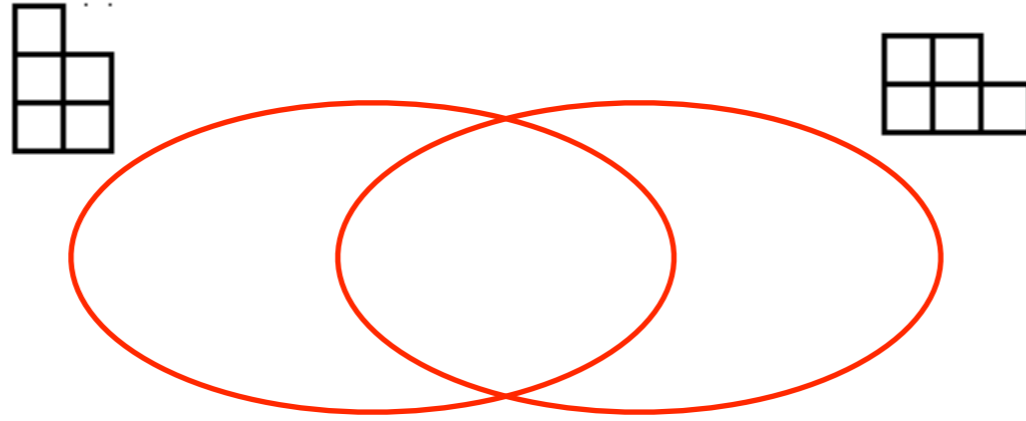
$$F_V(\mathbf{q}, t) = t^{n_x} \mathbf{q}^{n_y} F_V(1/\mathbf{q}, 1/t)$$

This explains the symmetry

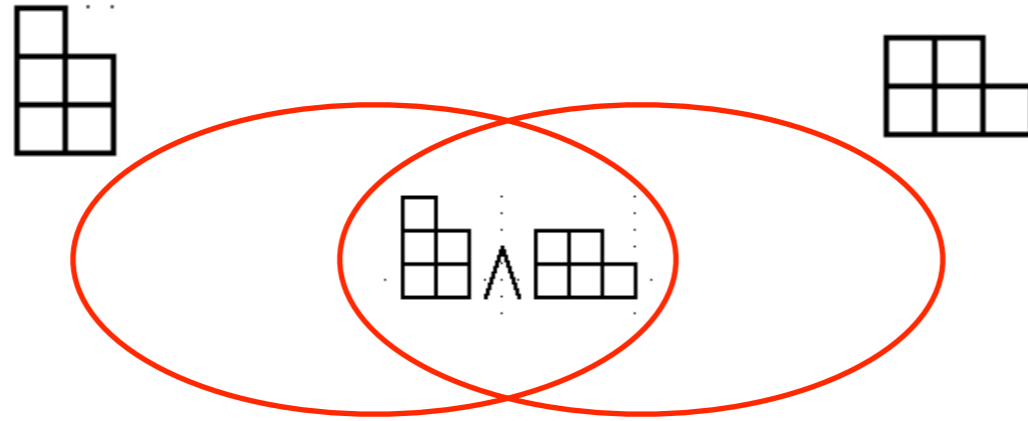
$$F_{32}(\mathbf{q}, t) = \begin{bmatrix} 5 & 11 & 9 & 4 & 1 \\ 4 & 15 & 22 & 15 & 4 \\ 1 & 4 & 9 & 11 & 5 \end{bmatrix}$$

next the miracles

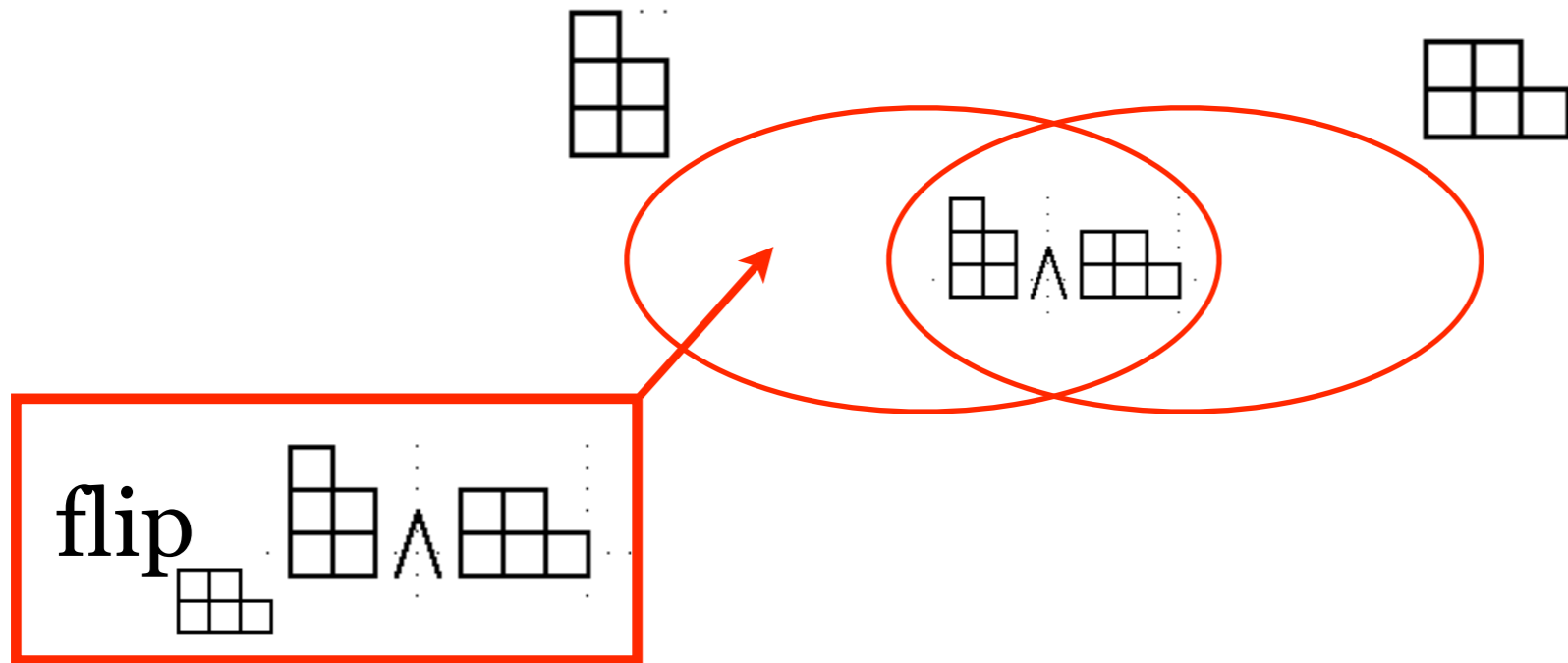
next the miracles



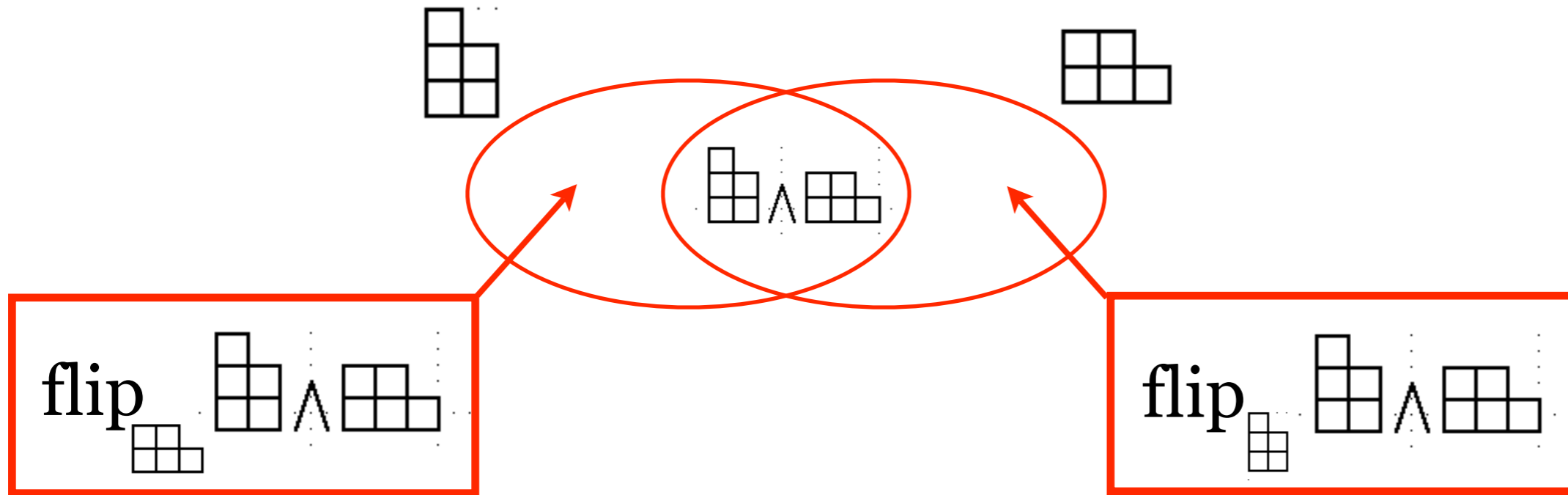
next the miracles



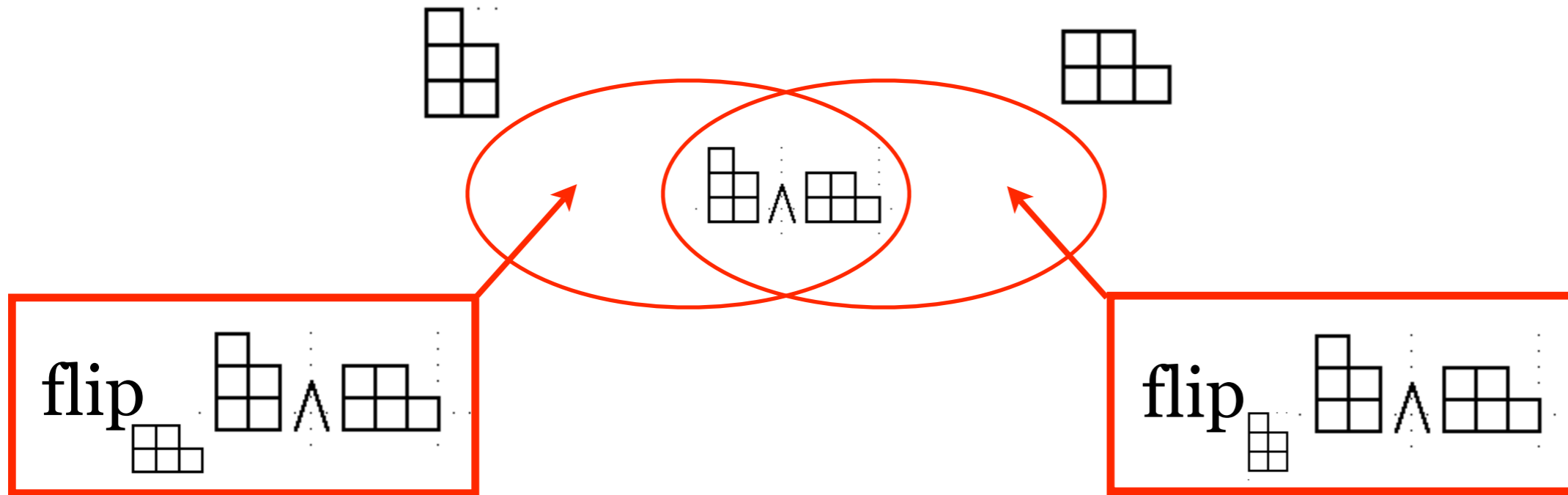
next the miracles



next the miracles

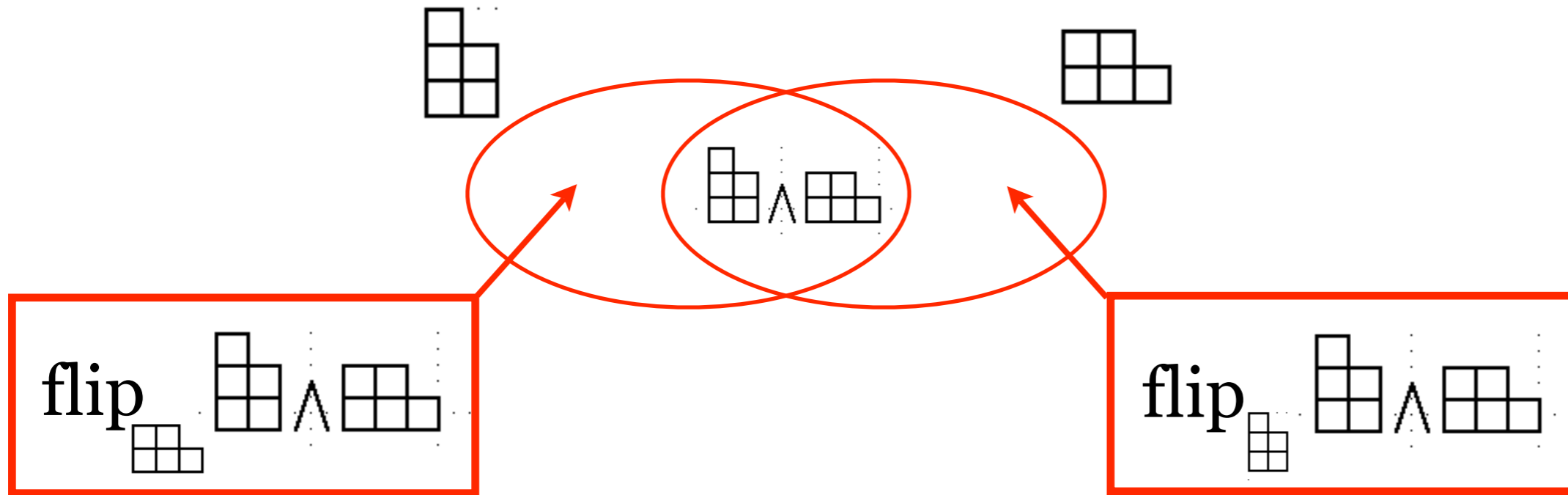


next the miracles



$$M_{221} = M_{32} \wedge M_{221} \oplus \text{flip}_{221} M_{32} \wedge M_{221}$$

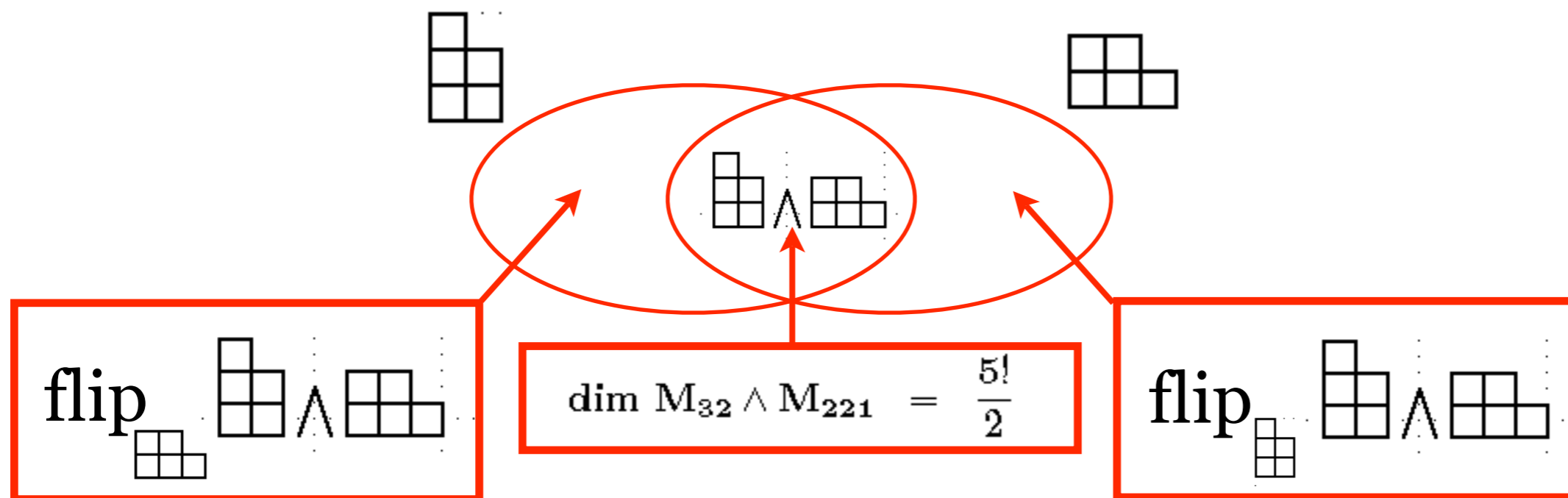
next the miracles



$$M_{221} = M_{32} \wedge M_{221} \oplus \text{flip}_{221} M_{32} \wedge M_{221}$$

$$M_{32} = M_{221} \wedge M_{32} \oplus \text{flip}_{32} M_{221} \wedge M_{32}$$

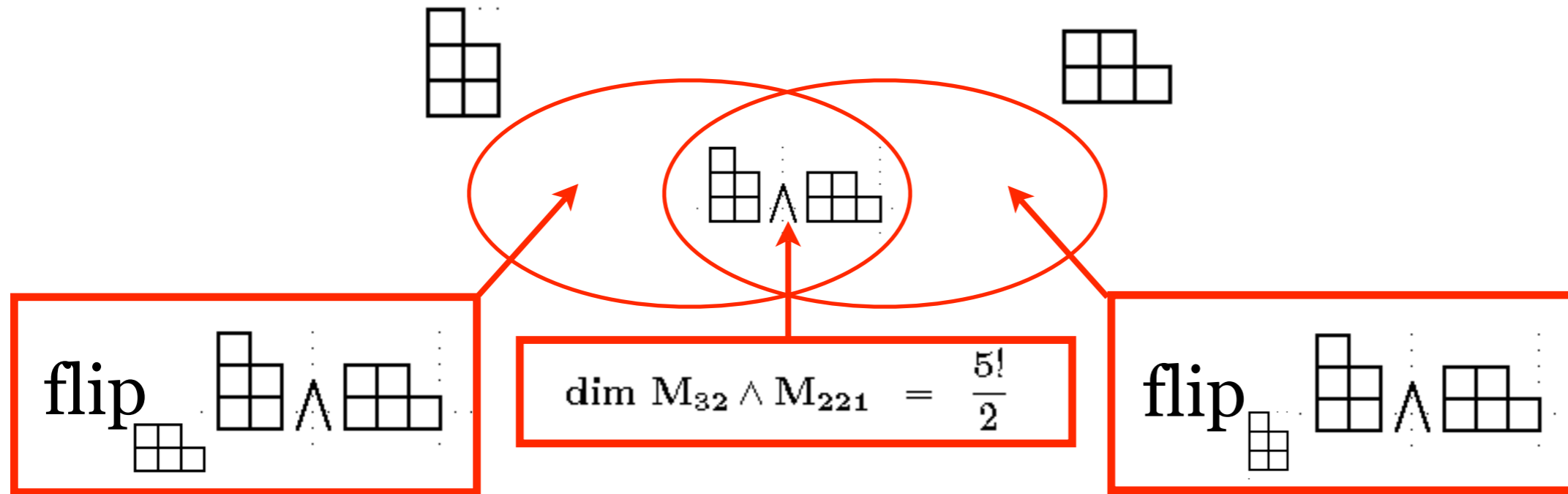
next the miracles



$$M_{221} = M_{32} \wedge M_{221} \oplus \text{flip}_{221} M_{32} \wedge M_{221}$$

$$M_{32} = M_{221} \wedge M_{32} \oplus \text{flip}_{32} M_{221} \wedge M_{32}$$

next the miracles

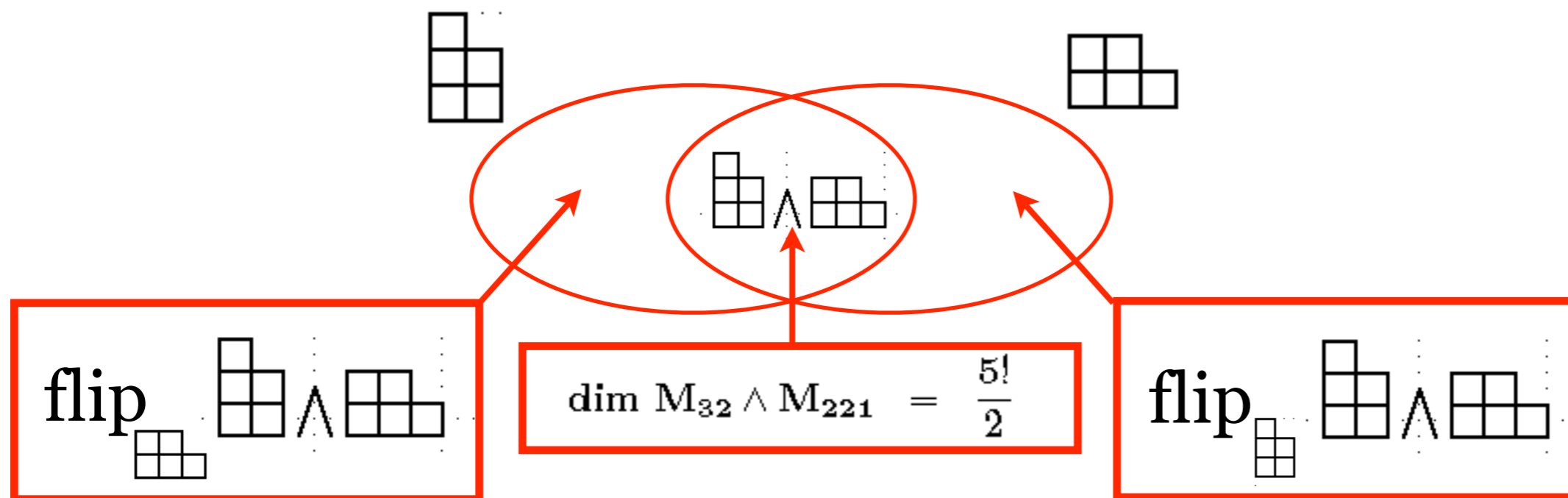


$$M_{221} = M_{32} \wedge M_{221} \oplus \text{flip}_{221} M_{32} \wedge M_{221}$$

$$M_{32} = M_{221} \wedge M_{32} \oplus \text{flip}_{32} M_{221} \wedge M_{32}$$

$\frac{n!}{2}$ Conjecture

next the miracles



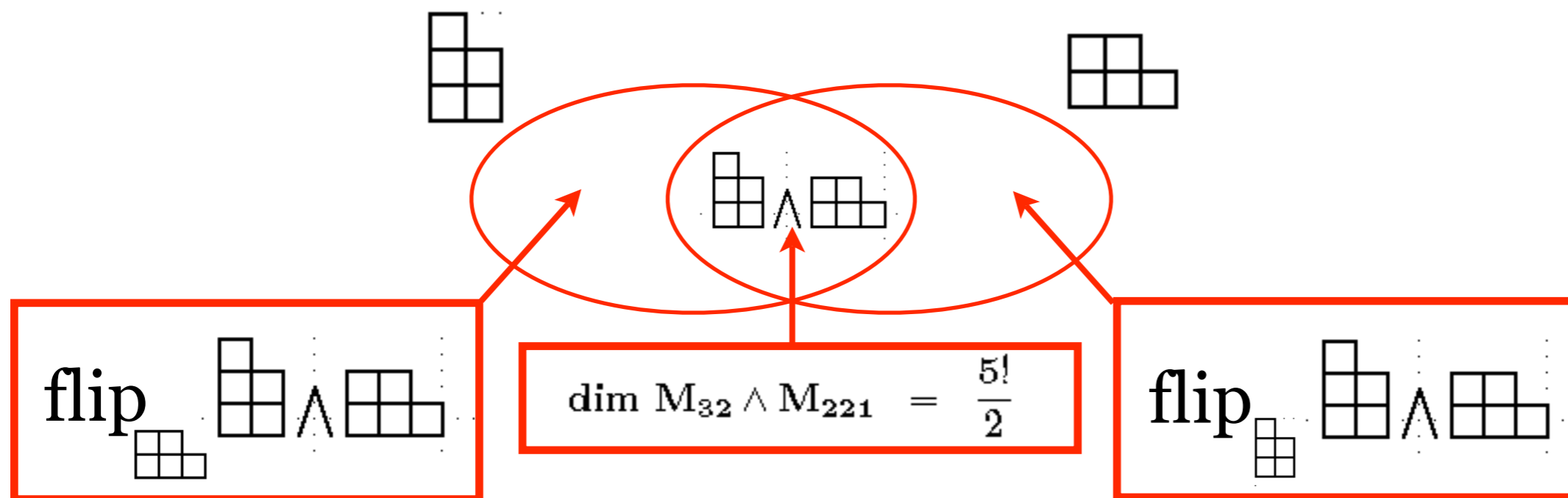
$$M_{221} = M_{32} \wedge M_{221} \oplus \text{flip}_{221} M_{32} \wedge M_{221}$$

$$M_{32} = M_{221} \wedge M_{32} \oplus \text{flip}_{32} M_{221} \wedge M_{32}$$

$\frac{n!}{2}$ Conjecture

If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then

next the miracles



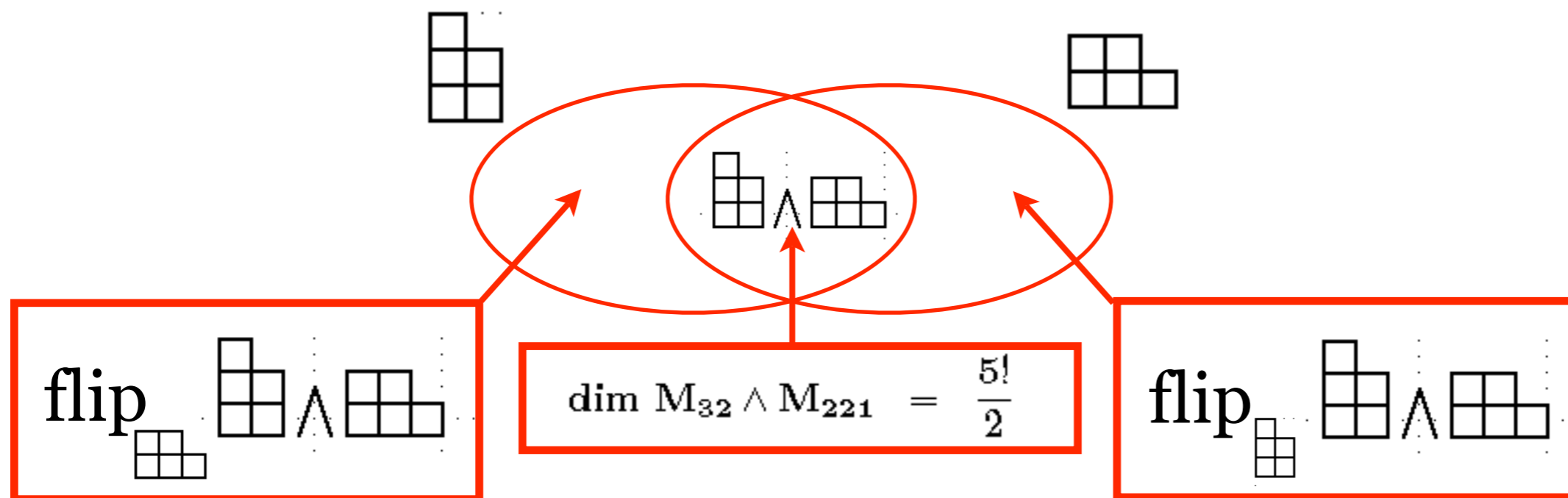
$$M_{221} = M_{32} \wedge M_{221} \oplus \text{flip}_{221} M_{32} \wedge M_{221}$$

$$M_{32} = M_{221} \wedge M_{32} \oplus \text{flip}_{32} M_{221} \wedge M_{32}$$

$\frac{n!}{2}$ Conjecture

If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then $\dim M_\alpha \wedge M_\beta = \frac{n!}{2}$

next the miracles



$$M_{221} = M_{32} \wedge M_{221} \oplus \text{flip}_{221} M_{32} \wedge M_{221}$$

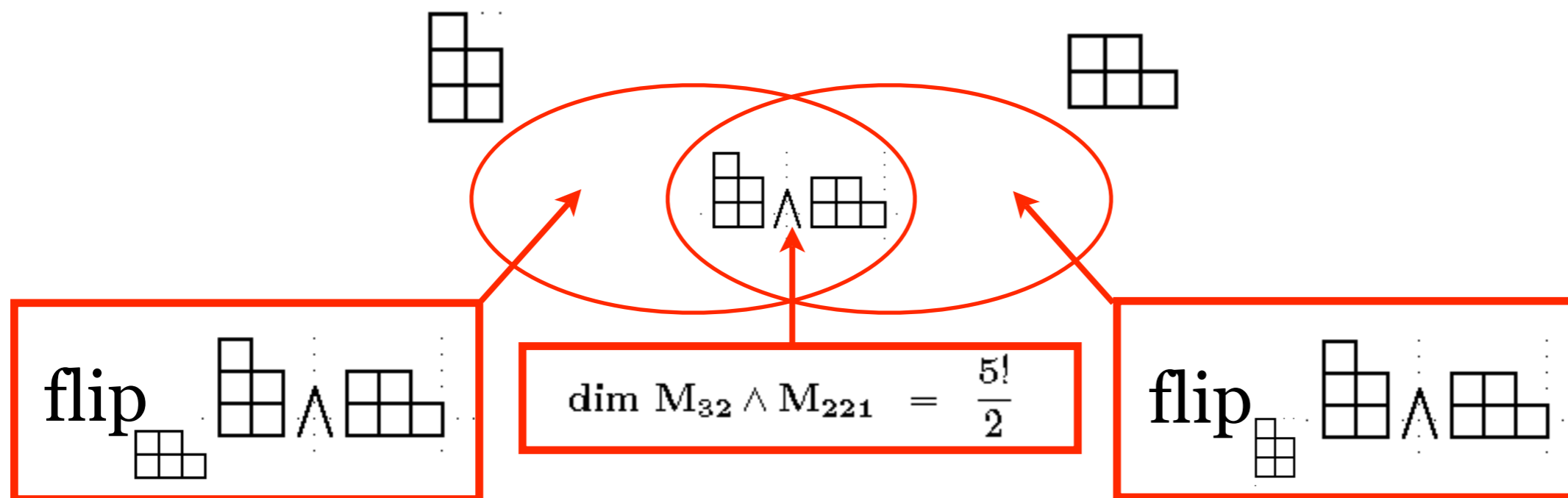
$$M_{32} = M_{221} \wedge M_{32} \oplus \text{flip}_{32} M_{221} \wedge M_{32}$$

$\frac{n!}{2}$ Conjecture

If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then $\dim M_\alpha \wedge M_\beta = \frac{n!}{2}$

SF Conjecture

next the miracles



$$M_{221} = M_{32} \wedge M_{221} \oplus \text{flip}_{221} M_{32} \wedge M_{221}$$

$$M_{32} = M_{221} \wedge M_{32} \oplus \text{flip}_{32} M_{221} \wedge M_{32}$$

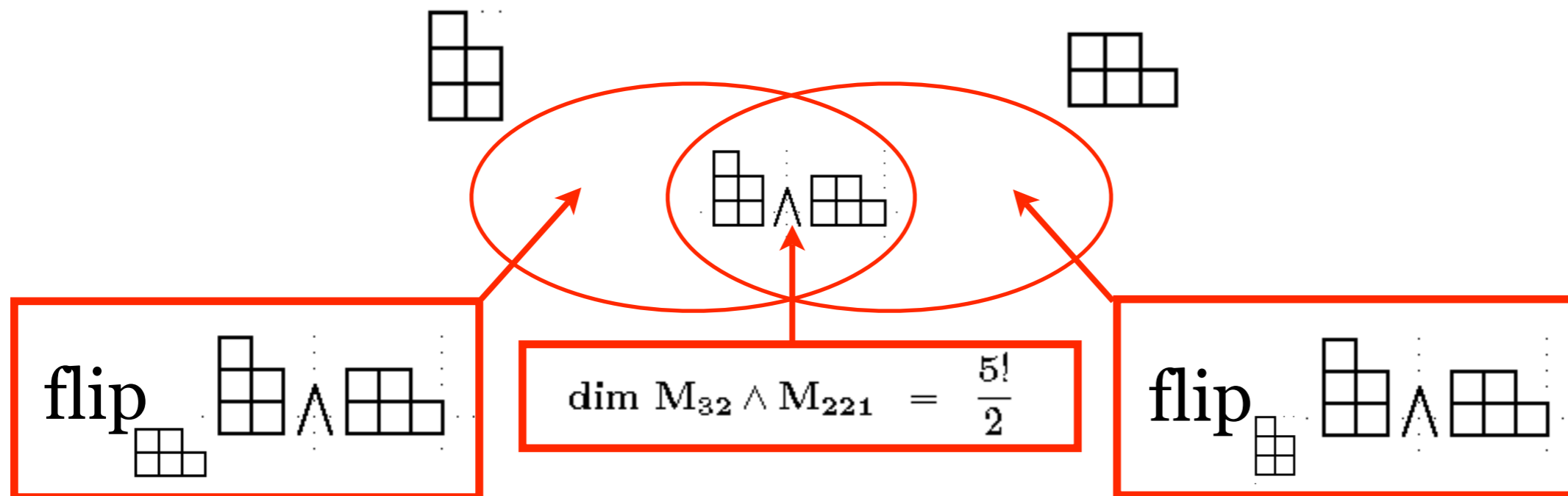
$\frac{n!}{2}$ Conjecture

If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then $\dim M_\alpha \wedge M_\beta = \frac{n!}{2}$

SF Conjecture

If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then

next the miracles



$$M_{221} = M_{32} \wedge M_{221} \oplus \text{flip}_{221} M_{32} \wedge M_{221}$$

$$M_{32} = M_{221} \wedge M_{32} \oplus \text{flip}_{32} M_{221} \wedge M_{32}$$

$\frac{n!}{2}$ Conjecture

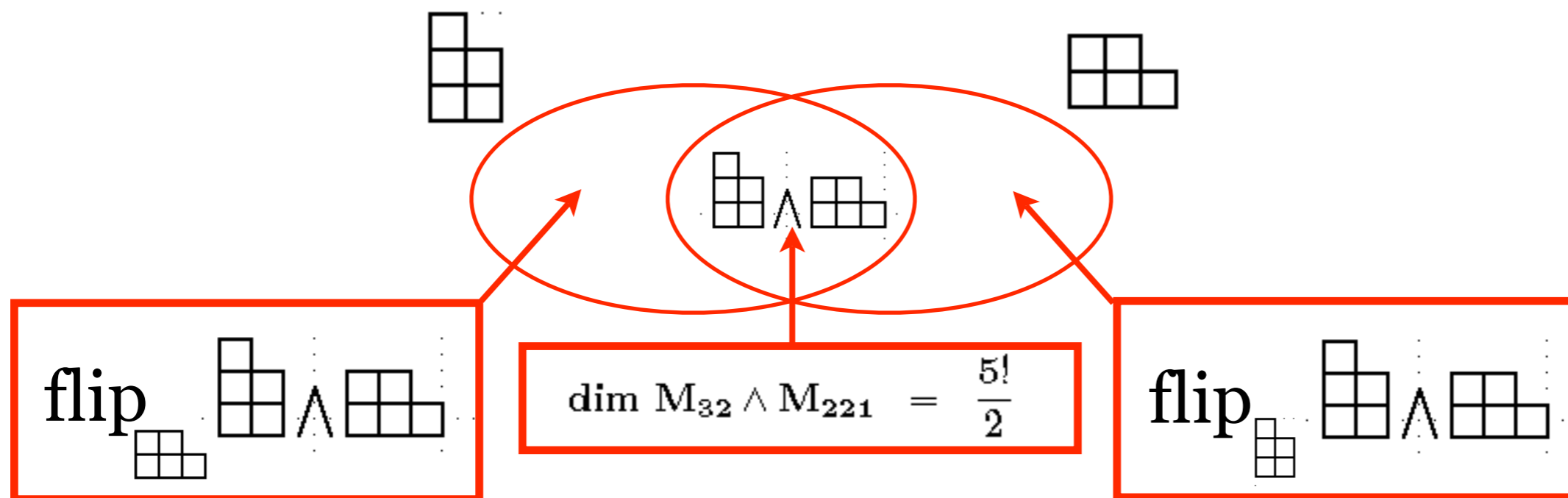
If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then $\dim M_\alpha \wedge M_\beta = \frac{n!}{2}$

SF Conjecture

If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then

$$M_\alpha = M_\alpha \wedge M_\beta \oplus \text{flip}_\alpha M_\alpha \wedge M_\beta ,$$

next the miracles



$$M_{221} = M_{32} \wedge M_{221} \oplus \text{flip}_{221} M_{32} \wedge M_{221}$$

$$M_{32} = M_{221} \wedge M_{32} \oplus \text{flip}_{32} M_{221} \wedge M_{32}$$

$\frac{n!}{2}$ Conjecture

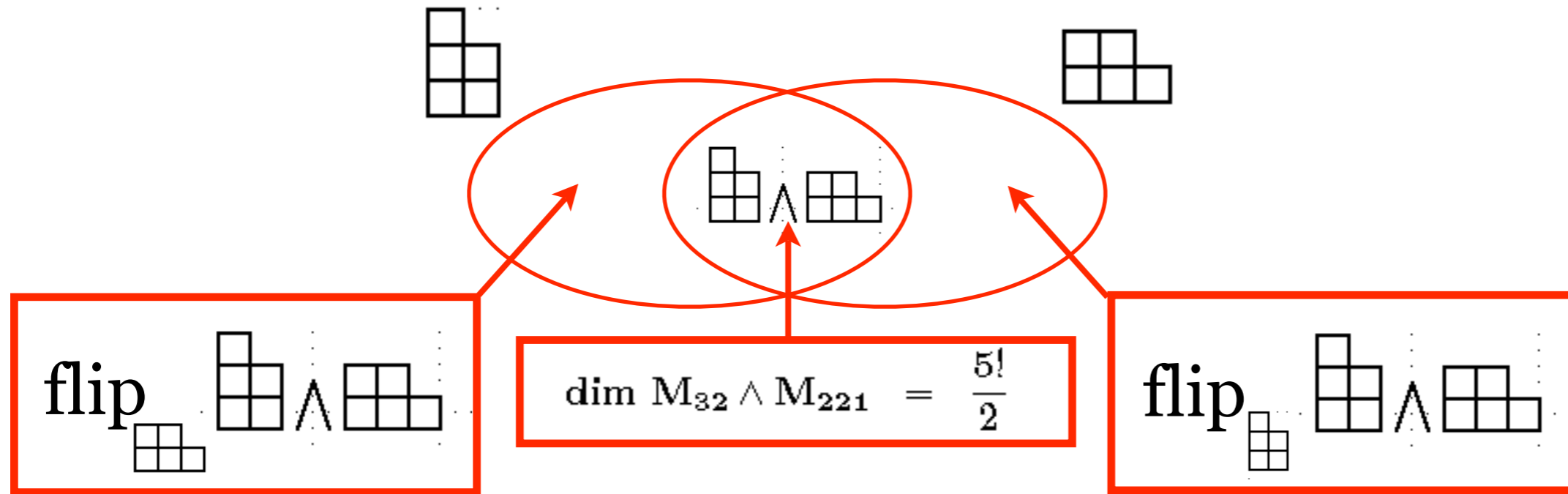
If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then $\dim M_\alpha \wedge M_\beta = \frac{n!}{2}$

SF Conjecture

If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then

$$M_\alpha = M_\alpha \wedge M_\beta \oplus \text{flip}_\alpha M_\alpha \wedge M_\beta, \quad M_\beta = M_\alpha \wedge M_\beta \oplus \text{flip}_\beta M_\alpha \wedge M_\beta$$

next the miracles



$$M_{221} = M_{32} \wedge M_{221} \oplus \text{flip}_{221} M_{32} \wedge M_{221}$$

$$M_{32} = M_{221} \wedge M_{32} \oplus \text{flip}_{32} M_{221} \wedge M_{32}$$

$\frac{n!}{2}$ Conjecture

If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then $\dim M_\alpha \wedge M_\beta = \frac{n!}{2}$

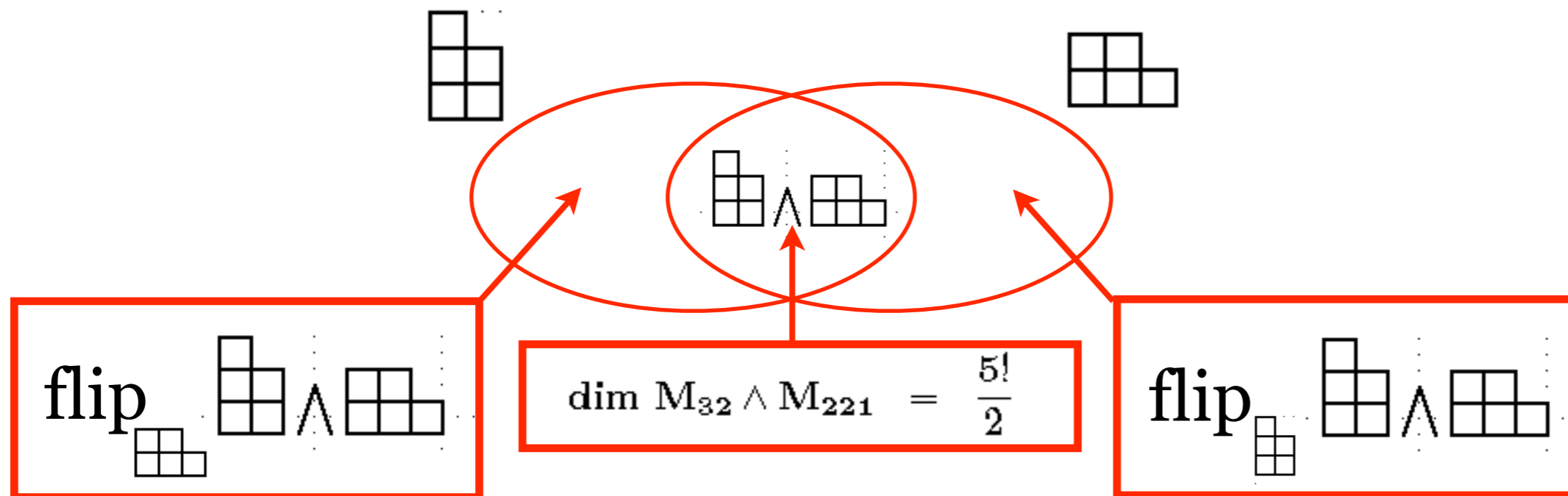
SF Conjecture

If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then

$$M_\alpha = M_\alpha \wedge M_\beta \oplus \text{flip}_\alpha M_\alpha \wedge M_\beta, \quad M_\beta = M_\alpha \wedge M_\beta \oplus \text{flip}_\beta M_\alpha \wedge M_\beta$$

This implies

next the miracles



$$M_{221} = M_{32} \wedge M_{221} \oplus \text{flip}_{221} M_{32} \wedge M_{221}$$

$$M_{32} = M_{221} \wedge M_{32} \oplus \text{flip}_{32} M_{221} \wedge M_{32}$$

$\frac{n!}{2}$ Conjecture

If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then $\dim M_\alpha \wedge M_\beta = \frac{n!}{2}$

SF Conjecture

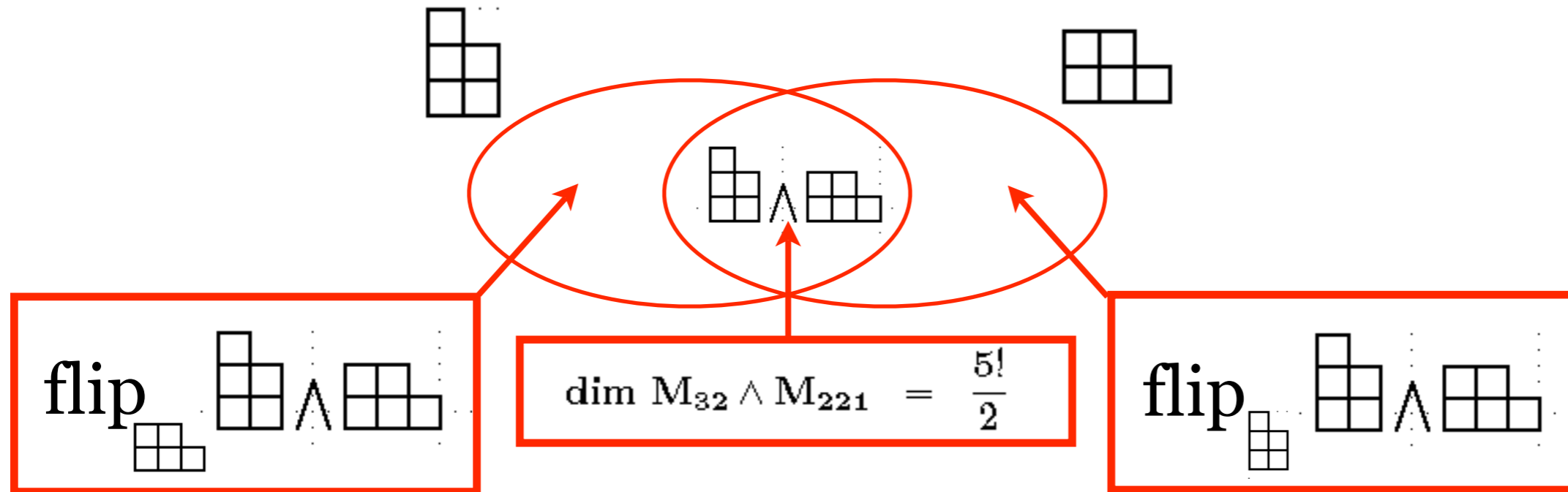
If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then

$$M_\alpha = M_\alpha \wedge M_\beta \oplus \text{flip}_\alpha M_\alpha \wedge M_\beta, \quad M_\beta = M_\alpha \wedge M_\beta \oplus \text{flip}_\beta M_\alpha \wedge M_\beta$$

This implies

$$F_{M_\alpha \wedge M_\beta}(\mathbf{q}, t) = \frac{T_\beta F_{M_\alpha}(\mathbf{q}, t) - T_\alpha F_{M_\beta}(\mathbf{q}, t)}{T_\alpha - T_\beta}$$

next the miracles



$$M_{221} = M_{32} \wedge M_{221} \oplus \text{flip}_{221} M_{32} \wedge M_{221}$$

$$M_{32} = M_{221} \wedge M_{32} \oplus \text{flip}_{32} M_{221} \wedge M_{32}$$

$\frac{n!}{2}$ Conjecture

If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then $\dim M_\alpha \wedge M_\beta = \frac{n!}{2}$

SF Conjecture

If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then

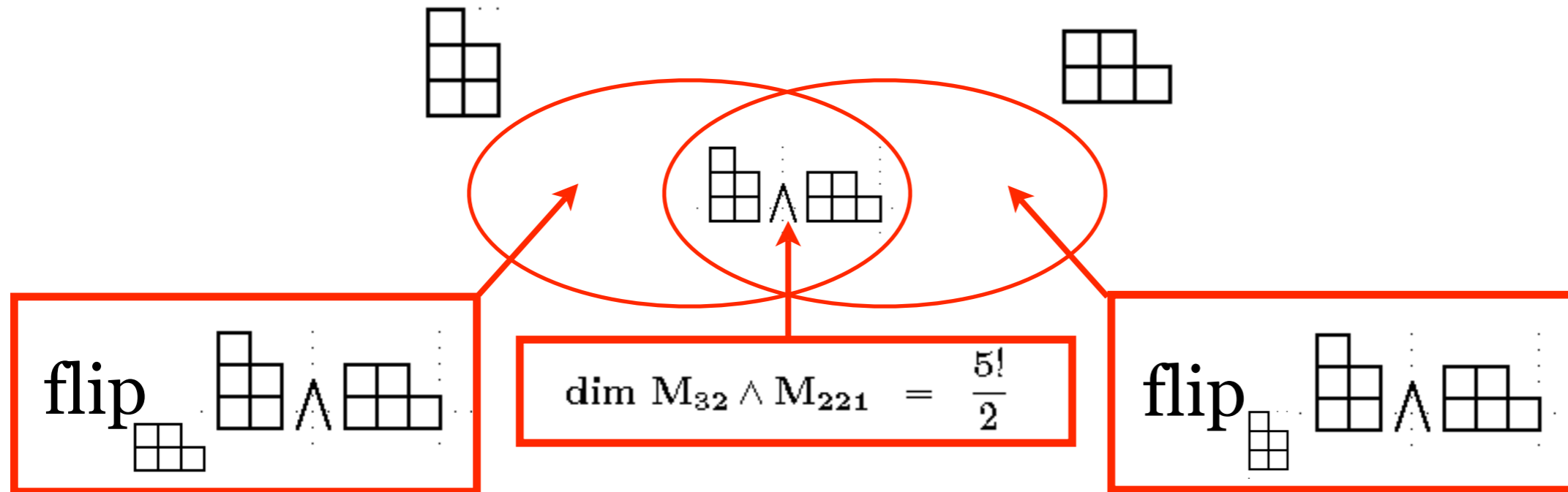
$$M_\alpha = M_\alpha \wedge M_\beta \oplus \text{flip}_\alpha M_\alpha \wedge M_\beta, \quad M_\beta = M_\alpha \wedge M_\beta \oplus \text{flip}_\beta M_\alpha \wedge M_\beta$$

This implies

$$F_{M_\alpha \wedge M_\beta}(q, t) = \frac{T_\beta F_{M_\alpha}(q, t) - T_\alpha F_{M_\beta}(q, t)}{T_\alpha - T_\beta}$$

with $T_\mu = t^{n(\mu)} q^{n(\mu')}$ and $n(\mu) = \sum_i (i-1)\mu_i$

next the miracles



$$M_{221} = M_{32} \wedge M_{221} \oplus \text{flip}_{221} M_{32} \wedge M_{221}$$

$$M_{32} = M_{221} \wedge M_{32} \oplus \text{flip}_{32} M_{221} \wedge M_{32}$$

$\frac{n!}{2}$ Conjecture (still open!)

If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then $\dim M_\alpha \wedge M_\beta = \frac{n!}{2}$

SF Conjecture

If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then

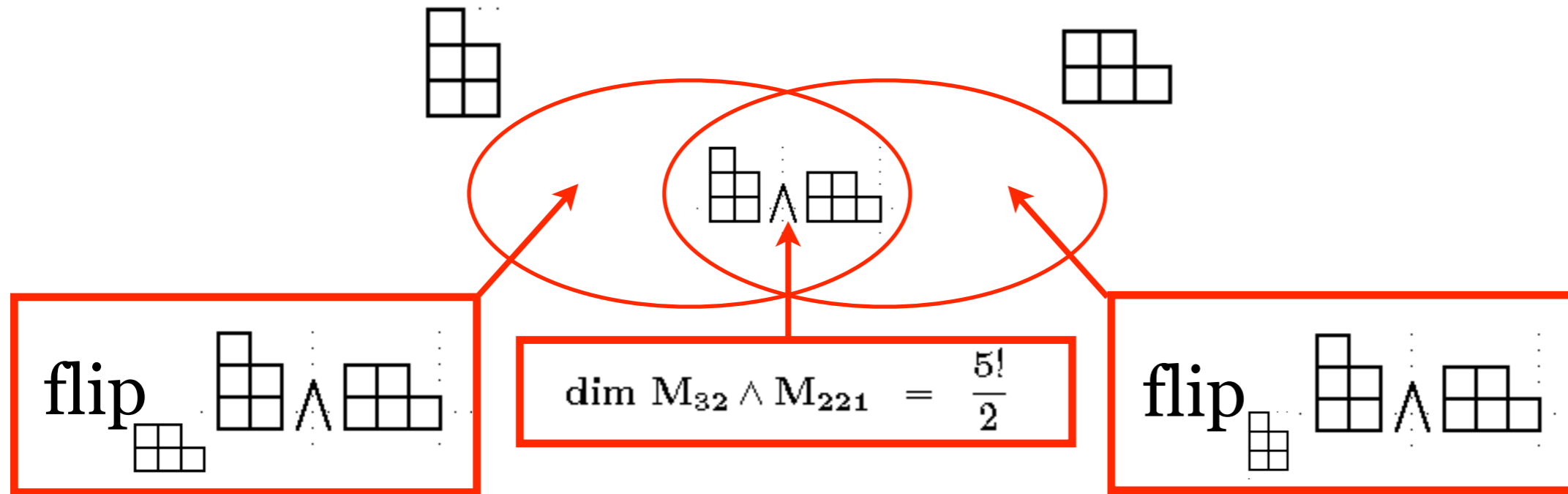
$$M_\alpha = M_\alpha \wedge M_\beta \oplus \text{flip}_\alpha M_\alpha \wedge M_\beta, \quad M_\beta = M_\alpha \wedge M_\beta \oplus \text{flip}_\beta M_\alpha \wedge M_\beta$$

This implies

$$F_{M_\alpha \wedge M_\beta}(q, t) = \frac{T_\beta F_{M_\alpha}(q, t) - T_\alpha F_{M_\beta}(q, t)}{T_\alpha - T_\beta}$$

with $T_\mu = t^{n(\mu)} q^{n(\mu')}$ and $n(\mu) = \sum_i (i-1)\mu_i$

next the miracles



$$M_{221} = M_{32} \wedge M_{221} \oplus \text{flip}_{221} M_{32} \wedge M_{221}$$

$$M_{32} = M_{221} \wedge M_{32} \oplus \text{flip}_{32} M_{221} \wedge M_{32}$$

$\frac{n!}{2}$ Conjecture (still open!)

If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then $\dim M_\alpha \wedge M_\beta = \frac{n!}{2}$

SF Conjecture (still open!)

If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then

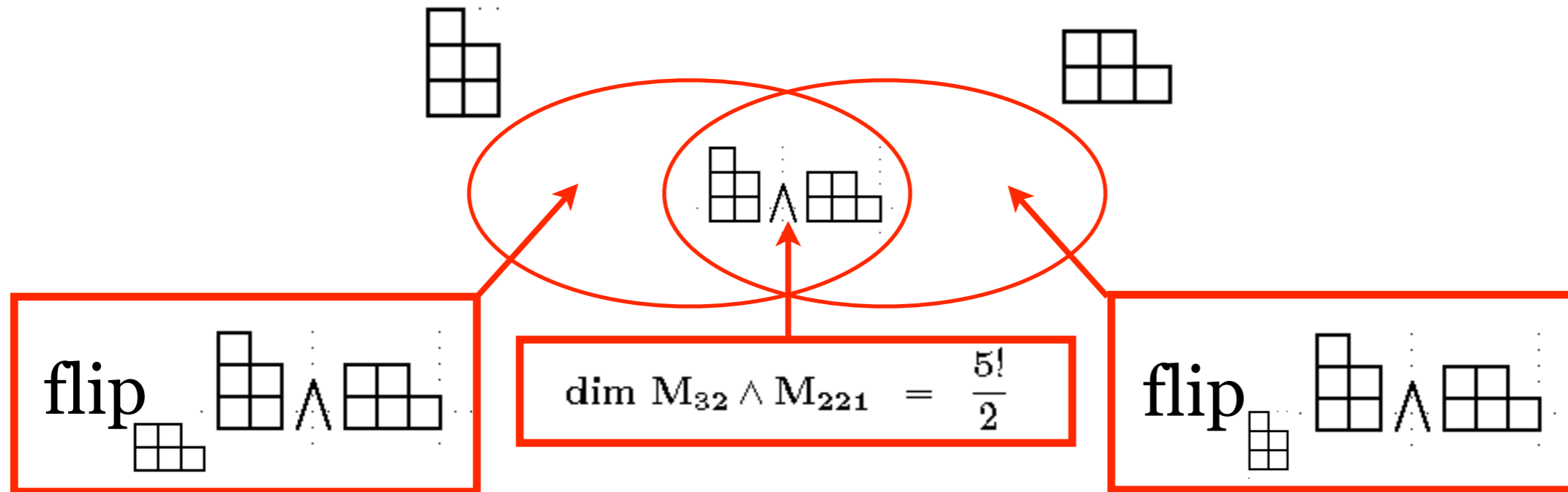
$$M_\alpha = M_\alpha \wedge M_\beta \oplus \text{flip}_\alpha M_\alpha \wedge M_\beta, \quad M_\beta = M_\alpha \wedge M_\beta \oplus \text{flip}_\beta M_\alpha \wedge M_\beta$$

This implies

$$F_{M_\alpha \wedge M_\beta}(q, t) = \frac{T_\beta F_{M_\alpha}(q, t) - T_\alpha F_{M_\beta}(q, t)}{T_\alpha - T_\beta}$$

with $T_\mu = t^{n(\mu)} q^{n(\mu')}$ and $n(\mu) = \sum_i (i-1)\mu_i$

next the miracles



$$M_{221} = M_{32} \wedge M_{221} \oplus \text{flip}_{221} M_{32} \wedge M_{221}$$

$$M_{32} = M_{221} \wedge M_{32} \oplus \text{flip}_{32} M_{221} \wedge M_{32}$$

$\frac{n!}{2}$ Conjecture (still open!)

If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then $\dim M_\alpha \wedge M_\beta = \frac{n!}{2}$

SF Conjecture (still open!)

If $\alpha, \beta \vdash n$ differ only by the position of one corner cell then

$$M_\alpha = M_\alpha \wedge M_\beta \oplus \text{flip}_\alpha M_\alpha \wedge M_\beta, \quad M_\beta = M_\alpha \wedge M_\beta \oplus \text{flip}_\beta M_\alpha \wedge M_\beta$$

This implies

$$F_{M_\alpha \wedge M_\beta}(q, t) = \frac{T_\beta F_{M_\alpha}(q, t) - T_\alpha F_{M_\beta}(q, t)}{T_\alpha - T_\beta}$$

with $T_\mu = t^{n(\mu)} q^{n(\mu')}$ and $n(\mu) = \sum_i (i-1)\mu_i$

next

How would you split in one half

How would you split in one half
a

How would you split in one half
a
Left regular representation ?

How would you split in one half
a
Left regular representation ?

$$e_1^n$$

How would you split in one half
a
Left regular representation ?

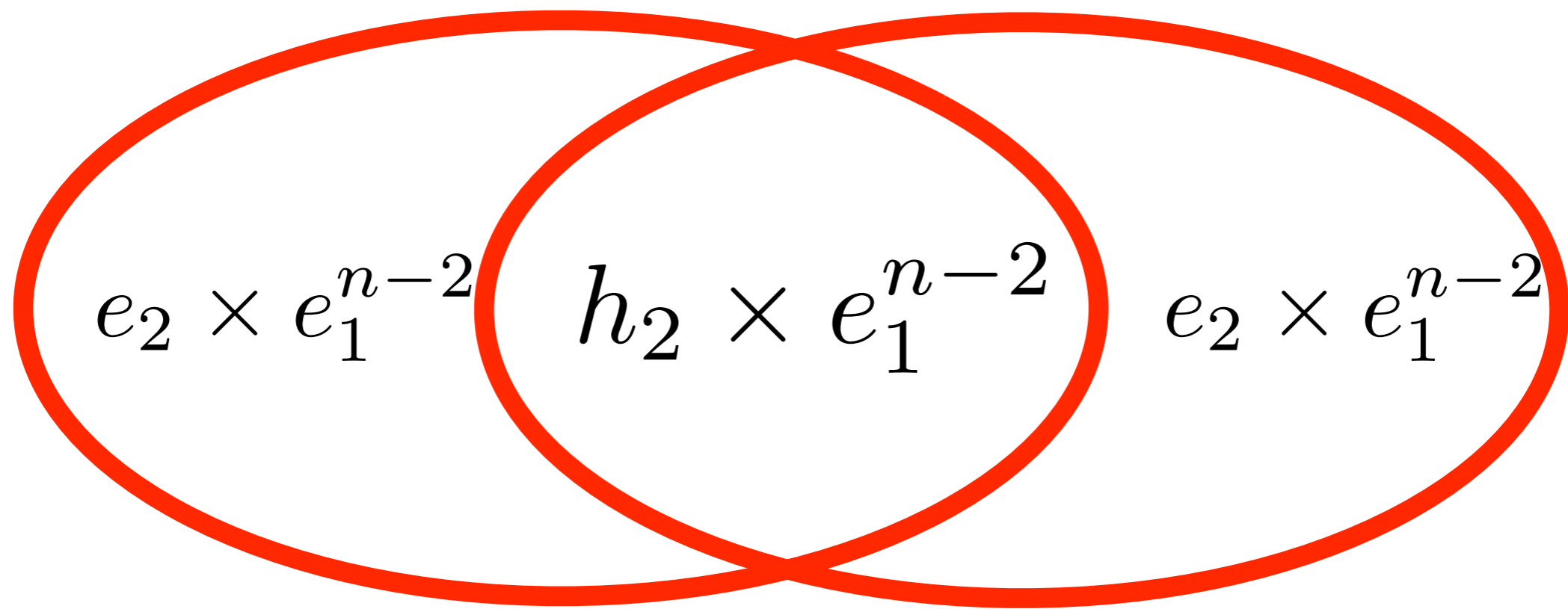
$$e_1^n = e_1^2 \times e_1^{n-2}$$

How would you split in one half
a
Left regular representation ?

$$\begin{aligned} e_1^n &= e_1^2 \times e_1^{n-2} \\ &= (h_2 + e_2) \times e_1^{n-2} \end{aligned}$$

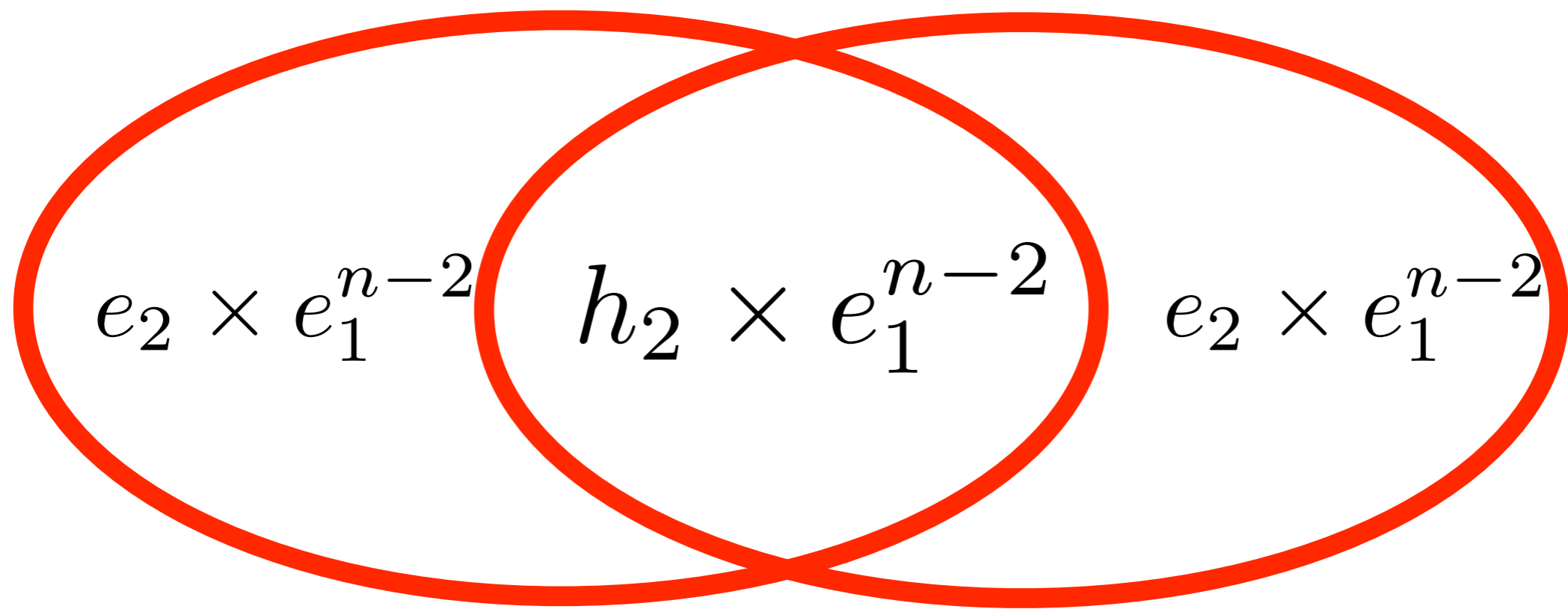
How would you split in one half
a
Left regular representation ?

$$\begin{aligned} e_1^n &= e_1^2 \times e_1^{n-2} \\ &= (h_2 + e_2) \times e_1^{n-2} \end{aligned}$$



How would you split in one half
a
Left regular representation ?

$$\begin{aligned} e_1^n &= e_1^2 \times e_1^{n-2} \\ &= (h_2 + e_2) \times e_1^{n-2} \end{aligned}$$



next

The basic tool : “gistol” Macdonalds

The basic tool : “gistol” Macdonalds

(1) A “gistol” is a lattice diagram that can be transformed to a

The basic tool : “gistol” Macdonalds

(1) A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges

The basic tool : “gistol” Macdonalds

- (1) A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges*
- (2) We postulate the existence of a family of polynomials indexed*

The basic tool : “gistol” Macdonalds

- (1) *A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges*
- (2) *We postulate the existence of a family of polynomials indexed by gistols with the following basic properties:*

The basic tool : “gistol” Macdonalds

(1) A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges

(2) We postulate the existence of a family of polynomials indexed by gistols with the following basic properties:

{

The basic tool : “gistol” Macdonalds

(1) A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges

(2) We postulate the existence of a family of polynomials indexed by gistols with the following basic properties:

$$\left\{ \begin{array}{l} (0) \quad G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \bar{H}_\mu(\mathbf{x}; \mathbf{q}, \mathbf{t}) \\ \vdots \\ \vdots \\ \vdots \\ \vdots \end{array} \right.$$

The basic tool : “gistol” Macdonalds

(1) A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges

(2) We postulate the existence of a family of polynomials indexed by gistols with the following basic properties:

$$\left\{ \begin{array}{l} (0) \quad G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \bar{H}_\mu(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \text{ is the diagram of } \mu \\ \vdots \\ \vdots \\ \vdots \\ \vdots \end{array} \right.$$

The basic tool : “gistol” Macdonalds

(1) A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges

(2) We postulate the existence of a family of polynomials indexed by gistols with the following basic properties:

$$\left\{ \begin{array}{ll} \text{(0)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \bar{H}_\mu(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \text{ is the diagram of } \mu \\ \text{(1)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \\ & \vdots \\ & \vdots \\ & \vdots \end{array} \right.$$

The basic tool : “gistol” Macdonalds

(1) A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges

(2) We postulate the existence of a family of polynomials indexed by gistols with the following basic properties:

$$\left\{ \begin{array}{ll} \text{(0)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \bar{H}_\mu(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \text{ is the diagram of } \mu \\ \text{(1)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D_1 \approx D_2 \\ & \vdots \\ & \vdots \\ & \vdots \end{array} \right.$$

The basic tool : “gistol” Macdonalds

(1) A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges

(2) We postulate the existence of a family of polynomials indexed by gistols with the following basic properties:

$$\left\{ \begin{array}{ll} \text{(0)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \bar{H}_\mu(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \text{ is the diagram of } \mu \\ \text{(1)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D_1 \approx D_2 \\ \text{(2)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{t}, \mathbf{q}) \\ & \vdots \\ & \vdots \end{array} \right.$$

The basic tool : “gistol” Macdonalds

(1) A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges

(2) We postulate the existence of a family of polynomials indexed by gistols with the following basic properties:

$$\left\{ \begin{array}{ll} \text{(0)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \bar{H}_\mu(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \text{ is the diagram of } \mu \\ \text{(1)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D_1 \approx D_2 \\ \text{(2)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{t}, \mathbf{q}) \quad \text{if } D_2 \approx D'_1 \\ & \vdots \\ & \vdots \end{array} \right.$$

The basic tool : “gistol” Macdonalds

(1) A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges

(2) We postulate the existence of a family of polynomials indexed by gistols with the following basic properties:

$$\left\{ \begin{array}{ll} \text{(0)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \bar{H}_\mu(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \text{ is the diagram of } \mu \\ \text{(1)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D_1 \approx D_2 \\ \text{(2)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{t}, \mathbf{q}) \quad \text{if } D_2 \approx D'_1 \\ \text{(3)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t})G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \end{array} \right.$$

The basic tool : “gistol” Macdonalds

(1) A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges

(2) We postulate the existence of a family of polynomials indexed by gistols with the following basic properties:

$$\left\{ \begin{array}{ll} \text{(0)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \bar{H}_\mu(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \text{ is the diagram of } \mu \\ \text{(1)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D_1 \approx D_2 \\ \text{(2)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{t}, \mathbf{q}) \quad \text{if } D_2 \approx D'_1 \\ \text{(3)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t})G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \approx D_1 \times D_2 \end{array} \right.$$

The basic tool : “gistol” Macdonalds

(1) A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges

(2) We postulate the existence of a family of polynomials indexed by gistols with the following basic properties:

$$\left\{ \begin{array}{ll} \text{(0)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \bar{H}_\mu(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \text{ is the diagram of } \mu \\ \text{(1)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D_1 \approx D_2 \\ \text{(2)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{t}, \mathbf{q}) \quad \text{if } D_2 \approx D'_1 \\ \text{(3)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \approx D_1 \times D_2 \\ \text{(4)} & \partial_{p_1} G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \sum_{s \in D} w_{s,D}(\mathbf{q}, \mathbf{t}) G_{D/s}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \end{array} \right.$$

The basic tool : “gistol” Macdonalds

(1) A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges

(2) We postulate the existence of a family of polynomials indexed by gistols with the following basic properties:

$$\left\{ \begin{array}{ll} \text{(0)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \bar{H}_\mu(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \text{ is the diagram of } \mu \\ \text{(1)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D_1 \approx D_2 \\ \text{(2)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{t}, \mathbf{q}) \quad \text{if } D_2 \approx D'_1 \\ \text{(3)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \approx D_1 \times D_2 \\ \text{(4)} & \partial_{p_1} G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \sum_{s \in D} w_{s,D}(\mathbf{q}, \mathbf{t}) G_{D/s}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \end{array} \right.$$

Representation theoretical reasons suggest that,

The basic tool : “gistol” Macdonalds

(1) A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges

(2) We postulate the existence of a family of polynomials indexed by gistols with the following basic properties:

$$\left\{ \begin{array}{ll} \text{(0)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \bar{H}_\mu(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \text{ is the diagram of } \mu \\ \text{(1)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D_1 \approx D_2 \\ \text{(2)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{t}, \mathbf{q}) \quad \text{if } D_2 \approx D'_1 \\ \text{(3)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \approx D_1 \times D_2 \\ \text{(4)} & \partial_{p_1} G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \sum_{s \in D} w_{s,D}(\mathbf{q}, \mathbf{t}) G_{D/s}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \end{array} \right.$$

Representation theoretical reasons suggest that,

in the case that D is a skew diagram,

The basic tool : “gistol” Macdonalds

(1) A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges

(2) We postulate the existence of a family of polynomials indexed by gistols with the following basic properties:

$$\left\{ \begin{array}{ll} \text{(0)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \bar{H}_\mu(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \text{ is the diagram of } \mu \\ \text{(1)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D_1 \approx D_2 \\ \text{(2)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{t}, \mathbf{q}) \quad \text{if } D_2 \approx D'_1 \\ \text{(3)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \approx D_1 \times D_2 \\ \text{(4)} & \partial_{p_1} G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \sum_{s \in D} w_{s,D}(\mathbf{q}, \mathbf{t}) G_{D/s}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \end{array} \right.$$

Representation theoretical reasons suggest that,

in the case that D is a skew diagram,

$$\text{a) } w_1[s, D] = t^{l_D(s)} q^{a'_D(s)} \quad \text{and} \quad \text{b) } w_2[s, D] = t^{l'_D(s)} q^{a_D(s)}$$

The basic tool : “gistol” Macdonalds

(1) A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges

(2) We postulate the existence of a family of polynomials indexed by gistols with the following basic properties:

$$\left\{ \begin{array}{ll} \text{(0)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \bar{H}_\mu(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \text{ is the diagram of } \mu \\ \text{(1)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D_1 \approx D_2 \\ \text{(2)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{t}, \mathbf{q}) \quad \text{if } D_2 \approx D_1' \\ \text{(3)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \approx D_1 \times D_2 \\ \text{(4)} & \partial_{p_1} G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \sum_{s \in D} w_{s,D}(\mathbf{q}, \mathbf{t}) G_{D/s}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \end{array} \right.$$

Representation theoretical reasons suggest that,

in the case that D is a skew diagram,

$$\text{a) } w_1[s, D] = t^{l_D(s)} q^{a'_D(s)} \quad \text{and} \quad \text{b) } w_2[s, D] = t^{l'_D(s)} q^{a_D(s)}$$

Note: these properties overdetermine the family $\{G_D(\mathbf{x}; \mathbf{q}, \mathbf{t})\}_D$,

The basic tool : “gistol” Macdonalds

(1) A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges

(2) We postulate the existence of a family of polynomials indexed by gistols with the following basic properties:

$$\left\{ \begin{array}{ll} \text{(0)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \bar{H}_\mu(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \text{ is the diagram of } \mu \\ \text{(1)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D_1 \approx D_2 \\ \text{(2)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{t}, \mathbf{q}) \quad \text{if } D_2 \approx D_1' \\ \text{(3)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \approx D_1 \times D_2 \\ \text{(4)} & \partial_{p_1} G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \sum_{s \in D} w_{s,D}(\mathbf{q}, \mathbf{t}) G_{D/s}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \end{array} \right.$$

Representation theoretical reasons suggest that,

in the case that D is a skew diagram,

$$\text{a) } w_1[s, D] = t^{l_D(s)} q^{a_D(s)} \quad \text{and} \quad \text{b) } w_2[s, D] = t^{l'_D(s)} q^{a_D(s)}$$

Note: these properties overdetermine the family $\{G_D(\mathbf{x}; \mathbf{q}, \mathbf{t})\}_D$,

existence is by no means guaranteed.

The basic tool : “gistol” Macdonalds

(1) A “gistol” is a lattice diagram that can be transformed to a skew diagram by row and column interchanges

(2) We postulate the existence of a family of polynomials indexed by gistols with the following basic properties:

$$\left\{ \begin{array}{ll} \text{(0)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \bar{H}_\mu(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \text{ is the diagram of } \mu \\ \text{(1)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D_1 \approx D_2 \\ \text{(2)} & G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_2}(\mathbf{x}; \mathbf{t}, \mathbf{q}) \quad \text{if } D_2 \approx D_1' \\ \text{(3)} & G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = G_{D_1}(\mathbf{x}; \mathbf{q}, \mathbf{t}) G_{D_2}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \quad \text{if } D \approx D_1 \times D_2 \\ \text{(4)} & \partial_{p_1} G_D(\mathbf{x}; \mathbf{q}, \mathbf{t}) = \sum_{s \in D} w_{s,D}(\mathbf{q}, \mathbf{t}) G_{D/s}(\mathbf{x}; \mathbf{q}, \mathbf{t}) \end{array} \right.$$

Representation theoretical reasons suggest that,

in the case that D is a skew diagram,

$$\text{a) } w_1[s, D] = t^{l_D(s)} q^{a_D(s)} \quad \text{and} \quad \text{b) } w_2[s, D] = t^{l'_D(s)} q^{a_D(s)}$$

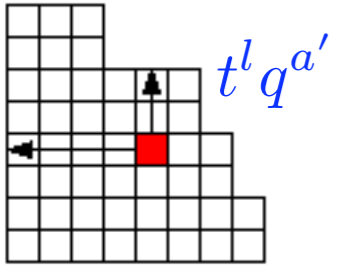
Note: these properties overdetermine the family $\{G_D(\mathbf{x}; \mathbf{q}, \mathbf{t})\}_D$,

existence is by no means guaranteed.

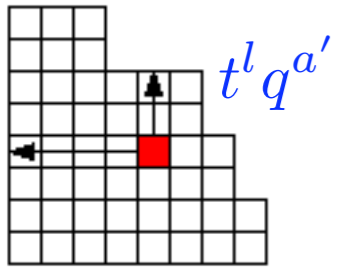
next

An example of a use of gistsols

An example of a use of gistols

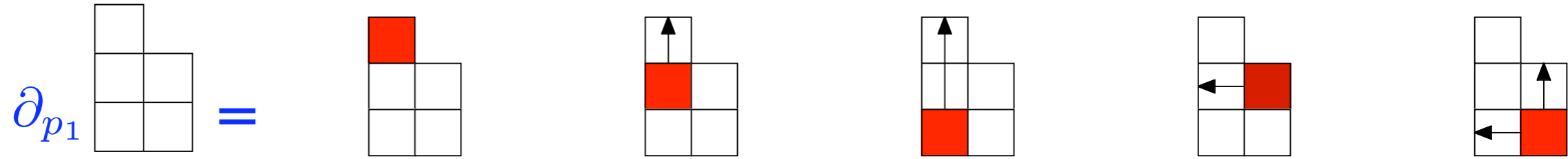
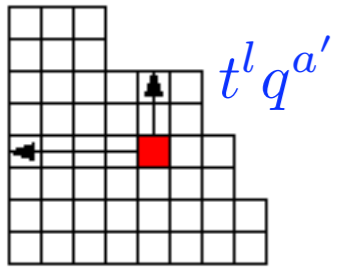


An example of a use of gistols

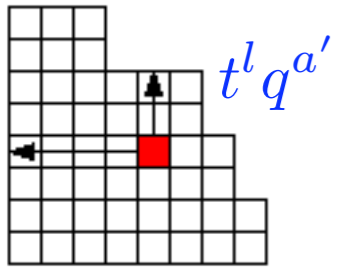


$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} =$$

An example of a use of gistols

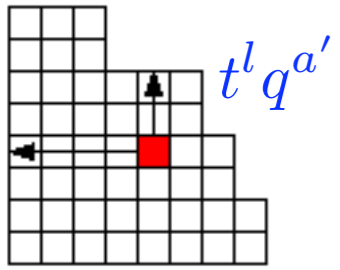


An example of a use of gistols



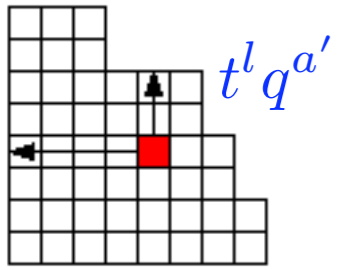
$$\partial_{p_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}\square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} + \begin{array}{|c|c|} \hline \square & \square \\ \hline \color{red}\square & \square \\ \hline \square & \square \\ \hline \end{array} + \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \color{red}\square & \square \\ \hline \end{array} + \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \color{red}\square \\ \hline \square & \square \\ \hline \end{array} + \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \color{red}\square \\ \hline \end{array}$$

An example of a use of gistols



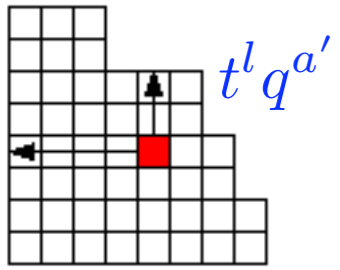
$$\partial_{p_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}\square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} + t \begin{array}{|c|c|} \hline \square & \square \\ \hline \color{red}\square & \square \\ \hline \square & \square \\ \hline \end{array} + \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \color{red}\square & \square \\ \hline \end{array} + \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \color{red}\square \\ \hline \square & \square \\ \hline \end{array} + \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \color{red}\square \\ \hline \square & \color{red}\square \\ \hline \end{array}$$

An example of a use of gistols



$$\partial_{p_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}\square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} + t \begin{array}{|c|c|} \hline \square & \color{red}\square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \color{red}\square \\ \hline \square & \square \\ \hline \end{array} + \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \color{red}\square \\ \hline \square & \square \\ \hline \end{array} + \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \color{red}\square \\ \hline \square & \color{red}\square \\ \hline \end{array}$$

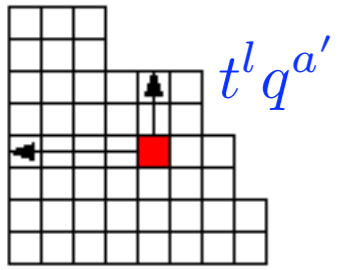
An example of a use of gistols



$t^l q^{a'}$

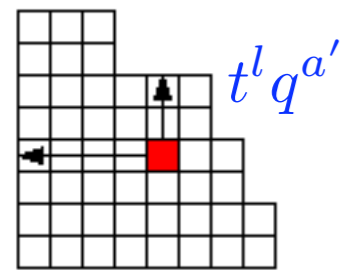
$$\partial_{p_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}\square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} + t \begin{array}{|c|c|} \hline \square & \color{red}\square \\ \hline \color{red}\square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} + t^2 \begin{array}{|c|c|} \hline \square & \color{red}\square \\ \hline \square & \color{red}\square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} + q \begin{array}{|c|c|} \hline \square & \color{red}\square \\ \hline \color{red}\square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} + \begin{array}{|c|c|} \hline \square & \color{red}\square \\ \hline \square & \color{red}\square \\ \hline \color{red}\square & \square \\ \hline \square & \square \\ \hline \end{array}$$

An example of a use of gistols

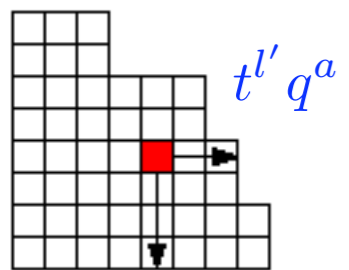


$$\partial_{p_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}\square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} + t \begin{array}{|c|c|} \hline \square & \color{red}\square \\ \hline \color{red}\square & \square \\ \hline \square & \square \\ \hline \end{array} + t^2 \begin{array}{|c|c|} \hline \square & \color{red}\square \\ \hline \square & \color{red}\square \\ \hline \square & \square \\ \hline \end{array} + q \begin{array}{|c|c|} \hline \square & \color{red}\square \\ \hline \square & \color{red}\square \\ \hline \square & \square \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline \square & \color{red}\square \\ \hline \square & \color{red}\square \\ \hline \color{red}\square & \color{red}\square \\ \hline \end{array}$$

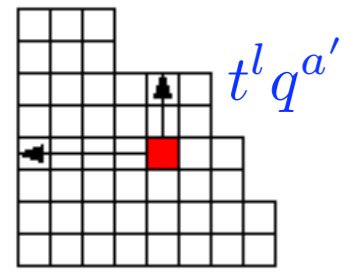
An example of a use of gistols



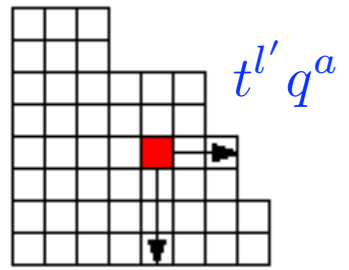
$$\partial_{p_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}\square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} + t \begin{array}{|c|c|} \hline \square & \color{red}\square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} + t^2 \begin{array}{|c|c|} \hline \square & \color{red}\square \\ \hline \square & \color{red}\square \\ \hline \square & \square \\ \hline \end{array} + q \begin{array}{|c|c|} \hline \square & \color{red}\square \\ \hline \square & \color{red}\square \\ \hline \square & \square \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline \square & \color{red}\square \\ \hline \square & \color{red}\square \\ \hline \square & \color{red}\square \\ \hline \end{array}$$



An example of a use of gistols

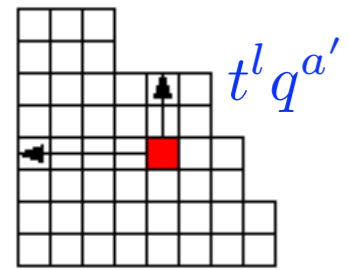


$$\partial_{p_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}\square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} + t \begin{array}{|c|c|} \hline \square & \color{red}\square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} + t^2 \begin{array}{|c|c|} \hline \square & \color{red}\square \\ \hline \square & \color{red}\square \\ \hline \square & \square \\ \hline \end{array} + q \begin{array}{|c|c|} \hline \square & \color{red}\square \\ \hline \square & \color{red}\square \\ \hline \square & \square \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline \square & \color{red}\square \\ \hline \square & \color{red}\square \\ \hline \square & \color{red}\square \\ \hline \end{array}$$

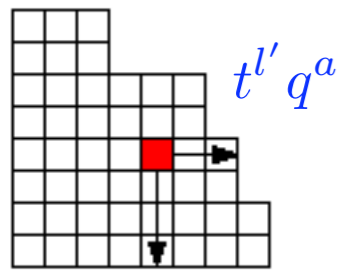


$$\partial_{p_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} =$$

An example of a use of gistols

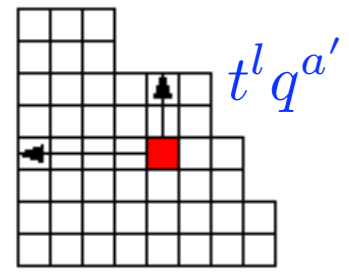


$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + t \begin{array}{|c|c|} \hline & \uparrow \\ \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline \end{array} + t^2 \begin{array}{|c|c|} \hline & \uparrow \\ \hline & \uparrow \\ \hline \color{red}{\square} & \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \\ \hline & \leftarrow \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \\ \hline & \uparrow \\ \hline & \leftarrow \color{red}{\square} \\ \hline & \\ \hline \end{array}$$

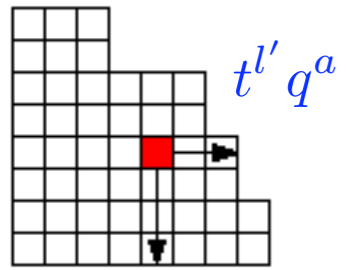


$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}{\square} & \\ \hline & \downarrow \\ \hline & \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \\ \hline \color{red}{\square} & \rightarrow \\ \hline & \downarrow \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline \color{red}{\square} & \rightarrow \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \color{red}{\square} \downarrow \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \color{red}{\square} \\ \hline & \\ \hline \end{array}$$

An example of a use of gistols

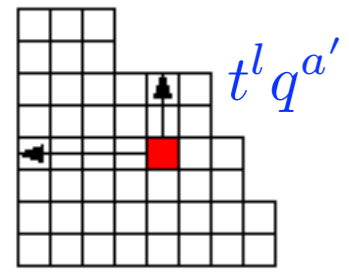


$$\partial_{p_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \begin{array}{|c|c|} \hline \blacksquare & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} + t \begin{array}{|c|c|} \hline \square & \uparrow \\ \hline \blacksquare & \square \\ \hline \square & \square \\ \hline \end{array} + t^2 \begin{array}{|c|c|} \hline \square & \uparrow \\ \hline \square & \uparrow \\ \hline \blacksquare & \square \\ \hline \end{array} + q \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \leftarrow \blacksquare \\ \hline \square & \square \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \uparrow \\ \hline \square & \leftarrow \blacksquare \\ \hline \end{array}$$

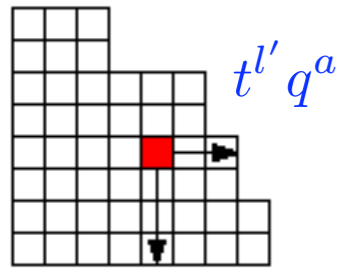


$$\partial_{p_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \begin{array}{|c|c|} \hline \blacksquare & \square \\ \hline \downarrow & \square \\ \hline \square & \square \\ \hline \end{array} + \begin{array}{|c|c|} \hline \square & \blacksquare \\ \hline \downarrow & \rightarrow \\ \hline \square & \square \\ \hline \end{array} + \begin{array}{|c|c|} \hline \square & \square \\ \hline \blacksquare & \rightarrow \\ \hline \square & \square \\ \hline \end{array} + \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \blacksquare \\ \hline \square & \downarrow \\ \hline \end{array} + \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \blacksquare \\ \hline \square & \square \\ \hline \end{array}$$

An example of a use of gistols

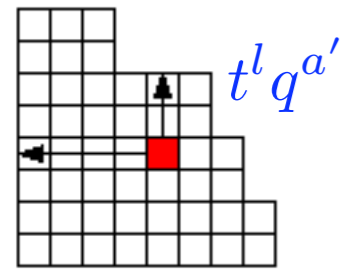


$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + t \begin{array}{|c|c|} \hline & \uparrow \\ \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline \end{array} + t^2 \begin{array}{|c|c|} \hline & \uparrow \\ \hline & \uparrow \\ \hline \color{red}{\square} & \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \\ \hline \leftarrow \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \\ \hline & \uparrow \\ \hline \leftarrow \color{red}{\square} & \\ \hline & \\ \hline \end{array}$$

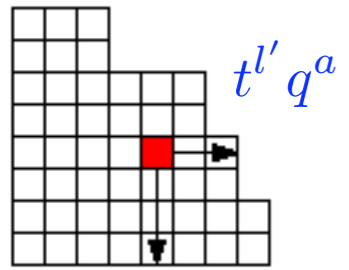


$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = t^2 \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \downarrow \\ \hline & \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \color{red}{\square} \rightarrow \\ \hline & \downarrow \\ \hline & \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \\ \hline & \color{red}{\square} \rightarrow \\ \hline & \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \\ \hline & \color{red}{\square} \downarrow \\ \hline & \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \color{red}{\square} \\ \hline & \\ \hline \end{array}$$

An example of a use of gistols

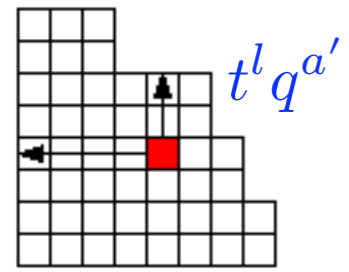


$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + t \begin{array}{|c|c|} \hline & \uparrow \\ \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline \end{array} + t^2 \begin{array}{|c|c|} \hline & \uparrow \\ \hline & \uparrow \\ \hline \color{red}{\square} & \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \\ \hline \leftarrow \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \\ \hline & \uparrow \\ \hline \leftarrow \color{red}{\square} & \\ \hline & \\ \hline \end{array}$$

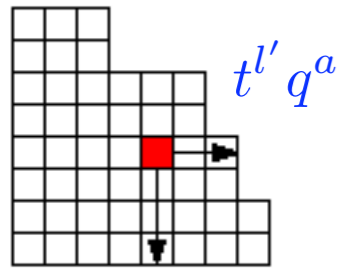


$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = t^2 \begin{array}{|c|c|} \hline \color{red}{\square} & \\ \hline & \downarrow \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \\ \hline \color{red}{\square} & \rightarrow \\ \hline & \downarrow \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \\ \hline & \color{red}{\square} \\ \hline & \rightarrow \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \\ \hline & \color{red}{\square} \\ \hline & \downarrow \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \color{red}{\square} \\ \hline & \\ \hline \end{array}$$

An example of a use of gistols

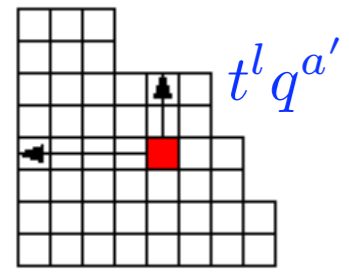


$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + t \begin{array}{|c|c|} \hline & \uparrow \\ \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline \end{array} + t^2 \begin{array}{|c|c|} \hline & \uparrow \\ \hline & \uparrow \\ \hline \color{red}{\square} & \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \\ \hline \leftarrow \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \\ \hline & \uparrow \\ \hline \leftarrow \color{red}{\square} & \uparrow \\ \hline & \\ \hline \end{array}$$

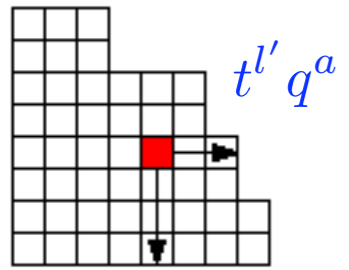


$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = t^2 \begin{array}{|c|c|} \hline \color{red}{\square} & \\ \hline \downarrow & \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \\ \hline \color{red}{\square} & \rightarrow \\ \hline \downarrow & \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline \color{red}{\square} & \rightarrow \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \\ \hline & \color{red}{\square} \\ \hline & \downarrow \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \color{red}{\square} \\ \hline & \\ \hline \end{array}$$

An example of a use of gistols

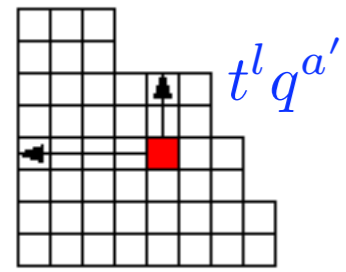


$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}{\blacksquare} & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + t \begin{array}{|c|c|} \hline & \uparrow \\ \hline \color{red}{\blacksquare} & \\ \hline & \\ \hline & \\ \hline \end{array} + t^2 \begin{array}{|c|c|} \hline & \uparrow \\ \hline & \uparrow \\ \hline \color{red}{\blacksquare} & \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \\ \hline \leftarrow \color{red}{\blacksquare} & \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \\ \hline & \uparrow \\ \hline \leftarrow \color{red}{\blacksquare} & \\ \hline & \\ \hline \end{array}$$

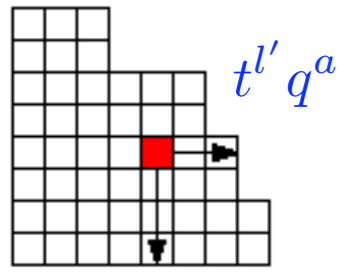


$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = t^2 \begin{array}{|c|c|} \hline & \color{red}{\blacksquare} \\ \hline & \downarrow \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \\ \hline \color{red}{\blacksquare} & \rightarrow \\ \hline & \downarrow \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline \color{red}{\blacksquare} & \rightarrow \\ \hline & \\ \hline \end{array} + t \begin{array}{|c|c|} \hline & \\ \hline & \color{red}{\blacksquare} \\ \hline & \downarrow \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \color{red}{\blacksquare} \\ \hline & \\ \hline \end{array}$$

An example of a use of gistols



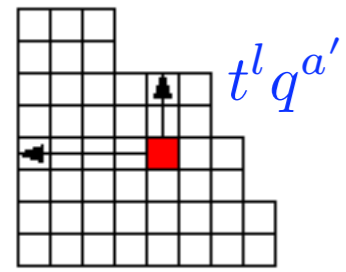
$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + t \begin{array}{|c|c|} \hline & \uparrow \\ \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline \end{array} + t^2 \begin{array}{|c|c|} \hline & \uparrow \\ \hline & \uparrow \\ \hline \color{red}{\square} & \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \\ \hline \leftarrow \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \\ \hline & \uparrow \\ \hline \leftarrow \color{red}{\square} & \\ \hline & \\ \hline \end{array}$$



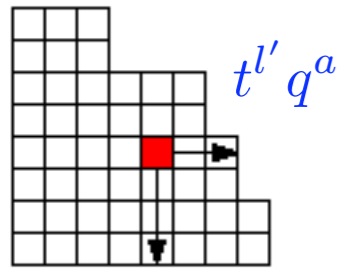
$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = t^2 \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \downarrow \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \\ \hline \color{red}{\square} & \rightarrow \\ \hline & \downarrow \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline \color{red}{\square} & \rightarrow \\ \hline & \\ \hline \end{array} + t \begin{array}{|c|c|} \hline & \\ \hline & \color{red}{\square} \\ \hline & \downarrow \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \color{red}{\square} \\ \hline & \\ \hline \end{array}$$

$$\partial_{P_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (t + t^2) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (q + tq) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array}$$

An example of a use of gistols



$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + t \begin{array}{|c|c|} \hline & \uparrow \\ \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline \end{array} + t^2 \begin{array}{|c|c|} \hline & \uparrow \\ \hline & \uparrow \\ \hline \color{red}{\square} & \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \\ \hline & \leftarrow \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \\ \hline & \uparrow \\ \hline \leftarrow \color{red}{\square} & \\ \hline & \\ \hline \end{array}$$

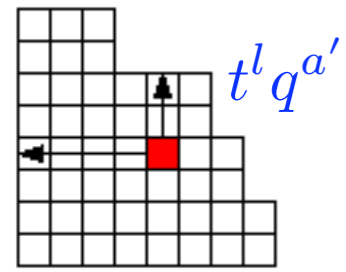


$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = t^2 \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \downarrow \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \\ \hline \color{red}{\square} & \rightarrow \\ \hline \downarrow & \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline \color{red}{\square} & \rightarrow \\ \hline & \\ \hline \end{array} + t \begin{array}{|c|c|} \hline & \\ \hline & \color{red}{\square} \\ \hline & \downarrow \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \color{red}{\square} \\ \hline & \\ \hline \end{array}$$

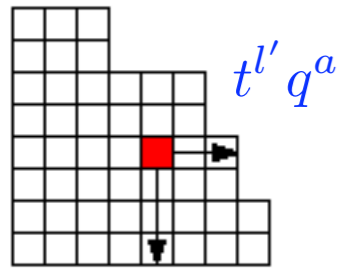
$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (t + t^2) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (q + tq) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = t^2 \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (q + qt) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (1 + t) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array}$$

An example of a use of gistols



$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + t \begin{array}{|c|c|} \hline & \uparrow \\ \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline \end{array} + t^2 \begin{array}{|c|c|} \hline & \uparrow \\ \hline & \uparrow \\ \hline \color{red}{\square} & \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \\ \hline \leftarrow \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \\ \hline & \uparrow \\ \hline \leftarrow \color{red}{\square} & \\ \hline & \\ \hline \end{array}$$



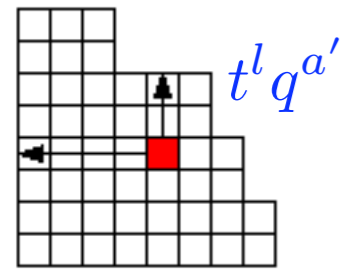
$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = t^2 \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \downarrow \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \\ \hline \color{red}{\square} & \rightarrow \\ \hline & \downarrow \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline \color{red}{\square} & \rightarrow \\ \hline & \\ \hline \end{array} + t \begin{array}{|c|c|} \hline & \\ \hline & \color{red}{\square} \\ \hline & \downarrow \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \color{red}{\square} \\ \hline & \\ \hline \end{array}$$

$$\partial_{P_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (t + t^2) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (q + tq) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array}$$

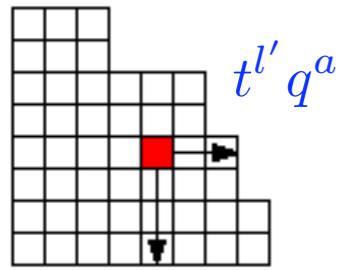
$$\partial_{P_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = t^2 \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (q + qt) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (1 + t) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array}$$



An example of a use of gistols



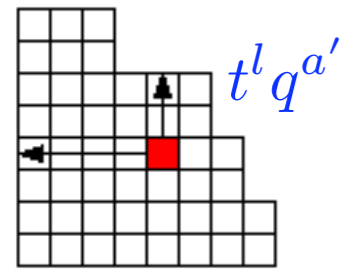
$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + t \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + t^2 \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array}$$



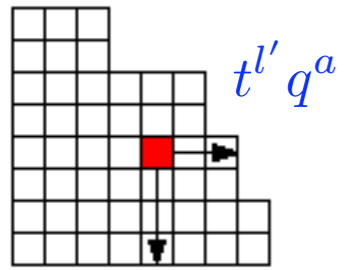
$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = t^2 \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array} + t \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array}$$

$$\begin{aligned} \partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} &= \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (t + t^2) \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array} + (q + tq) \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline \end{array} \\ \partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} &= t^2 \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array} + (q + qt) \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline \end{array} + (1 + t) \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array} \end{aligned} \Rightarrow \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array} = \frac{(1-t) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (q-1) \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline \end{array}}{q-t}$$

An example of a use of gistols



$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + t \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + t^2 \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array}$$

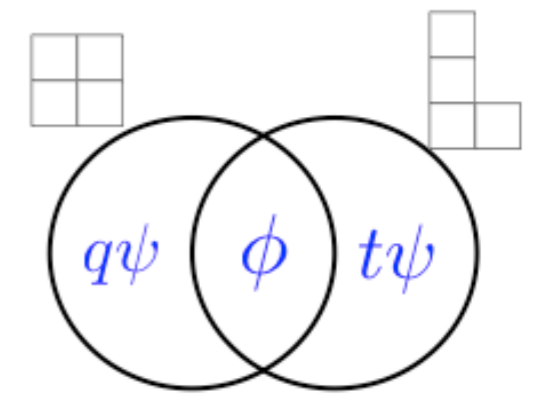


$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = t^2 \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline \end{array} + t \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array}$$

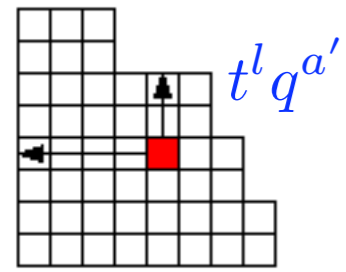
$$\partial_{P_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (t + t^2) \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array} + (q + tq) \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline \end{array}$$

$$\partial_{P_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = t^2 \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline \end{array} + (q + qt) \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline \end{array} + (1 + t) \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline \end{array}$$

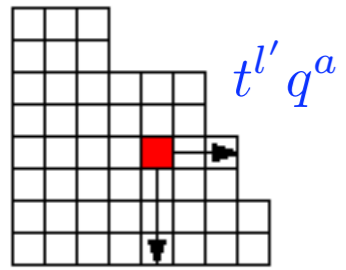
$$\begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \frac{(1-t) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (q-1) \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline \end{array}}{q-t}$$



An example of a use of gistols



$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + t \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + t^2 \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline \color{red}{\square} & \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array}$$



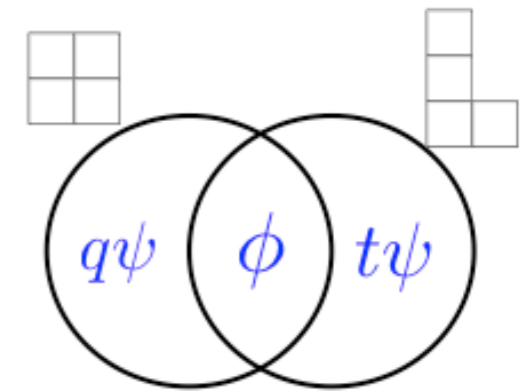
$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = t^2 \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array} + qt \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline \end{array} + q \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array} + t \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline \end{array} + \begin{array}{|c|c|} \hline & \color{red}{\square} \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (t + t^2) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (q + tq) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = t^2 \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (q + qt) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (1 + t) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array}$$

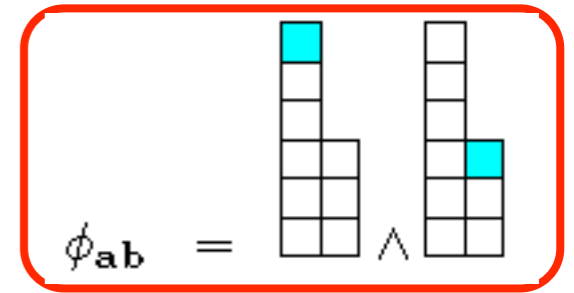
$$\begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \frac{(1-t) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (q-1) \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array}}{q-t}$$

$$\begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + t^2 q^2 \downarrow \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \phi + q\psi$$

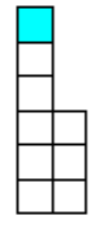


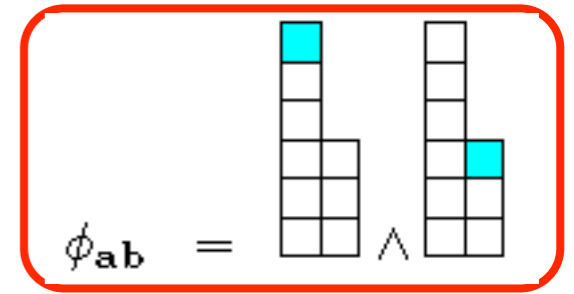
The General case

The General case

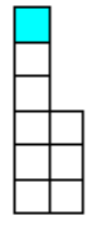



The General case

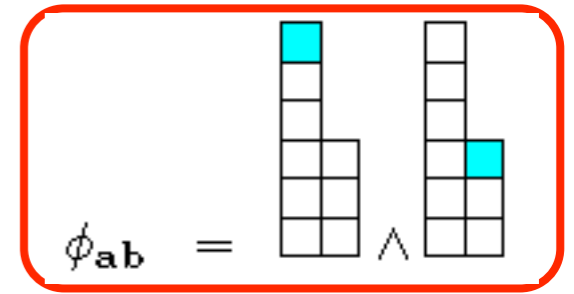

$$= \phi_{\mathbf{ab}} + q\psi_{\mathbf{ab}},$$


$$\phi_{\mathbf{ab}} = \text{Diagram 1} \wedge \text{Diagram 2}$$

The General case


$$= \phi_{ab} + q\psi_{ab},$$


$$= \phi_{ab} + t^{a-b}\psi_{ab}$$


$$\phi_{ab} = \text{diagram 1} \wedge \text{diagram 2}$$

The General case

$$\begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} = \phi_{ab} + q\psi_{ab},$$

$$\begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \color{cyan} \square \\ \hline \square \\ \hline \square \\ \hline \end{array} = \phi_{ab} + t^{a-b}\psi_{ab}$$

$$\phi_{ab} = \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} \wedge \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \color{cyan} \square \\ \hline \square \\ \hline \square \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} = [a-b]_t \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} + t^{a-b}[b]_t \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \color{cyan} \square \\ \hline \square \\ \hline \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \color{cyan} \square \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} = t^b[a-b]_t \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \color{cyan} \square \\ \hline \square \\ \hline \square \\ \hline \end{array} + [b]_t \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \color{cyan} \square \\ \hline \end{array}$$

The General case

$$\begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} = \phi_{ab} + q\psi_{ab},$$

$$\begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} = \phi_{ab} + t^{a-b}\psi_{ab}$$

$$\phi_{ab} = \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} \wedge \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} = [a-b]_t \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} + t^{a-b}[b]_t \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} = t^b[a-b]_t \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} + [b]_t \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array}$$

The General case

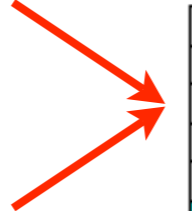
$$\begin{matrix} \color{cyan} \blacksquare \\ \square \\ \square \\ \square \\ \square \end{matrix} = \phi_{ab} + q\psi_{ab},$$

$$\begin{matrix} \square \\ \square \\ \square \\ \square \end{matrix} \begin{matrix} \blacksquare \\ \square \\ \square \\ \square \end{matrix} = \phi_{ab} + t^{a-b}\psi_{ab}$$

$\phi_{ab} = \begin{matrix} \color{cyan} \blacksquare \\ \square \\ \square \\ \square \\ \square \end{matrix} \wedge \begin{matrix} \square \\ \square \\ \square \\ \square \\ \square \end{matrix}$

$$\partial_{p_1} \begin{matrix} \square \\ \square \\ \square \\ \square \end{matrix} = [a-b]_t \begin{matrix} \color{cyan} \blacksquare \\ \square \\ \square \\ \square \end{matrix} + t^{a-b}[b]_t \begin{matrix} \square \\ \square \\ \color{cyan} \blacksquare \\ \square \end{matrix} + q[b]_t \begin{matrix} \square \\ \square \\ \square \\ \color{cyan} \blacksquare \end{matrix}$$

$$\partial_{p_1} \begin{matrix} \square \\ \square \\ \square \\ \square \end{matrix} = t^b[a-b]_t \begin{matrix} \color{cyan} \blacksquare \\ \square \\ \square \\ \square \end{matrix} + q[b]_t \begin{matrix} \square \\ \square \\ \color{cyan} \blacksquare \\ \square \end{matrix} + [b]_t \begin{matrix} \square \\ \square \\ \square \\ \color{cyan} \blacksquare \end{matrix}$$



$$\begin{matrix} \square \\ \square \\ \square \\ \square \\ \color{cyan} \blacksquare \end{matrix} = \frac{(t^{a-b} - 1) \begin{matrix} \color{cyan} \blacksquare \\ \square \\ \square \\ \square \end{matrix} + (1 - q) \begin{matrix} \square \\ \square \\ \square \\ \color{cyan} \blacksquare \end{matrix}}{t^{a-b} - q} \rightarrow \begin{matrix} \square \\ \square \\ \square \\ \square \\ \color{cyan} \blacksquare \end{matrix} = \phi_{ab} + \psi_{ab}$$

The General case

$$\begin{array}{|c|} \hline \color{cyan} \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \end{array} = \phi_{ab} + q\psi_{ab},$$

$$\begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \\ \hline \end{array} = \phi_{ab} + t^{a-b}\psi_{ab}$$

$$\phi_{ab} = \begin{array}{|c|} \hline \color{cyan} \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \end{array} \wedge \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \end{array} = [a-b]_t \begin{array}{|c|} \hline \color{cyan} \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \end{array} + t^{a-b} [b]_t \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \\ \hline \end{array} + q [b]_t \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \end{array} = t^b [a-b]_t \begin{array}{|c|} \hline \color{cyan} \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \end{array} + q [b]_t \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \\ \hline \end{array} + [b]_t \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \\ \hline \end{array}$$

$$\begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \\ \hline \end{array} = \frac{(t^{a-b} - 1) \begin{array}{|c|} \hline \color{cyan} \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \end{array} + (1 - q) \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \\ \hline \end{array}}{t^{a-b} - q} \rightarrow \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \\ \hline \end{array} = \phi_{ab} + \psi_{ab}$$



The General case

$$\begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = \phi_{ab} + q\psi_{ab},$$

$$\begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \phi_{ab} + t^{a-b}\psi_{ab}$$

$$\phi_{ab} = \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} \wedge \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = [a-b]_t \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + t^{a-b}[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = t^b[a-b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} + [b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}$$

$$\begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \frac{(t^{a-b} - 1) \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + (1 - q) \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}}{t^{a-b} - q} \rightarrow \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \phi_{ab} + \psi_{ab}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = t^b[a-b]_t(\phi_{ab} + q\psi_{ab}) + q[b]_t(\phi_{ab} + \psi_{ab}) + [b]_t(\phi_{ab} + t^{a-b}\psi_{ab})$$

The General case

$$\begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = \boxed{\phi_{ab} + q\psi_{ab}},$$

$$\begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \phi_{ab} + t^{a-b}\psi_{ab}$$

$$\boxed{\phi_{ab} = \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} \wedge \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}}$$

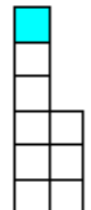
$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = [a-b]_t \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + t^{a-b}[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}$$

$$\boxed{\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = t^b[a-b]_t \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} + [b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}}$$


$$\begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \frac{(t^{a-b} - 1) \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + (1 - q) \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}}{t^{a-b} - q} \rightarrow \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \phi_{ab} + \psi_{ab}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = t^b[a-b]_t (\phi_{ab} + q\psi_{ab}) + q[b]_t (\phi_{ab} + \psi_{ab}) + [b]_t (\phi_{ab} + t^{a-b}\psi_{ab})$$

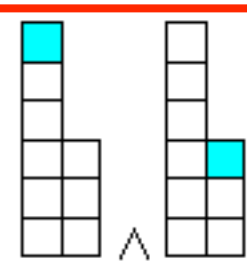
The General case



$$= \phi_{ab} + q\psi_{ab},$$




$$= \phi_{ab} + t^{a-b}\psi_{ab}$$



$$\phi_{ab} = \text{Young diagram for } (a,b)$$

$$\partial_{p_1} \text{ (Young diagram for } (a,b) \text{)} = [a-b]_t \text{ (Young diagram for } (a,b) \text{)} + t^{a-b}[b]_t \text{ (Young diagram for } (a,b) \text{)} + q[b]_t \text{ (Young diagram for } (a,b) \text{)}$$

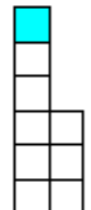
$$\partial_{p_1} \text{ (Young diagram for } (a,b) \text{)} = t^b[a-b]_t \text{ (Young diagram for } (a,b) \text{)} + q[b]_t \text{ (Young diagram for } (a,b) \text{)} + [b]_t \text{ (Young diagram for } (a,b) \text{)}$$




$$= \frac{(t^{a-b} - 1) \text{ (Young diagram for } (a,b) \text{)} + (1 - q) \text{ (Young diagram for } (a,b) \text{)}}{t^{a-b} - q} \rightarrow \text{ (Young diagram for } (a,b) \text{)} = \phi_{ab} + \psi_{ab}$$

$$\partial_{p_1} \text{ (Young diagram for } (a,b) \text{)} = t^b[a-b]_t (\phi_{ab} + q\psi_{ab}) + q[b]_t (\phi_{ab} + \psi_{ab}) + [b]_t (\phi_{ab} + t^{a-b}\psi_{ab})$$

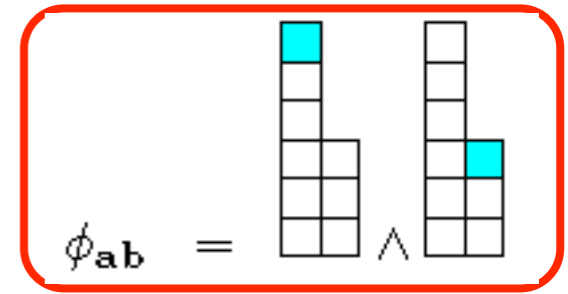
The General case



$$= \phi_{ab} + q\psi_{ab},$$



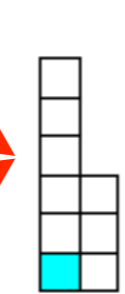
$$= \phi_{ab} + t^{a-b}\psi_{ab}$$



$$\phi_{ab} = \text{diagram 1} \wedge \text{diagram 2}$$

$$\partial_{P_1} \text{diagram} = [a-b]_t \text{diagram} + t^{a-b}[b]_t \text{diagram} + q[b]_t \text{diagram}$$

$$\partial_{P_1} \text{diagram} = t^b[a-b]_t \text{diagram} + q[b]_t \text{diagram} + [b]_t \text{diagram}$$



$$= \frac{(t^{a-b} - 1) \text{diagram} + (1 - q) \text{diagram}}{t^{a-b} - q} \rightarrow \text{diagram} = \phi_{ab} + \psi_{ab}$$

$$\partial_{P_1} \text{diagram} = t^b[a-b]_t(\phi_{ab} + q\psi_{ab}) + q[b]_t(\phi_{ab} + \psi_{ab}) + [b]_t(\phi_{ab} + t^{a-b}\psi_{ab})$$

The General case

$$\begin{array}{|c|} \hline \color{cyan} \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \end{array} = \phi_{ab} + q\psi_{ab},$$

$$\begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \\ \hline \end{array} = \phi_{ab} + t^{a-b}\psi_{ab}$$

$\phi_{ab} = \begin{array}{|c|} \hline \color{cyan} \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \end{array} \wedge \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \\ \hline \end{array}$

$$\partial_{p_1} \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \end{array} = [a-b]_t \begin{array}{|c|} \hline \color{cyan} \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \end{array} + t^{a-b}[b]_t \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \end{array} = t^b[a-b]_t \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \end{array} + q[b]_t \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \end{array} + [b]_t \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \end{array}$$



$$\begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \end{array} = \frac{(t^{a-b} - 1) \begin{array}{|c|} \hline \color{cyan} \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \end{array} + (1 - q) \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \end{array}}{t^{a-b} - q} \rightarrow \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \color{cyan} \end{array} = \phi_{ab} + \psi_{ab}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \\ \hline \\ \hline \\ \hline \\ \hline \\ \hline \end{array} = t^b[a-b]_t(\phi_{ab} + q\psi_{ab}) + q[b]_t(\phi_{ab} + \psi_{ab}) + [b]_t(\phi_{ab} + t^{a-b}\psi_{ab})$$

The General case

$$\begin{array}{|c|c|} \hline & \blacksquare \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \phi_{ab} + q\psi_{ab},$$

$$\begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \blacksquare \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \phi_{ab} + t^{a-b}\psi_{ab}$$

$$\phi_{ab} = \begin{array}{|c|c|} \hline & \blacksquare \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \blacksquare \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = [a-b]_t \begin{array}{|c|c|} \hline & \blacksquare \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + t^{a-b}[b]_t \begin{array}{|c|c|} \hline & \blacksquare \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + q[b]_t \begin{array}{|c|c|} \hline & \blacksquare \\ \hline & \blacksquare \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = t^b[a-b]_t \begin{array}{|c|c|} \hline & \blacksquare \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + q[b]_t \begin{array}{|c|c|} \hline & \blacksquare \\ \hline & \blacksquare \\ \hline & \blacksquare \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + [b]_t \begin{array}{|c|c|} \hline & \blacksquare \\ \hline & \blacksquare \\ \hline & \blacksquare \\ \hline & \blacksquare \\ \hline & \\ \hline & \\ \hline \end{array}$$



$$\begin{array}{|c|c|} \hline & \blacksquare \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \frac{(t^{a-b} - 1) \begin{array}{|c|c|} \hline & \blacksquare \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} + (1 - q) \begin{array}{|c|c|} \hline & \blacksquare \\ \hline & \blacksquare \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array}}{t^{a-b} - q}$$

$$\begin{array}{|c|c|} \hline & \blacksquare \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = \phi_{ab} + \psi_{ab}$$

$$\partial_{p_1} \begin{array}{|c|c|} \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline & \\ \hline \end{array} = t^b[a-b]_t(\phi_{ab} + q\psi_{ab}) + q[b]_t(\phi_{ab} + \psi_{ab}) + [b]_t(\phi_{ab} + t^{a-b}\psi_{ab})$$

The General case

$$\begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = \phi_{ab} + q\psi_{ab},$$

$$\begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \phi_{ab} + t^{a-b}\psi_{ab}$$

$$\phi_{ab} = \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} \wedge \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = [a-b]_t \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + t^{a-b}[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = t^b[a-b]_t \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} + [b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}$$



$$\begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \frac{(t^{a-b} - 1) \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + (1 - q) \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}}{t^{a-b} - q} \rightarrow \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \phi_{ab} + \psi_{ab}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = t^b[a-b]_t(\phi_{ab} + q\psi_{ab}) + q[b]_t(\phi_{ab} + \psi_{ab}) + [b]_t(\phi_{ab} + t^{a-b}\psi_{ab})$$

The General case

$$\begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = \phi_{ab} + q\psi_{ab},$$

$$\begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \phi_{ab} + t^{a-b}\psi_{ab}$$

$$\phi_{ab} = \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} \wedge \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = [a-b]_t \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + t^{a-b}[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = t^b[a-b]_t \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} + [b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}$$



$$\begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \frac{(t^{a-b} - 1) \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + (1 - q) \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}}{t^{a-b} - q} \rightarrow \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \phi_{ab} + \psi_{ab}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = t^b[a-b]_t(\phi_{ab} + q\psi_{ab}) + q[b]_t(\phi_{ab} + \psi_{ab}) + [b]_t(\phi_{ab} + t^{a-b}\psi_{ab})$$

$$\psi_{ab} : q(t^b[a-b]_t + [b]_t) + t^{a-b}[b]_t$$

The General case

$$\begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} = \phi_{ab} + q\psi_{ab},$$

$$\begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \color{cyan} \square \\ \hline \end{array} = \phi_{ab} + t^{a-b}\psi_{ab}$$

$$\phi_{ab} = \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} \wedge \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \color{cyan} \square \\ \hline \square \\ \hline \end{array}$$

$$\partial_{P1} \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} = [a-b]_t \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} + t^{a-b} [b]_t \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \color{cyan} \square \\ \hline \square \\ \hline \end{array} + q [b]_t \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \color{cyan} \square \\ \hline \end{array}$$

$$\partial_{P1} \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} = t^b [a-b]_t \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \color{cyan} \square \\ \hline \end{array} + q [b]_t \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \color{cyan} \square \\ \hline \end{array} + [b]_t \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \color{cyan} \square \\ \hline \end{array}$$



$$\begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \color{cyan} \square \\ \hline \end{array} = \frac{(t^{a-b} - 1) \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} + (1 - q) \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \color{cyan} \square \\ \hline \end{array}}{t^{a-b} - q} \rightarrow \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \color{cyan} \square \\ \hline \end{array} = \phi_{ab} + \psi_{ab}$$

$$\partial_{P1} \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} = t^b [a-b]_t (\phi_{ab} + q\psi_{ab}) + q [b]_t (\phi_{ab} + \psi_{ab}) + [b]_t (\phi_{ab} + t^{a-b}\psi_{ab})$$

$$\psi_{ab} : q(t^b [a-b]_t + [b]_t) + t^{a-b} [b]_t$$

$$[b]_t + t^b [a-b]_t = 1 + t + \dots + t^{a-1} = [a-b]_t + t^{a-b} [b]_t$$

The General case

$$\begin{array}{c} \color{cyan}\blacksquare \\ \square \\ \square \\ \square \\ \square \end{array} = \phi_{ab} + q\psi_{ab},$$

$$\begin{array}{c} \square \\ \square \\ \square \\ \square \\ \color{cyan}\blacksquare \end{array} = \phi_{ab} + t^{a-b}\psi_{ab}$$

$$\phi_{ab} = \begin{array}{c} \color{cyan}\blacksquare \\ \square \\ \square \\ \square \\ \square \end{array} \wedge \begin{array}{c} \square \\ \square \\ \square \\ \color{cyan}\blacksquare \\ \square \end{array}$$

$$\partial_{p_1} \begin{array}{c} \square \\ \square \\ \square \\ \square \\ \square \end{array} = [a-b]_t \begin{array}{c} \color{cyan}\blacksquare \\ \square \\ \square \\ \square \\ \square \end{array} + t^{a-b}[b]_t \begin{array}{c} \square \\ \square \\ \square \\ \square \\ \color{cyan}\blacksquare \end{array} + q[b]_t \begin{array}{c} \square \\ \square \\ \square \\ \color{cyan}\blacksquare \\ \square \end{array}$$

$$\partial_{p_1} \begin{array}{c} \square \\ \square \\ \square \\ \square \\ \square \end{array} = t^b[a-b]_t \begin{array}{c} \color{cyan}\blacksquare \\ \square \\ \square \\ \square \\ \square \end{array} + q[b]_t \begin{array}{c} \square \\ \square \\ \square \\ \square \\ \color{cyan}\blacksquare \end{array} + [b]_t \begin{array}{c} \square \\ \square \\ \square \\ \color{cyan}\blacksquare \\ \square \end{array}$$



$$\begin{array}{c} \square \\ \square \\ \square \\ \square \\ \color{cyan}\blacksquare \end{array} = \frac{(t^{a-b} - 1) \begin{array}{c} \color{cyan}\blacksquare \\ \square \\ \square \\ \square \\ \square \end{array} + (1 - q) \begin{array}{c} \square \\ \square \\ \square \\ \square \\ \color{cyan}\blacksquare \end{array}}{t^{a-b} - q} \rightarrow \begin{array}{c} \square \\ \square \\ \square \\ \square \\ \color{cyan}\blacksquare \end{array} = \phi_{ab} + \psi_{ab}$$

$$\partial_{p_1} \begin{array}{c} \square \\ \square \\ \square \\ \square \\ \square \end{array} = t^b[a-b]_t(\phi_{ab} + q\psi_{ab}) + q[b]_t(\phi_{ab} + \psi_{ab}) + [b]_t(\phi_{ab} + t^{a-b}\psi_{ab})$$

$$\psi_{ab} : q(t^b[a-b]_t + [b]_t) + t^{a-b}[b]_t$$

$$[b]_t + t^b[a-b]_t = 1 + t + \dots + t^{a-1} = [a-b]_t + t^{a-b}[b]_t$$

$$\psi_{ab} : q([a-b]_t + t^{a-b}[b]_t) + t^{a-b}[b]_t$$

The General case

$$\begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = \phi_{ab} + q\psi_{ab},$$

$$\begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = \phi_{ab} + t^{a-b}\psi_{ab}$$

$\phi_{ab} = \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} \wedge \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array}$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = [a-b]_t \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + t^{a-b}[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = t^b[a-b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} + [b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array}$$



$$\begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = \frac{(t^{a-b} - 1) \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + (1 - q) \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array}}{t^{a-b} - q} \rightarrow \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = \phi_{ab} + \psi_{ab}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = t^b[a-b]_t(\phi_{ab} + q\psi_{ab}) + q[b]_t(\phi_{ab} + \psi_{ab}) + [b]_t(\phi_{ab} + t^{a-b}\psi_{ab})$$

$$\psi_{ab} : q(t^b[a-b]_t + [b]_t) + t^{a-b}[b]_t$$

$$[b]_t + t^b[a-b]_t = 1 + t + \dots + t^{a-1} = [a-b]_t + t^{a-b}[b]_t$$

$$\psi_{ab} : q([a-b]_t + t^{a-b}[b]_t) + t^{a-b}[b]_t$$

$$\psi_{ab} : q[a-b]_t + (1+q)t^{a-b}[b]_t$$

The General case

$$\begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = \phi_{ab} + q\psi_{ab},$$

$$\begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \phi_{ab} + t^{a-b}\psi_{ab}$$

$\phi_{ab} = \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} \wedge \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}$

$$\begin{aligned} \partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} &= [a-b]_t \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + t^{a-b}[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} \\ \partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} &= t^b[a-b]_t \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} + [b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} \end{aligned}$$
$$\begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \frac{(t^{a-b} - 1) \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + (1 - q) \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}}{t^{a-b} - q} \rightarrow \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \phi_{ab} + \psi_{ab}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = t^b[a-b]_t(\phi_{ab} + q\psi_{ab}) + q[b]_t(\phi_{ab} + \psi_{ab}) + [b]_t(\phi_{ab} + t^{a-b}\psi_{ab})$$

$$\psi_{ab} : q(t^b[a-b]_t + [b]_t) + t^{a-b}[b]_t$$

$$[b]_t + t^b[a-b]_t = 1 + t + \dots + t^{a-1} = [a-b]_t + t^{a-b}[b]_t$$

$$\psi_{ab} : q([a-b]_t + t^{a-b}[b]_t) + t^{a-b}[b]_t$$

$$\phi_{ab} : t^b[a-b]_t + (1+q)[b]_t$$

$$\psi_{ab} : q[a-b]_t + (1+q)t^{a-b}[b]_t$$

The General case

$$\begin{array}{|c|} \hline \blacksquare \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} = \phi_{ab} + q\psi_{ab},$$

$$\begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \blacksquare \\ \hline \square \\ \hline \end{array} = \phi_{ab} + t^{a-b}\psi_{ab}$$

$$\phi_{ab} = \begin{array}{|c|} \hline \blacksquare \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} \wedge \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \blacksquare \\ \hline \square \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} = [a-b]_t \begin{array}{|c|} \hline \blacksquare \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} + t^{a-b}[b]_t \begin{array}{|c|} \hline \square \\ \hline \blacksquare \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \blacksquare \\ \hline \square \\ \hline \square \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} = t^b[a-b]_t \begin{array}{|c|} \hline \blacksquare \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \hline \blacksquare \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} + [b]_t \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \blacksquare \\ \hline \square \\ \hline \end{array}$$

$$\begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \blacksquare \\ \hline \square \\ \hline \end{array} = \frac{(t^{a-b} - 1) \begin{array}{|c|} \hline \blacksquare \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} + (1 - q) \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \blacksquare \\ \hline \square \\ \hline \square \\ \hline \end{array}}{t^{a-b} - q} \rightarrow \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \blacksquare \\ \hline \square \\ \hline \end{array} = \phi_{ab} + \psi_{ab}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} = t^b[a-b]_t(\phi_{ab} + q\psi_{ab}) + q[b]_t(\phi_{ab} + \psi_{ab}) + [b]_t(\phi_{ab} + t^{a-b}\psi_{ab})$$

$$\psi_{ab} : q(t^b[a-b]_t + [b]_t) + t^{a-b}[b]_t$$

$$[b]_t + t^b[a-b]_t = 1 + t + \dots + t^{a-1} = [a-b]_t + t^{a-b}[b]_t$$

$$\psi_{ab} : q([a-b]_t + t^{a-b}[b]_t) + t^{a-b}[b]_t$$

$$\phi_{ab} : t^b[a-b]_t + (1+q)[b]_t$$

$$\psi_{ab} : q[a-b]_t + (1+q)t^{a-b}[b]_t$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t(t^b\phi_{ab} + q\psi_{ab})$$

The General case

$$\begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = \phi_{ab} + q\psi_{ab},$$

$$\begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \phi_{ab} + t^{a-b}\psi_{ab}$$

$$\phi_{ab} = \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} \wedge \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = [a-b]_t \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + t^{a-b}[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = t^b[a-b]_t \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} + [b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}$$

$$\begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \frac{(t^{a-b} - 1) \begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} + (1 - q) \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}}{t^{a-b} - q} \rightarrow \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \phi_{ab} + \psi_{ab}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = t^b[a-b]_t(\phi_{ab} + q\psi_{ab}) + q[b]_t(\phi_{ab} + \psi_{ab}) + [b]_t(\phi_{ab} + t^{a-b}\psi_{ab})$$

$$\psi_{ab} : q(t^b[a-b]_t + [b]_t) + t^{a-b}[b]_t$$

$$[b]_t + t^b[a-b]_t = 1 + t + \dots + t^{a-1} = [a-b]_t + t^{a-b}[b]_t$$

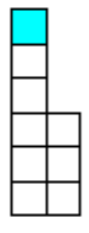
$$\psi_{ab} : q([a-b]_t + t^{a-b}[b]_t) + t^{a-b}[b]_t$$

$$\psi_{ab} : q[a-b]_t + (1+q)t^{a-b}[b]_t$$


$$\phi_{ab} : t^b[a-b]_t + (1+q)[b]_t$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t(t^b\phi_{ab} + q\psi_{ab})$$



The General case



$$= \phi_{ab} + q\psi_{ab},$$



$$= \phi_{ab} + t^{a-b}\psi_{ab}$$



 \wedge


$$\phi_{ab} =$$

$$\partial_{p_1} \begin{array}{c} \square \\ \square \\ \square \\ \square \end{array} = [a-b]_t \begin{array}{c} \square \\ \square \\ \square \\ \square \end{array} + t^{a-b}[b]_t \begin{array}{c} \square \\ \square \\ \square \\ \square \end{array} + q[b]_t \begin{array}{c} \square \\ \square \\ \square \\ \square \end{array}$$

$$\partial_{p_1} \begin{array}{c} \square \\ \square \\ \square \\ \square \end{array} = t^b[a-b]_t \begin{array}{c} \square \\ \square \\ \square \\ \square \end{array} + q[b]_t \begin{array}{c} \square \\ \square \\ \square \\ \square \end{array} + [b]_t \begin{array}{c} \square \\ \square \\ \square \\ \square \end{array}$$





$$= \frac{(t^{a-b} - 1) \begin{array}{c} \square \\ \square \\ \square \\ \square \end{array} + (1 - q) \begin{array}{c} \square \\ \square \\ \square \\ \square \end{array}}{t^{a-b} - q} \rightarrow \begin{array}{c} \square \\ \square \\ \square \\ \square \end{array} = \phi_{ab} + \psi_{ab}$$

$$\partial_{p_1} \begin{array}{c} \square \\ \square \\ \square \\ \square \end{array} = t^b[a-b]_t(\phi_{ab} + q\psi_{ab}) + q[b]_t(\phi_{ab} + \psi_{ab}) + [b]_t(\phi_{ab} + t^{a-b}\psi_{ab})$$


$$\psi_{ab} : q(t^b[a-b]_t + [b]_t) + t^{a-b}[b]_t$$

$$[b]_t + t^b[a-b]_t = 1 + t + \dots + t^{a-1} = [a-b]_t + t^{a-b}[b]_t$$

$$\psi_{ab} : q([a-b]_t + t^{a-b}[b]_t) + t^{a-b}[b]_t$$

$$\psi_{ab} : q[a-b]_t + (1+q)t^{a-b}[b]_t$$

$$\phi_{ab} : t^b[a-b]_t + (1+q)[b]_t$$



$$\partial_{p_1} \begin{array}{c} \square \\ \square \\ \square \\ \square \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t(t^b\phi_{ab} + q\psi_{ab})$$

The General case

$$= \phi_{ab} + q\psi_{ab},$$

$$= \phi_{ab} + t^{a-b}\psi_{ab}$$

$$\phi_{ab} = \wedge$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = [a-b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} + t^{a-b}[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = t^b[a-b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} + [b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array}$$



$$= \frac{(t^{a-b} - 1) \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} + (1 - q) \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array}}{t^{a-b} - q} \rightarrow \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = \phi_{ab} + \psi_{ab}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = t^b[a-b]_t(\phi_{ab} + q\psi_{ab}) + q[b]_t(\phi_{ab} + \psi_{ab}) + [b]_t(\phi_{ab} + t^{a-b}\psi_{ab})$$

$$\psi_{ab} : q(t^b[a-b]_t + [b]_t) + t^{a-b}[b]_t$$

$$[b]_t + t^b[a-b]_t = 1 + t + \dots + t^{a-1} = [a-b]_t + t^{a-b}[b]_t$$

$$\psi_{ab} : q([a-b]_t + t^{a-b}[b]_t) + t^{a-b}[b]_t$$

$$\phi_{ab} : t^b[a-b]_t + (1+q)[b]_t$$

$$\psi_{ab} : q[a-b]_t + (1+q)t^{a-b}[b]_t$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t(t^b\phi_{ab} + q\psi_{ab})$$

The General case

$$= \phi_{ab} + q\psi_{ab},$$

$$= \phi_{ab} + t^{a-b}\psi_{ab}$$

$$\phi_{ab} = \text{Diagram} \wedge \text{Diagram}$$

$$\partial_{p_1} \text{Diagram} = [a-b]_t \text{Diagram} + t^{a-b}[b]_t \text{Diagram} + q[b]_t \text{Diagram}$$

$$\partial_{p_1} \text{Diagram} = t^b[a-b]_t \text{Diagram} + q[b]_t \text{Diagram} + [b]_t \text{Diagram}$$

$$\text{Diagram} = \frac{(t^{a-b} - 1) \text{Diagram} + (1 - q) \text{Diagram}}{t^{a-b} - q} \rightarrow \text{Diagram} = \phi_{ab} + \psi_{ab}$$

$$\partial_{p_1} \text{Diagram} = t^b[a-b]_t(\phi_{ab} + q\psi_{ab}) + q[b]_t(\phi_{ab} + \psi_{ab}) + [b]_t(\phi_{ab} + t^{a-b}\psi_{ab})$$

$$\psi_{ab} : q(t^b[a-b]_t + [b]_t) + t^{a-b}[b]_t$$

$$[b]_t + t^b[a-b]_t = 1 + t + \dots + t^{a-1} = [a-b]_t + t^{a-b}[b]_t$$

$$\psi_{ab} : q([a-b]_t + t^{a-b}[b]_t) + t^{a-b}[b]_t$$

$$\phi_{ab} : t^b[a-b]_t + (1+q)[b]_t$$

$$\psi_{ab} : q[a-b]_t + (1+q)t^{a-b}[b]_t$$

$$\partial_{p_1} \text{Diagram} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t(t^b\phi_{ab} + q\psi_{ab})$$

The General case

$$\begin{array}{|c|} \hline \color{cyan} \square \\ \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = \phi_{ab} + q\psi_{ab},$$

$$\begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \phi_{ab} + t^{a-b}\psi_{ab}$$

$$\phi_{ab} = \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} \wedge \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = [a-b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} + t^{a-b}[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = t^b[a-b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} + q[b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} + [b]_t \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}$$

$$\begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \frac{(t^{a-b} - 1) \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} + (1 - q) \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array}}{t^{a-b} - q} \rightarrow \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \color{cyan} \square \\ \hline \end{array} = \phi_{ab} + \psi_{ab}$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = t^b[a-b]_t(\phi_{ab} + q\psi_{ab}) + q[b]_t(\phi_{ab} + \psi_{ab}) + [b]_t(\phi_{ab} + t^{a-b}\psi_{ab})$$

$$\psi_{ab} : q(t^b[a-b]_t + [b]_t) + t^{a-b}[b]_t$$

$$[b]_t + t^b[a-b]_t = 1 + t + \dots + t^{a-1} = [a-b]_t + t^{a-b}[b]_t$$

$$\psi_{ab} : q([a-b]_t + t^{a-b}[b]_t) + t^{a-b}[b]_t$$

$$\phi_{ab} : t^b[a-b]_t + (1+q)[b]_t$$

$$\psi_{ab} : q[a-b]_t + (1+q)t^{a-b}[b]_t$$

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \hline \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t(t^b\phi_{ab} + q\psi_{ab})$$

next

the next step

the next step

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t(t^b\phi_{ab} + q\psi_{ab})$$

the next step

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t(t^b\phi_{ab} + q\psi_{ab})$$

While my representation theoretical extension of the Haglund conjecture is

the next step

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t(t^b\phi_{ab} + q\psi_{ab})$$

While my representation theoretical extension of the Haglund conjecture is

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t t^b \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} (q/t, t)$$

the next step

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t(t^b\phi_{ab} + q\psi_{ab})$$

While my representation theoretical extension of the Haglund conjecture is

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t t^b \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} (q/t, t)$$

the next step

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t(t^b\phi_{ab} + q\psi_{ab})$$

While my representation theoretical extension of the Haglund conjecture is

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t t^b \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} (q/t, t)$$

the next step

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t(t^b\phi_{ab} + q\psi_{ab})$$

While my representation theoretical extension of the Haglund conjecture is

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t t^b \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} (q/t, t)$$

so we are reduced to proving the identity

the next step

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t(t^b\phi_{ab} + q\psi_{ab})$$

While my representation theoretical extension of the Haglund conjecture is

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t t^b \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} (q/t, t)$$

so we are reduced to proving the identity

$$t^b \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} (q/t, t) = t^b\phi_{ab} + q\psi_{ab}$$

the next step

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t(t^b\phi_{ab} + q\psi_{ab})$$

While my representation theoretical extension of the Haglund conjecture is

$$\partial_{p_1} \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} = (1+q)[b]_t(\phi_{ab} + t^{a-b}\psi_{ab}) + [a-b]_t t^b \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} (q/t, t)$$

so we are reduced to proving the identity

$$t^b \begin{array}{|c|} \hline \square \\ \square \\ \square \\ \square \\ \square \\ \hline \end{array} (q/t, t) = t^b\phi_{ab} + q\psi_{ab}$$

k-schur visualization of the $a=3$ $b=2$ case

k-schur visualization of the $a=3$ $b=2$ case

$$\partial_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

k-schur visualization of the $a=3$ $b=2$ case

$$\partial_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

k-schur visualization of the $a=3$ $b=2$ case

$$\partial_{p_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$\begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} = \phi_{32} + t\psi_{32}$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q\psi_{32}$$

k-schur visualization of the $a=3$ $b=2$ case

$$\partial_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

k-schur visualization of the $a=3$ $b=2$ case

$$\partial_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

Now in terms of 2-Schur we get

k-schur visualization of the $a=3$ $b=2$ case

$$\partial_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

Now in terms of 2-Schur we get

$$\phi_{32} = \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \frac{q \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} - t \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t}$$

k-schur visualization of the $a=3$ $b=2$ case

$$\partial_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

Now in terms of 2-Schur we get

$$\phi_{32} = \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \frac{q \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - t \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = A_{22} + qA_{211}$$

k-schur visualization of the $a=3$ $b=2$ case

$$\partial_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

Now in terms of 2-Schur we get

$$\phi_{32} = \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \frac{q \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - t \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = \mathbf{A}_{22} + q \mathbf{A}_{211}$$

$$\phi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \end{bmatrix}$$

k-schur visualization of the $a=3$ $b=2$ case

$$\partial_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

Now in terms of 2-Schur we get

$$\phi_{32} = \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \frac{q \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - t \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = \mathbf{A}_{22} + q \mathbf{A}_{211}$$

$$\phi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \end{bmatrix} \quad t^2 \phi_{32} = \begin{bmatrix} \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

k-schur visualization of the $a=3$ $b=2$ case

$$\partial_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

Now in terms of 2-Schur we get

$$\phi_{32} = \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \frac{q \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - t \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = \mathbf{A}_{22} + q \mathbf{A}_{211}$$

$$\psi_{32} = \frac{\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t}$$

$$\phi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \end{bmatrix} \quad t^2 \phi_{32} = \begin{bmatrix} \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

k-schur visualization of the $a=3$ $b=2$ case

$$\partial_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

Now in terms of 2-Schur we get

$$\phi_{32} = \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \frac{q \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - t \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = \mathbf{A}_{22} + q \mathbf{A}_{211}$$

$$\psi_{32} = \frac{\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = t \mathbf{A}_{211} + q \mathbf{A}_{1111}$$

$$\phi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \end{bmatrix} \quad t^2 \phi_{32} = \begin{bmatrix} \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

k-schur visualization of the $a=3$ $b=2$ case

$$\partial_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

Now in terms of 2-Schur we get

$$\phi_{32} = \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \frac{q \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - t \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = \mathbf{A}_{22} + q \mathbf{A}_{211}$$

$$\psi_{32} = \frac{\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = t \mathbf{A}_{211} + q \mathbf{A}_{1111}$$

$$\phi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \end{bmatrix} \quad t^2 \phi_{32} = \begin{bmatrix} \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ \mathbf{A}_{211} & 0 & 0 \\ 0 & \mathbf{A}_{1111} & 0 \end{bmatrix}$$

k-schur visualization of the $a=3$ $b=2$ case

$$\partial_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

Now in terms of 2-Schur we get

$$\phi_{32} = \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \frac{q \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - t \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = \mathbf{A}_{22} + q \mathbf{A}_{211}$$

$$\psi_{32} = \frac{\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = t \mathbf{A}_{211} + q \mathbf{A}_{1111}$$

$$\phi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \end{bmatrix} \quad t^2 \phi_{32} = \begin{bmatrix} \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ \mathbf{A}_{211} & 0 & 0 \\ 0 & \mathbf{A}_{1111} & 0 \end{bmatrix} \quad q \psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \mathbf{A}_{211} & 0 \\ 0 & 0 & \mathbf{A}_{1111} \end{bmatrix}$$

k-schur visualization of the $a=3$ $b=2$ case

$$\partial_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

Now in terms of 2-Schur we get

$$\phi_{32} = \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \frac{q \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - t \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = \mathbf{A}_{22} + q \mathbf{A}_{211}$$

$$\psi_{32} = \frac{\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = t \mathbf{A}_{211} + q \mathbf{A}_{1111}$$

$$\phi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \end{bmatrix} \quad t^2 \phi_{32} = \begin{bmatrix} \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ \mathbf{A}_{211} & 0 & 0 \\ 0 & \mathbf{A}_{1111} & 0 \end{bmatrix} \quad q \psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \mathbf{A}_{211} & 0 \\ 0 & 0 & \mathbf{A}_{1111} \end{bmatrix}$$

thus

k-schur visualization of the $a=3$ $b=2$ case

$$\partial_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

Now in terms of 2-Schur we get

$$\phi_{32} = \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \frac{q \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - t \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = A_{22} + qA_{211}$$

$$\psi_{32} = \frac{\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = tA_{211} + qA_{1111}$$

$$\phi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ A_{22} & A_{211} & 0 \end{bmatrix} \quad t^2 \phi_{32} = \begin{bmatrix} A_{22} & A_{211} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ A_{211} & 0 & 0 \\ 0 & A_{1111} & 0 \end{bmatrix} \quad q\psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & A_{211} & 0 \\ 0 & 0 & A_{1111} \end{bmatrix}$$

thus

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = A_{22} + qA_{211} + qtA_{211} + q^2A_{1111} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & A_{211} & 0 \\ A_{22} & A_{211} & A_{1111} \end{bmatrix}$$

k-schur visualization of the $a=3$ $b=2$ case

$$\partial_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

Now in terms of 2-Schur we get

$$\phi_{32} = \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \frac{q \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - t \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = \mathbf{A}_{22} + q \mathbf{A}_{211}$$

$$\psi_{32} = \frac{\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = t \mathbf{A}_{211} + q \mathbf{A}_{1111}$$

$$\phi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \end{bmatrix} \quad t^2 \phi_{32} = \begin{bmatrix} \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ \mathbf{A}_{211} & 0 & 0 \\ 0 & \mathbf{A}_{1111} & 0 \end{bmatrix} \quad q \psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \mathbf{A}_{211} & 0 \\ 0 & 0 & \mathbf{A}_{1111} \end{bmatrix}$$

thus

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \mathbf{A}_{22} + q \mathbf{A}_{211} + q t \mathbf{A}_{211} + q^2 \mathbf{A}_{1111} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \mathbf{A}_{211} & 0 \\ \mathbf{A}_{22} & \mathbf{A}_{211} & \mathbf{A}_{1111} \end{bmatrix}$$

and thus

k-schur visualization of the $a=3$ $b=2$ case

$$\partial_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

Now in terms of 2-Schur we get

$$\phi_{32} = \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \frac{q \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - t \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = \mathbf{A}_{22} + q \mathbf{A}_{211}$$

$$\psi_{32} = \frac{\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = t \mathbf{A}_{211} + q \mathbf{A}_{1111}$$

$$\phi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \end{bmatrix} \quad t^2 \phi_{32} = \begin{bmatrix} \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ \mathbf{A}_{211} & 0 & 0 \\ 0 & \mathbf{A}_{1111} & 0 \end{bmatrix} \quad q \psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \mathbf{A}_{211} & 0 \\ 0 & 0 & \mathbf{A}_{1111} \end{bmatrix}$$

thus

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \mathbf{A}_{22} + q \mathbf{A}_{211} + q t \mathbf{A}_{211} + q^2 \mathbf{A}_{1111} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \mathbf{A}_{211} & 0 \\ \mathbf{A}_{22} & \mathbf{A}_{211} & \mathbf{A}_{1111} \end{bmatrix}$$

and thus

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \mathbf{A}_{22} + t q \mathbf{A}_{211} + t^2 \mathbf{A}_{211} + q^2 \mathbf{A}_{1111} = \begin{bmatrix} \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \\ 0 & \mathbf{A}_{211} & 0 \\ 0 & 0 & \mathbf{A}_{1111} \end{bmatrix}$$

k-schur visualization of the $a=3$ $b=2$ case

$$\delta_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

Now in terms of 2-Schur we get

$$\phi_{32} = \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \frac{q \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} - t \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = A_{22} + qA_{211}$$

$$\psi_{32} = \frac{\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array}}{q-t} = tA_{211} + qA_{1111}$$

$$\phi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ A_{22} & A_{211} & 0 \end{bmatrix} \quad t^2 \phi_{32} = \begin{bmatrix} A_{22} & A_{211} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ A_{211} & 0 & 0 \\ 0 & A_{1111} & 0 \end{bmatrix} \quad q\psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & A_{211} & 0 \\ 0 & 0 & A_{1111} \end{bmatrix}$$

thus

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = A_{22} + qA_{211} + qtA_{211} + q^2A_{1111} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & A_{211} & 0 \\ A_{22} & A_{211} & A_{1111} \end{bmatrix}$$

and thus

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 A_{22} + tqA_{211} + t^2 A_{211} + q^2 A_{1111} = \begin{bmatrix} A_{22} & A_{211} & 0 \\ 0 & A_{211} & 0 \\ 0 & 0 & A_{1111} \end{bmatrix}$$

$$t^2 \phi_{32} + q \psi_{32}$$

k-schur visualization of the $a=3$ $b=2$ case

$$\delta_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

Now in terms of 2-Schur we get

$$\phi_{32} = \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \frac{q \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} - t \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = \mathbf{A}_{22} + q \mathbf{A}_{211}$$

$$\psi_{32} = \frac{\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array}}{q-t} = t \mathbf{A}_{211} + q \mathbf{A}_{1111}$$

$$\phi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \end{bmatrix} \quad t^2 \phi_{32} = \begin{bmatrix} \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ \mathbf{A}_{211} & 0 & 0 \\ 0 & \mathbf{A}_{1111} & 0 \end{bmatrix} \quad q \psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \mathbf{A}_{211} & 0 \\ 0 & 0 & \mathbf{A}_{1111} \end{bmatrix}$$

thus

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \mathbf{A}_{22} + q \mathbf{A}_{211} + q t \mathbf{A}_{211} + q^2 \mathbf{A}_{1111} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \mathbf{A}_{211} & 0 \\ \mathbf{A}_{22} & \mathbf{A}_{211} & \mathbf{A}_{1111} \end{bmatrix}$$

and thus

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \mathbf{A}_{22} + t q \mathbf{A}_{211} + t^2 \mathbf{A}_{211} + q^2 \mathbf{A}_{1111} = \begin{bmatrix} \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \\ 0 & \mathbf{A}_{211} & 0 \\ 0 & 0 & \mathbf{A}_{1111} \end{bmatrix}$$

$$t^2 \phi_{32} + q \psi_{32} = t^2 (\mathbf{A}_{22} + q \mathbf{A}_{211}) + q (t \mathbf{A}_{211} + q \mathbf{A}_{1111})$$

k-schur visualization of the a=3 b=2 case

$$\delta_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

Now in terms of 2-Schur we get

$$\phi_{32} = \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline \square & \square \\ \hline \end{array} = \frac{q \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} - t \begin{array}{|c|c|} \hline \square & \square \\ \hline \end{array}}{q-t} = \mathbf{A}_{22} + q \mathbf{A}_{211}$$

$$\psi_{32} = \frac{\begin{array}{|c|c|} \hline \square & \square \\ \hline \end{array} - \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array}}{q-t} = t \mathbf{A}_{211} + q \mathbf{A}_{1111}$$

$$\phi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \end{bmatrix} \quad t^2 \phi_{32} = \begin{bmatrix} \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ \mathbf{A}_{211} & 0 & 0 \\ 0 & \mathbf{A}_{1111} & 0 \end{bmatrix} \quad q \psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \mathbf{A}_{211} & 0 \\ 0 & 0 & \mathbf{A}_{1111} \end{bmatrix}$$

thus

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \end{array} = \mathbf{A}_{22} + q \mathbf{A}_{211} + q t \mathbf{A}_{211} + q^2 \mathbf{A}_{1111} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \mathbf{A}_{211} & 0 \\ \mathbf{A}_{22} & \mathbf{A}_{211} & \mathbf{A}_{1111} \end{bmatrix}$$

and thus

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \mathbf{A}_{22} + t q \mathbf{A}_{211} + t^2 \mathbf{A}_{211} + q^2 \mathbf{A}_{1111} = \begin{bmatrix} \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \\ 0 & \mathbf{A}_{211} & 0 \\ 0 & 0 & \mathbf{A}_{1111} \end{bmatrix}$$

$$t^2 \phi_{32} + q \psi_{32} = t^2 (\mathbf{A}_{22} + q \mathbf{A}_{211}) + q (t \mathbf{A}_{211} + q \mathbf{A}_{1111}) = \begin{bmatrix} \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \\ 0 & \mathbf{A}_{211} & 0 \\ 0 & 0 & \mathbf{A}_{1111} \end{bmatrix}$$

k-schur visualization of the a=3 b=2 case

$$\delta_{\mathbf{p}_1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

Now in terms of 2-Schur we get

$$\phi_{32} = \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \frac{q \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} - t \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = A_{22} + qA_{211}$$

$$\psi_{32} = \frac{\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array}}{q-t} = tA_{211} + qA_{1111}$$

$$\phi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ A_{22} & A_{211} & 0 \end{bmatrix} \quad t^2 \phi_{32} = \begin{bmatrix} A_{22} & A_{211} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ A_{211} & 0 & 0 \\ 0 & A_{1111} & 0 \end{bmatrix} \quad q\psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & A_{211} & 0 \\ 0 & 0 & A_{1111} \end{bmatrix}$$

thus

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = A_{22} + qA_{211} + qtA_{211} + q^2A_{1111} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & A_{211} & 0 \\ A_{22} & A_{211} & A_{1111} \end{bmatrix}$$

and thus

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 A_{22} + tqA_{211} + t^2 A_{211} + q^2 A_{1111} = \begin{bmatrix} A_{22} & A_{211} & 0 \\ 0 & A_{211} & 0 \\ 0 & 0 & A_{1111} \end{bmatrix}$$

$$t^2 \phi_{32} + q \psi_{32} = t^2 (A_{22} + qA_{211}) + q(tA_{211} + qA_{1111}) = \begin{bmatrix} A_{22} & A_{211} & 0 \\ 0 & A_{211} & 0 \\ 0 & 0 & A_{1111} \end{bmatrix}$$

QED !

k-schur visualization of the $a=3$ $b=2$ case

$$\delta_{\mathbf{p}^1} \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q, t) = (1+t)(1+q) \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} (q, t) + t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t)$$

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \phi_{32} + q \psi_{32}$$

$$\begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} = \phi_{32} + t \psi_{32}$$

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \phi_{32} + q \psi_{32}$$

Now in terms of 2-Schur we get

$$\phi_{32} = \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} \wedge \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \frac{q \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} - t \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array}}{q-t} = \mathbf{A}_{22} + q \mathbf{A}_{211}$$

$$\psi_{32} = \frac{\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} - \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array}}{q-t} = t \mathbf{A}_{211} + q \mathbf{A}_{1111}$$

$$\phi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \end{bmatrix} \quad t^2 \phi_{32} = \begin{bmatrix} \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ \mathbf{A}_{211} & 0 & 0 \\ 0 & \mathbf{A}_{1111} & 0 \end{bmatrix} \quad q \psi_{32} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \mathbf{A}_{211} & 0 \\ 0 & 0 & \mathbf{A}_{1111} \end{bmatrix}$$

thus

$$\begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} = \mathbf{A}_{22} + q \mathbf{A}_{211} + q t \mathbf{A}_{211} + q^2 \mathbf{A}_{1111} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \mathbf{A}_{211} & 0 \\ \mathbf{A}_{22} & \mathbf{A}_{211} & \mathbf{A}_{1111} \end{bmatrix}$$

and thus

$$t^2 \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} (q/t, t) = t^2 \mathbf{A}_{22} + t q \mathbf{A}_{211} + t^2 \mathbf{A}_{211} + q^2 \mathbf{A}_{1111} = \begin{bmatrix} \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \\ 0 & \mathbf{A}_{211} & 0 \\ 0 & 0 & \mathbf{A}_{1111} \end{bmatrix}$$

$$t^2 \phi_{32} + q \psi_{32} = t^2 (\mathbf{A}_{22} + q \mathbf{A}_{211}) + q (t \mathbf{A}_{211} + q \mathbf{A}_{1111}) = \begin{bmatrix} \mathbf{A}_{22} & \mathbf{A}_{211} & 0 \\ 0 & \mathbf{A}_{211} & 0 \\ 0 & 0 & \mathbf{A}_{1111} \end{bmatrix}$$

QED !

next

A simpler question?

A simpler question?

Count the number of permutations of S_n

A simpler question?

Count the number of permutations of S_n
whose first $n - k$ entries are increasing

A simpler question?

Count the number of permutations of S_n
whose first $n - k$ entries are increasing
and have no increasing subsequence of length greater than $n - k$

A simpler question?

Count the number of permutations of S_n
whose first $n - k$ entries are increasing
and have no increasing subsequence of length greater than $n - k$

A simpler question?

Count the number of permutations of S_n
whose first $n - k$ entries are increasing
and have no increasing subsequence of length greater than $n - k$

In symbols, we want $\#\Pi_{n,k}$ where

A simpler question?

Count the number of permutations of S_n
whose first $n - k$ entries are increasing
and have no increasing subsequence of length greater than $n - k$

In symbols, we want $\#\Pi_{n,k}$ where

$$\Pi_{n,k} = \{a = (a_1, a_2, \dots, a_n) \in S_n : a_1 < a_2 < \dots < a_{n-k} \ \& \ LI(a) = n - k\}$$

A simpler question?

Count the number of permutations of S_n
whose first $n - k$ entries are increasing
and have no increasing subsequence of length greater than $n - k$

In symbols, we want $\#\Pi_{n,k}$ where

$$\Pi_{n,k} = \{a = (a_1, a_2, \dots, a_n) \in S_n : a_1 < a_2 < \dots < a_{n-k} \ \& \ LI(a) = n - k\}$$

$LI(a)$ denotes the length of the longest increasing subsequence

A simpler question?

Count the number of permutations of S_n
whose first $n - k$ entries are increasing
and have no increasing subsequence of length greater than $n - k$

In symbols, we want $\#\Pi_{n,k}$ where

$$\Pi_{n,k} = \{a = (a_1, a_2, \dots, a_n) \in S_n : a_1 < a_2 < \dots < a_{n-k} \ \& \ LI(a) = n - k\}$$

$LI(a)$ denotes the length of the longest increasing subsequence

Let $C_{n,k}$ be a collection of “*colored permutations*” of S_n such that

A simpler question?

Count the number of permutations of S_n
whose first $n - k$ entries are increasing
and have no increasing subsequence of length greater than $n - k$

In symbols, we want $\#\Pi_{n,k}$ where

$$\Pi_{n,k} = \{a = (a_1, a_2, \dots, a_n) \in S_n : a_1 < a_2 < \dots < a_{n-k} \ \& \ LI(a) = n - k\}$$

$LI(a)$ denotes the length of the longest increasing subsequence

Let $C_{n,k}$ be a collection of “*colored permutations*” of S_n such that

- 1) each element is red or blue

A simpler question?

Count the number of permutations of S_n
whose first $n - k$ entries are increasing
and have no increasing subsequence of length greater than $n - k$

In symbols, we want $\#\Pi_{n,k}$ where

$$\Pi_{n,k} = \{a = (a_1, a_2, \dots, a_n) \in S_n : a_1 < a_2 < \dots < a_{n-k} \ \& \ LI(a) = n - k\}$$

$LI(a)$ denotes the length of the longest increasing subsequence

Let $C_{n,k}$ be a collection of “*colored permutations*” of S_n such that

- 1) each element is red or blue
- 2) the blue entries are increasing

A simpler question?

Count the number of permutations of S_n
whose first $n - k$ entries are increasing
and have no increasing subsequence of length greater than $n - k$

In symbols, we want $\#\Pi_{n,k}$ where

$$\Pi_{n,k} = \{a = (a_1, a_2, \dots, a_n) \in S_n : a_1 < a_2 < \dots < a_{n-k} \ \& \ LI(a) = n - k\}$$

$LI(a)$ denotes the length of the longest increasing subsequence

Let $C_{n,k}$ be a collection of “*colored permutations*” of S_n such that

- 1) each element is red or blue
- 2) the blue entries are increasing
- 3) only a subset of the last k entries can be red

A simpler question?

Count the number of permutations of S_n
whose first $n - k$ entries are increasing
and have no increasing subsequence of length greater than $n - k$

In symbols, we want $\#\Pi_{n,k}$ where

$$\Pi_{n,k} = \{a = (a_1, a_2, \dots, a_n) \in S_n : a_1 < a_2 < \dots < a_{n-k} \ \& \ LI(a) = n - k\}$$

$LI(a)$ denotes the length of the longest increasing subsequence

Let $C_{n,k}$ be a collection of “*colored permutations*” of S_n such that

- 1) each element is red or blue
- 2) the blue entries are increasing
- 3) only a subset of the last k entries can be red
- 4) the sign of a colored permutation is $(-1)^{\#\text{blue}}$

A simpler question?

Count the number of permutations of S_n
whose first $n - k$ entries are increasing
and have no increasing subsequence of length greater than $n - k$

In symbols, we want $\#\Pi_{n,k}$ where

$$\Pi_{n,k} = \{a = (a_1, a_2, \dots, a_n) \in S_n : a_1 < a_2 < \dots < a_{n-k} \ \& \ LI(a) = n - k\}$$

$LI(a)$ denotes the length of the longest increasing subsequence

Let $C_{n,k}$ be a collection of “*colored permutations*” of S_n such that

- 1) each element is red or blue
- 2) the blue entries are increasing
- 3) only a subset of the last k entries can be red
- 4) the sign of a colored permutation is $(-1)^{\#\text{blue}}$



A simpler question?

Count the number of permutations of S_n
whose first $n - k$ entries are increasing
and have no increasing subsequence of length greater than $n - k$

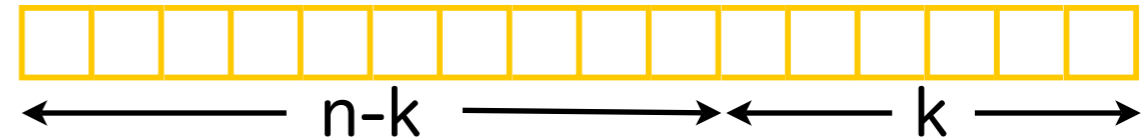
In symbols, we want $\#\Pi_{n,k}$ where

$$\Pi_{n,k} = \{a = (a_1, a_2, \dots, a_n) \in S_n : a_1 < a_2 < \dots < a_{n-k} \text{ \& LI}(a) = n - k\}$$

$LI(a)$ denotes the length of the longest increasing subsequence

Let $C_{n,k}$ be a collection of “*colored permutations*” of S_n such that

- 1) each element is red or blue
- 2) the blue entries are increasing
- 3) only a subset of the last k entries can be red
- 4) the sign of a colored permutation is $(-1)^{\#\text{blue}}$



A simpler question?

Count the number of permutations of S_n
whose first $n - k$ entries are increasing
and have no increasing subsequence of length greater than $n - k$

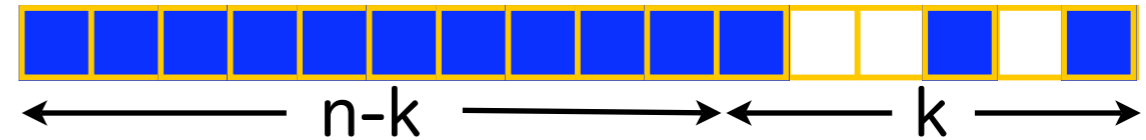
In symbols, we want $\#\Pi_{n,k}$ where

$$\Pi_{n,k} = \{a = (a_1, a_2, \dots, a_n) \in S_n : a_1 < a_2 < \dots < a_{n-k} \ \& \ LI(a) = n - k\}$$

$LI(a)$ denotes the length of the longest increasing subsequence

Let $C_{n,k}$ be a collection of “*colored permutations*” of S_n such that

- 1) each element is red or blue
- 2) the blue entries are increasing
- 3) only a subset of the last k entries can be red
- 4) the sign of a colored permutation is $(-1)^{\#\text{blue}}$



A simpler question?

Count the number of permutations of S_n
 whose first $n - k$ entries are increasing
 and have no increasing subsequence of length greater than $n - k$

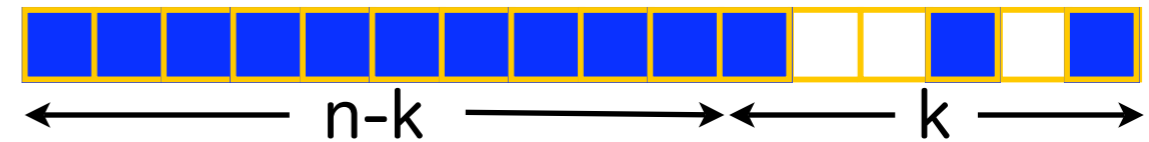
In symbols, we want $\#\Pi_{n,k}$ where

$$\Pi_{n,k} = \{a = (a_1, a_2, \dots, a_n) \in S_n : a_1 < a_2 < \dots < a_{n-k} \ \& \ LI(a) = n - k\}$$

$LI(a)$ denotes the length of the longest increasing subsequence

Let $C_{n,k}$ be a collection of “*colored permutations*” of S_n such that

- 1) each element is red or blue
- 2) the blue entries are increasing
- 3) only a subset of the last k entries can be red
- 4) the sign of a colored permutation is $(-1)^{\#\text{blue}}$



$$\sum_{a \in C_{n,k}} \text{sign}(a) = \sum_{r=0}^k \binom{k}{r} (-1)^{k-r} n(n-1) \cdots (n-r+1)$$

A simpler question?

Count the number of permutations of S_n
whose first $n - k$ entries are increasing
and have no increasing subsequence of length greater than $n - k$

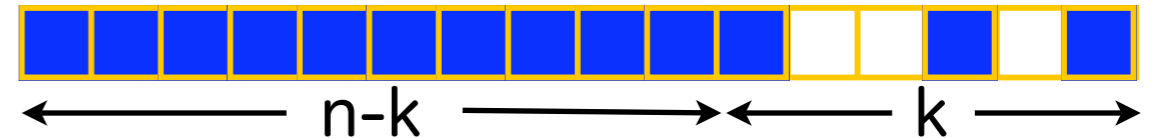
In symbols, we want $\#\Pi_{n,k}$ where

$$\Pi_{n,k} = \{a = (a_1, a_2, \dots, a_n) \in S_n : a_1 < a_2 < \dots < a_{n-k} \ \& \ LI(a) = n - k\}$$

$LI(a)$ denotes the length of the longest increasing subsequence

Let $C_{n,k}$ be a collection of “*colored permutations*” of S_n such that

- 1) each element is red or blue
- 2) the blue entries are increasing
- 3) only a subset of the last k entries can be red
- 4) the sign of a colored permutation is $(-1)^{\#\text{blue}}$



Theorem

$$\sum_{a \in C_{n,k}} \text{sign}(a) = \sum_{r=0}^k \binom{k}{r} (-1)^{k-r} n(n-1) \cdots (n-r+1)$$

A simpler question?

Count the number of permutations of S_n
whose first $n - k$ entries are increasing
and have no increasing subsequence of length greater than $n - k$

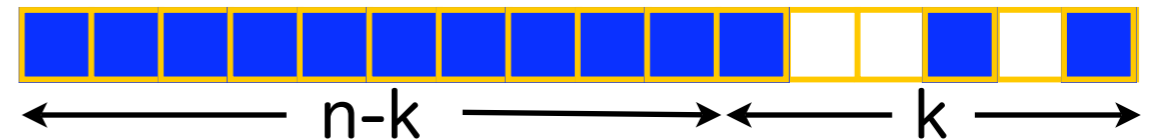
In symbols, we want $\#\Pi_{n,k}$ where

$$\Pi_{n,k} = \{a = (a_1, a_2, \dots, a_n) \in S_n : a_1 < a_2 < \dots < a_{n-k} \ \& \ LI(a) = n - k\}$$

$LI(a)$ denotes the length of the longest increasing subsequence

Let $C_{n,k}$ be a collection of “*colored permutations*” of S_n such that

- 1) each element is red or blue
- 2) the blue entries are increasing
- 3) only a subset of the last k entries can be red
- 4) the sign of a colored permutation is $(-1)^{\#\text{blue}}$



Theorem

$$\#\Pi_{n,k} = \sum_{a \in C_{n,k}} \text{sign}(a) = \sum_{r=0}^k \binom{k}{r} (-1)^{k-r} n(n-1) \cdots (n-r+1)$$

A simpler question?

Count the number of permutations of S_n
 whose first $n - k$ entries are increasing
 and have no increasing subsequence of length greater than $n - k$

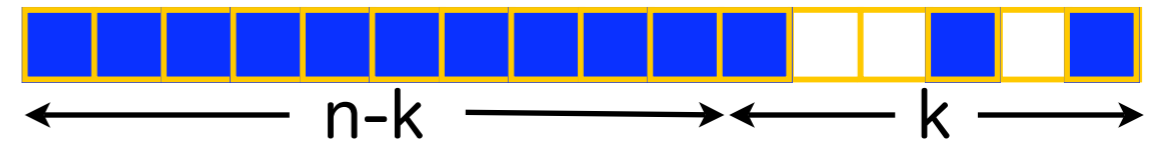
In symbols, we want $\#\Pi_{n,k}$ where

$$\Pi_{n,k} = \{a = (a_1, a_2, \dots, a_n) \in S_n : a_1 < a_2 < \dots < a_{n-k} \ \& \ LI(a) = n - k\}$$

$LI(a)$ denotes the length of the longest increasing subsequence

Let $C_{n,k}$ be a collection of “colored permutations” of S_n such that

- 1) each element is red or blue
- 2) the blue entries are increasing
- 3) only a subset of the last k entries can be red
- 4) the sign of a colored permutation is $(-1)^{\#\text{blue}}$



Theorem

$$\#\Pi_{n,k} = \sum_{a \in C_{n,k}} \text{sign}(a) = \sum_{r=0}^k \binom{k}{r} (-1)^{k-r} n(n-1) \cdots (n-r+1)$$



100\$
 Reward
 for an “elementary” proof

Do you think that was enough?

Do you think that was enough? no!

Do you think that was enough? no!

here is more

Do you think that was enough? no!

here is more

$$\sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} = \sum_{r=0}^k (-1)^{k-r} \binom{k}{r} [n]_q [n-1]_q \cdots [n-r+1]_q$$

Do you think that was enough? no!

here is more

$$\sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} = \sum_{r=0}^k (-1)^{k-r} \binom{k}{r} [n]_q [n-1]_q \cdots [n-r+1]_q$$

Proof (sketch)

Do you think that was enough? no!

here is more

$$\sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} = \sum_{r=0}^k (-1)^{k-r} \binom{k}{r} [n]_q [n-1]_q \cdots [n-r+1]_q$$

Proof (sketch)

From a theorem of Schensted it follows that

Do you think that was enough? no!

here is more

$$\sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} = \sum_{r=0}^k (-1)^{k-r} \binom{k}{r} [n]_q [n-1]_q \cdots [n-r+1]_q$$

Proof (sketch)

From a theorem of Schensted it follows that

$$\sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} = \sum_{\mu \vdash k} f_{\mu} \sum_{\mathbf{T} \in \text{ST}(n-k, \mu)} q^{\text{maj}(\mathbf{T})}$$

Do you think that was enough? no!

here is more

$$\sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} = \sum_{r=0}^k (-1)^{k-r} \binom{k}{r} [n]_q [n-1]_q \cdots [n-r+1]_q$$

Proof (sketch)

From a theorem of Schensted it follows that

$$\sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} = \sum_{\mu \vdash k} f_{\mu} \sum_{\mathbf{T} \in \text{ST}(n-k, \mu)} q^{\text{maj}(\mathbf{T})} = \sum_{\mu \vdash k} f_{\mu} \langle \mathbf{H}_n[\mathbf{X}], \mathbf{S}_{n-k, \mu} \rangle$$

Do you think that was enough? no!

here is more

$$\sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} = \sum_{r=0}^k (-1)^{k-r} \binom{k}{r} [n]_q [n-1]_q \cdots [n-r+1]_q$$

Proof (sketch)

the Frobenius Characteristic of S_n Harmonics

From a theorem of Schensted it follows that

$$\sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} = \sum_{\mu \vdash k} f_\mu \sum_{\mathbf{T} \in \text{ST}(n-k, \mu)} q^{\text{maj}(\mathbf{T})} = \sum_{\mu \vdash k} f_\mu \langle \mathbf{H}_n[\mathbf{X}], \mathbf{S}_{n-k, \mu} \rangle$$

Do you think that was enough? no!

here is more

$$\sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} = \sum_{r=0}^k (-1)^{k-r} \binom{k}{r} [n]_q [n-1]_q \cdots [n-r+1]_q$$

Proof (sketch)

the Frobenius Characteristic of S_n Harmonics

From a theorem of Schensted it follows that

$$\begin{aligned} \sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} &= \sum_{\mu \vdash k} \mathbf{f}_\mu \sum_{\mathbf{T} \in \text{ST}(n-k, \mu)} q^{\text{maj}(\mathbf{T})} = \sum_{\mu \vdash k} \mathbf{f}_\mu \langle \mathbf{H}_n[\mathbf{X}], \mathbf{S}_{n-k, \mu} \rangle \\ &= \sum_{\mu \vdash k} \mathbf{f}_\mu \langle \mathbf{H}_n[\mathbf{X}], \mathbf{V}_{n-k} \mathbf{S}_\mu \rangle \end{aligned}$$

Do you think that was enough? no!

here is more

$$\sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} = \sum_{r=0}^k (-1)^{k-r} \binom{k}{r} [n]_q [n-1]_q \cdots [n-r+1]_q$$

Proof (sketch)

the Frobenius Characteristic of S_n Harmonics

From a theorem of Schensted it follows that

$$\begin{aligned} \sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} &= \sum_{\mu \vdash k} \mathbf{f}_\mu \sum_{\mathbf{T} \in \text{ST}(n-k, \mu)} q^{\text{maj}(\mathbf{T})} = \sum_{\mu \vdash k} \mathbf{f}_\mu \langle \mathbf{H}_n[\mathbf{X}], \mathbf{S}_{n-k, \mu} \rangle \\ &= \sum_{\mu \vdash k} \mathbf{f}_\mu \langle \mathbf{H}_n[\mathbf{X}], \mathbf{V}_{n-k} \mathbf{S}_\mu \rangle \quad \text{with } \mathbf{V}_m = \sum_{s \geq 0} (-1)^s \mathbf{h}_{m+s} \mathbf{e}_s^\perp \end{aligned}$$

Do you think that was enough? no!

here is more

$$\sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} = \sum_{r=0}^k (-1)^{k-r} \binom{k}{r} [n]_q [n-1]_q \cdots [n-r+1]_q$$

Proof (sketch)

the Frobenius Characteristic of S_n Harmonics

From a theorem of Schensted it follows that

$$\begin{aligned} \sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} &= \sum_{\mu \vdash k} f_\mu \sum_{\mathbf{T} \in \text{ST}(n-k, \mu)} q^{\text{maj}(\mathbf{T})} = \sum_{\mu \vdash k} f_\mu \langle \mathbf{H}_n[\mathbf{X}], \mathbf{S}_{n-k, \mu} \rangle \\ &= \sum_{\mu \vdash k} f_\mu \langle \mathbf{H}_n[\mathbf{X}], \mathbf{V}_{n-k} \mathbf{S}_\mu \rangle \quad \text{with } \mathbf{V}_m = \sum_{s \geq 0} (-1)^s h_{m+s} \mathbf{e}_s^\perp \\ &= \langle \mathbf{H}_n[\mathbf{X}], \mathbf{V}_{n-k} \mathbf{e}_1^k \rangle \end{aligned}$$

Do you think that was enough? no!

here is more

$$\sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} = \sum_{r=0}^k (-1)^{k-r} \binom{k}{r} [n]_q [n-1]_q \cdots [n-r+1]_q$$

Proof (sketch)

the Frobenius Characteristic of S_n Harmonics

From a theorem of Schensted it follows that

$$\begin{aligned} \sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} &= \sum_{\mu \vdash k} f_\mu \sum_{\mathbf{T} \in \text{ST}(n-k, \mu)} q^{\text{maj}(\mathbf{T})} = \sum_{\mu \vdash k} f_\mu \langle \mathbf{H}_n[\mathbf{X}], \mathbf{S}_{n-k, \mu} \rangle \\ &= \sum_{\mu \vdash k} f_\mu \langle \mathbf{H}_n[\mathbf{X}], \mathbf{V}_{n-k} \mathbf{S}_\mu \rangle \quad \text{with } \mathbf{V}_m = \sum_{s \geq 0} (-1)^s h_{m+s} \mathbf{e}_s^\perp \\ &= \langle \mathbf{H}_n[\mathbf{X}], \mathbf{V}_{n-k} \mathbf{e}_1^k \rangle = \sum_{s \geq 0} (-1)^s \binom{k}{s} \langle \mathbf{H}_n[\mathbf{X}], h_{n-k+s} \mathbf{e}_1^{k-s} \rangle \end{aligned}$$

Do you think that was enough? no!

here is more

$$\sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} = \sum_{r=0}^k (-1)^{k-r} \binom{k}{r} [n]_q [n-1]_q \cdots [n-r+1]_q \quad (*)$$

Proof (sketch)

the Frobenius Characteristic of S_n Harmonics

From a theorem of Schensted it follows that

$$\begin{aligned} \sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} &= \sum_{\mu \vdash k} f_\mu \sum_{\mathbf{T} \in \text{ST}(n-k, \mu)} q^{\text{maj}(\mathbf{T})} = \sum_{\mu \vdash k} f_\mu \langle \mathbf{H}_n[\mathbf{X}], \mathbf{S}_{n-k, \mu} \rangle \\ &= \sum_{\mu \vdash k} f_\mu \langle \mathbf{H}_n[\mathbf{X}], \mathbf{V}_{n-k} \mathbf{S}_\mu \rangle \quad \text{with } \mathbf{V}_m = \sum_{s \geq 0} (-1)^s \mathbf{h}_{m+s} \mathbf{e}_s^\perp \\ &= \langle \mathbf{H}_n[\mathbf{X}], \mathbf{V}_{n-k} \mathbf{e}_1^k \rangle = \sum_{s \geq 0} (-1)^s \binom{k}{s} \langle \mathbf{H}_n[\mathbf{X}], \mathbf{h}_{n-k+s} \mathbf{e}_1^{k-s} \rangle \end{aligned}$$

and (*) follows easily from this

Do you think that was enough? no!

here is more

$$\sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} = \sum_{r=0}^k (-1)^{k-r} \binom{k}{r} [n]_q [n-1]_q \cdots [n-r+1]_q \quad (*)$$

Proof (sketch)

the Frobenius Characteristic of S_n Harmonics

From a theorem of Schensted it follows that

$$\begin{aligned} \sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} &= \sum_{\mu \vdash k} f_\mu \sum_{\mathbf{T} \in \text{ST}(n-k, \mu)} q^{\text{maj}(\mathbf{T})} = \sum_{\mu \vdash k} f_\mu \langle \mathbf{H}_n[\mathbf{X}], \mathbf{S}_{n-k, \mu} \rangle \\ &= \sum_{\mu \vdash k} f_\mu \langle \mathbf{H}_n[\mathbf{X}], \mathbf{V}_{n-k} \mathbf{S}_\mu \rangle \quad \text{with } \mathbf{V}_m = \sum_{s \geq 0} (-1)^s h_{m+s} \mathbf{e}_s^\perp \\ &= \langle \mathbf{H}_n[\mathbf{X}], \mathbf{V}_{n-k} \mathbf{e}_1^k \rangle = \sum_{s \geq 0} (-1)^s \binom{k}{s} \langle \mathbf{H}_n[\mathbf{X}], h_{n-k+s} \mathbf{e}_1^{k-s} \rangle \end{aligned}$$

and (*) follows easily from this

Problem: Get a Combinatorial interpretation when $H_n[\mathbf{X}]$ is replaced by one of our Macdonald polynomials

Do you think that was enough? no!

here is more

$$\sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} = \sum_{r=0}^k (-1)^{k-r} \binom{k}{r} [n]_q [n-1]_q \cdots [n-r+1]_q \quad (*)$$

Proof (sketch)

the Frobenius Characteristic of S_n Harmonics

From a theorem of Schensted it follows that

$$\begin{aligned} \sum_{\mathbf{a} \in \Pi_{n,k}} q^{\text{maj}(\mathbf{a}^{-1})} &= \sum_{\mu \vdash k} f_\mu \sum_{\mathbf{T} \in \text{ST}(n-k, \mu)} q^{\text{maj}(\mathbf{T})} = \sum_{\mu \vdash k} f_\mu \langle \mathbf{H}_n[\mathbf{X}], \mathbf{S}_{n-k, \mu} \rangle \\ &= \sum_{\mu \vdash k} f_\mu \langle \mathbf{H}_n[\mathbf{X}], \mathbf{V}_{n-k} \mathbf{S}_\mu \rangle \quad \text{with } \mathbf{V}_m = \sum_{s \geq 0} (-1)^s \mathbf{h}_{m+s} \mathbf{e}_s^\perp \\ &= \langle \mathbf{H}_n[\mathbf{X}], \mathbf{V}_{n-k} \mathbf{e}_1^k \rangle = \sum_{s \geq 0} (-1)^s \binom{k}{s} \langle \mathbf{H}_n[\mathbf{X}], \mathbf{h}_{n-k+s} \mathbf{e}_1^{k-s} \rangle \end{aligned}$$

and (*) follows easily from this

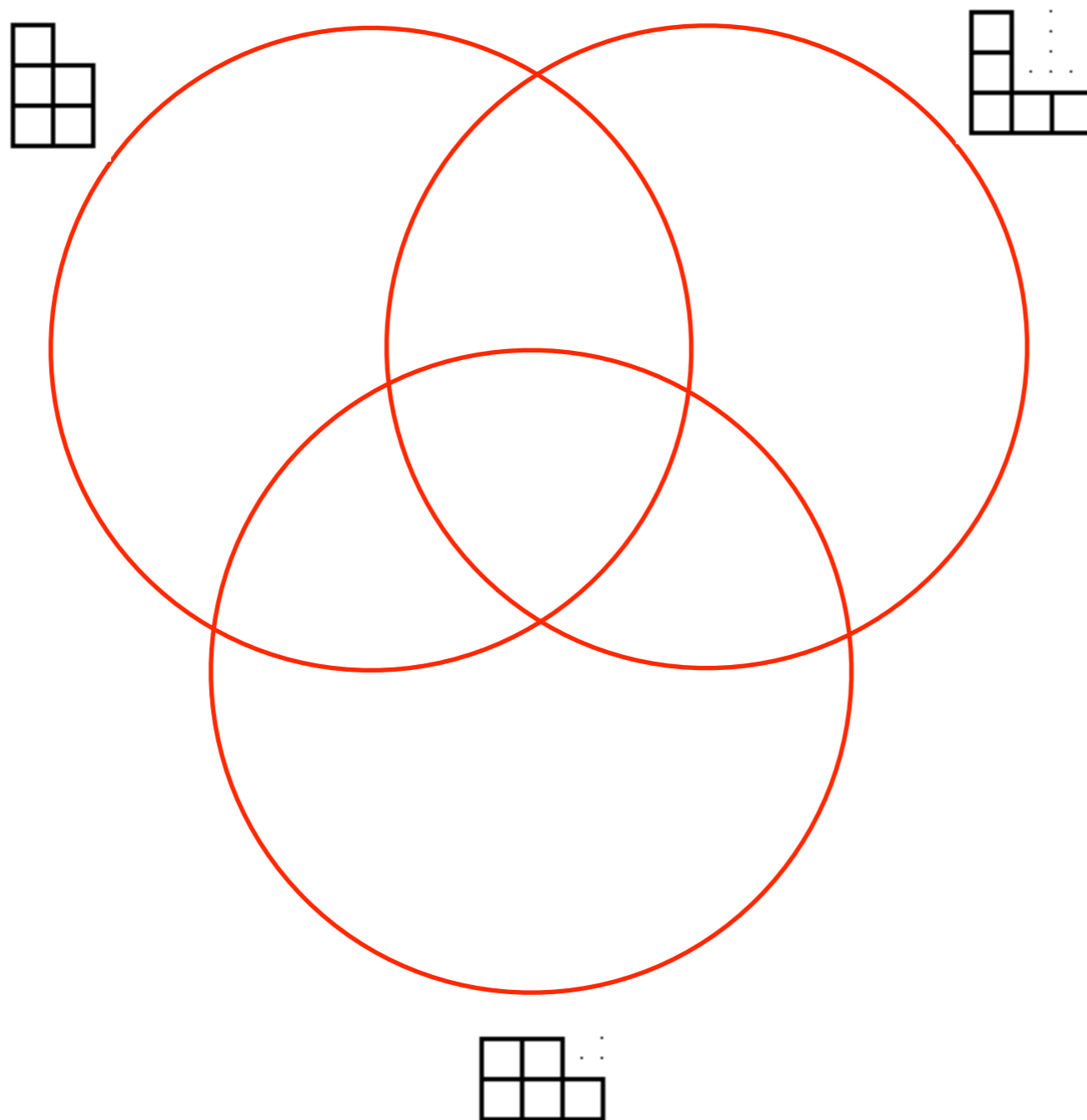
Problem: Get a Combinatorial interpretation when $\mathbf{H}_n[\mathbf{X}]$ is replaced by one of our Macdonald polynomials

next

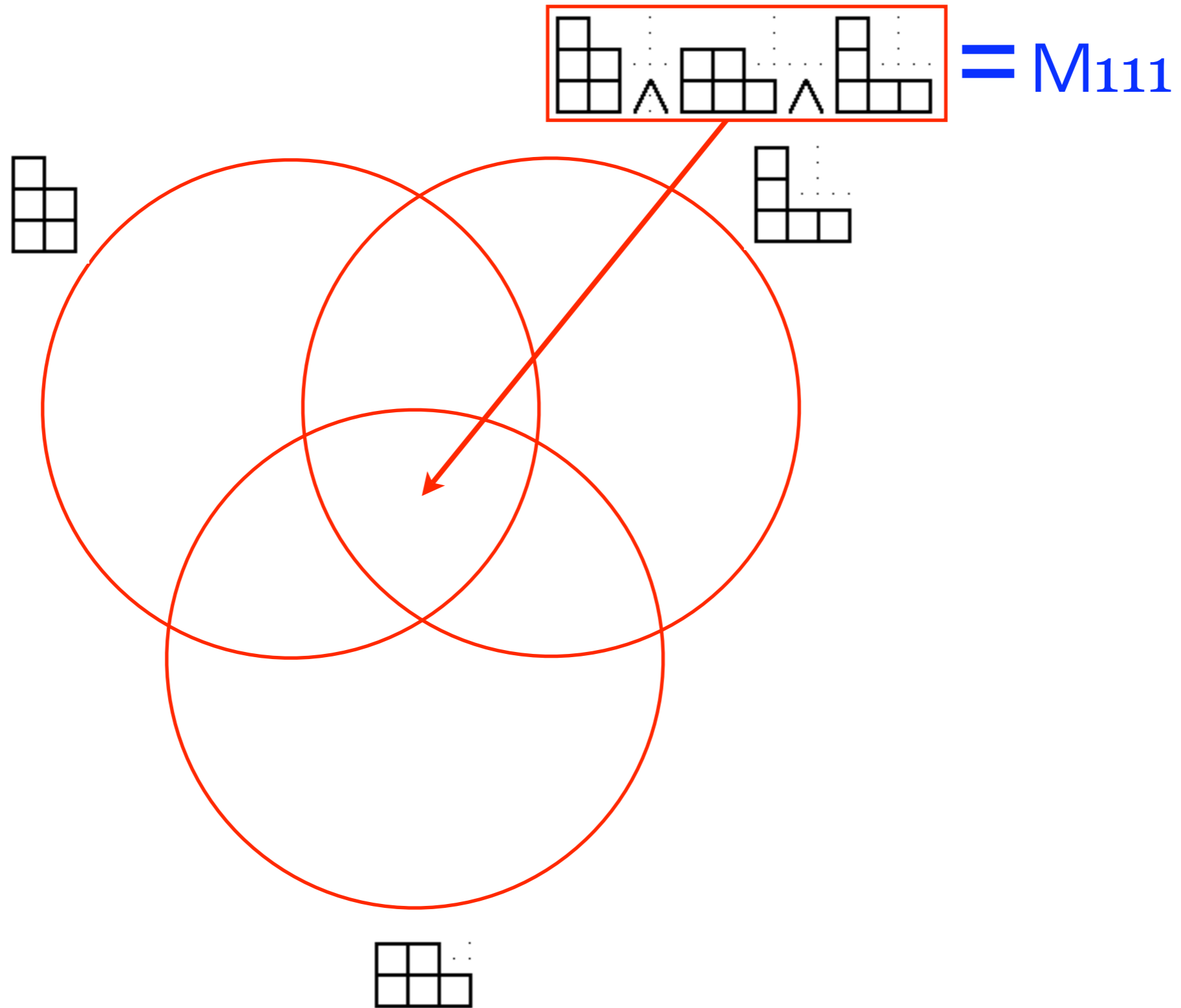
THE END

More miracles

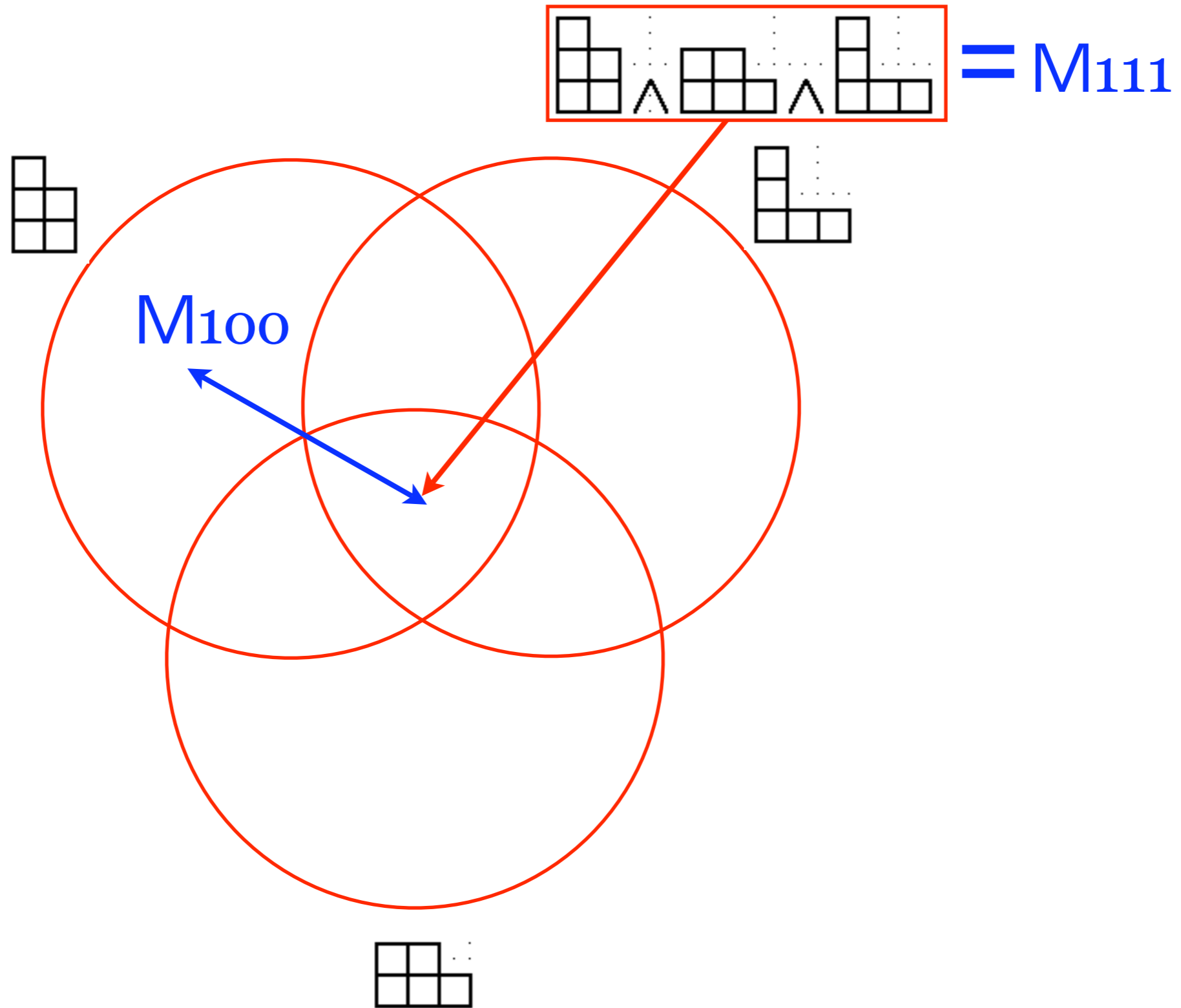
More miracles



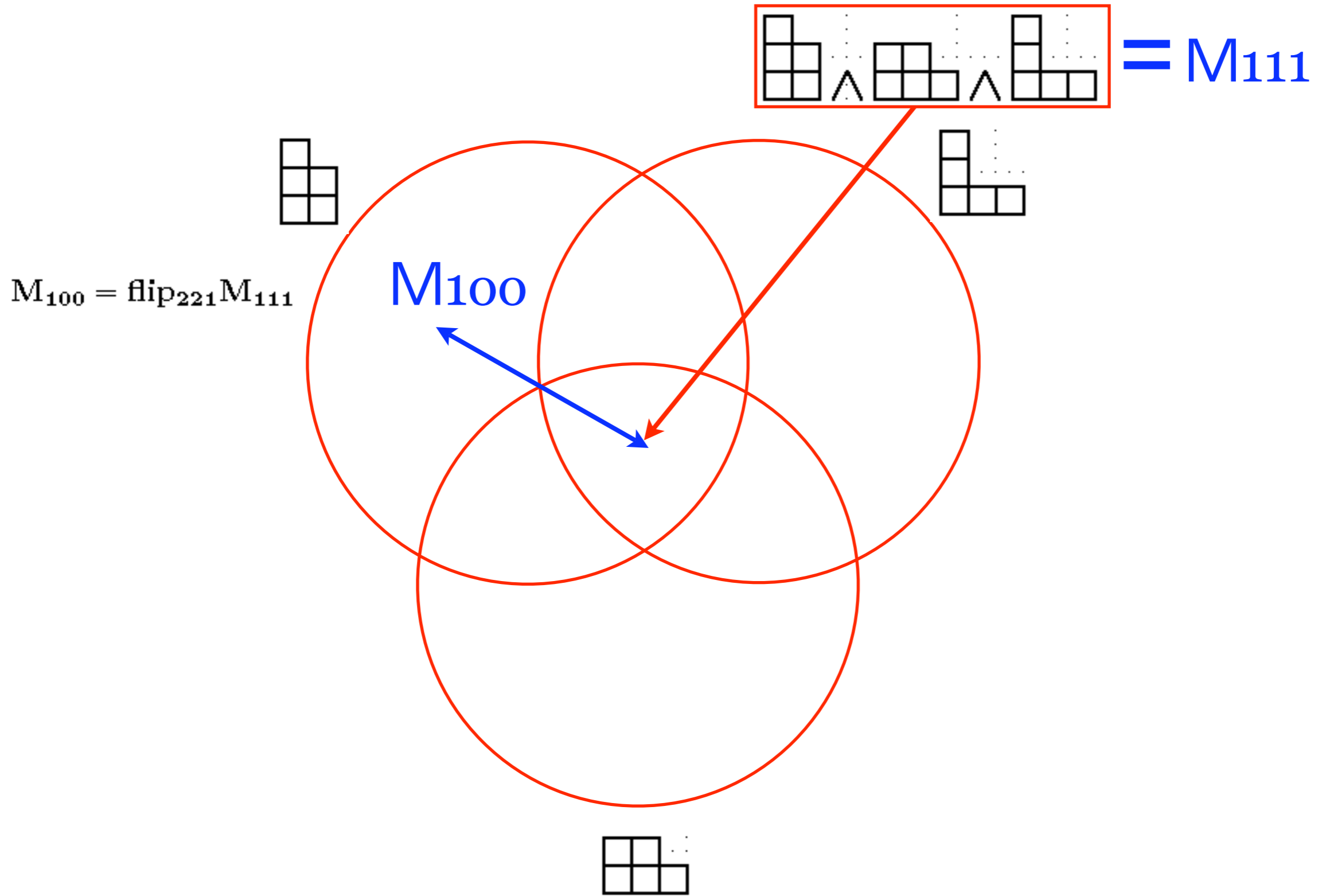
More miracles



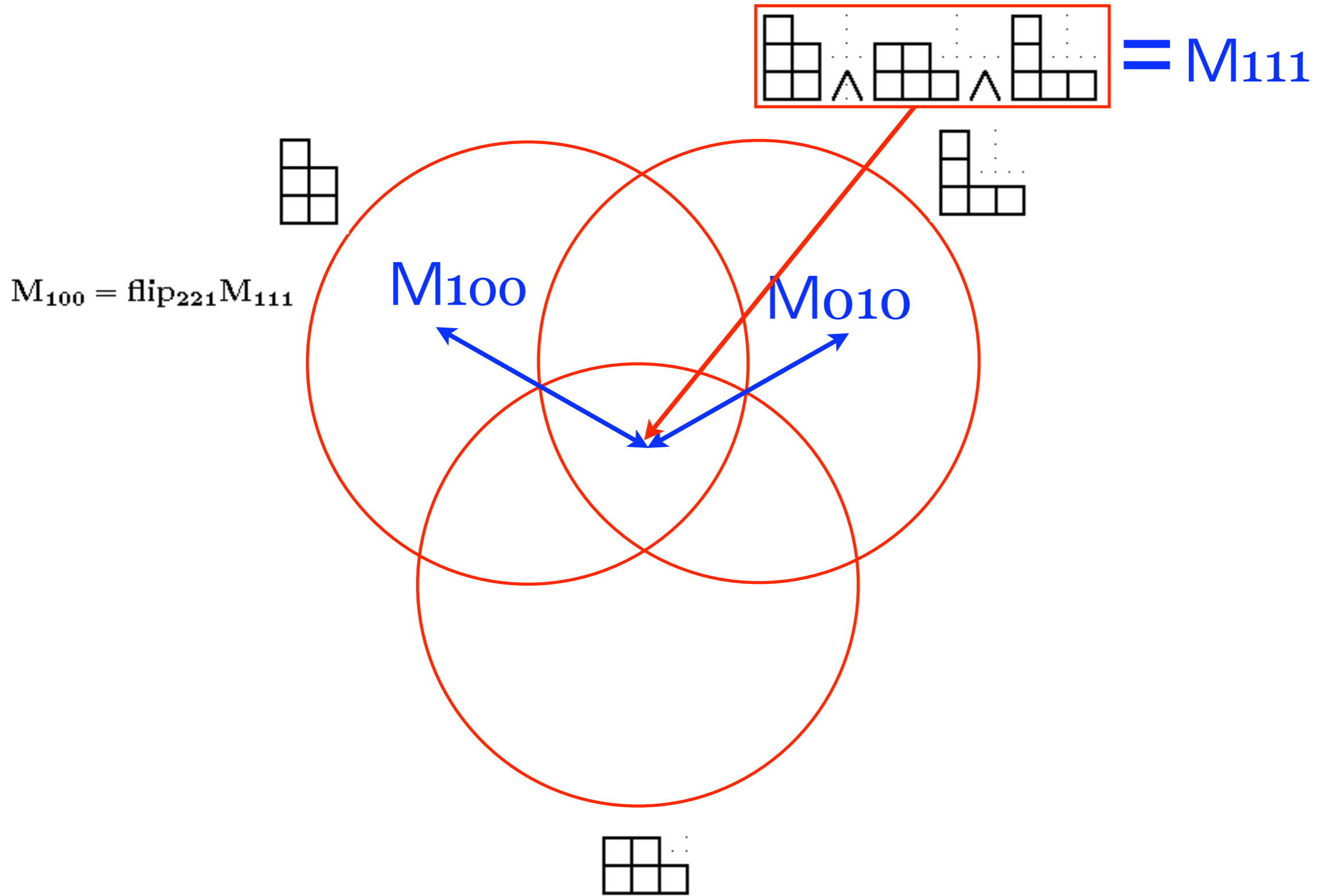
More miracles



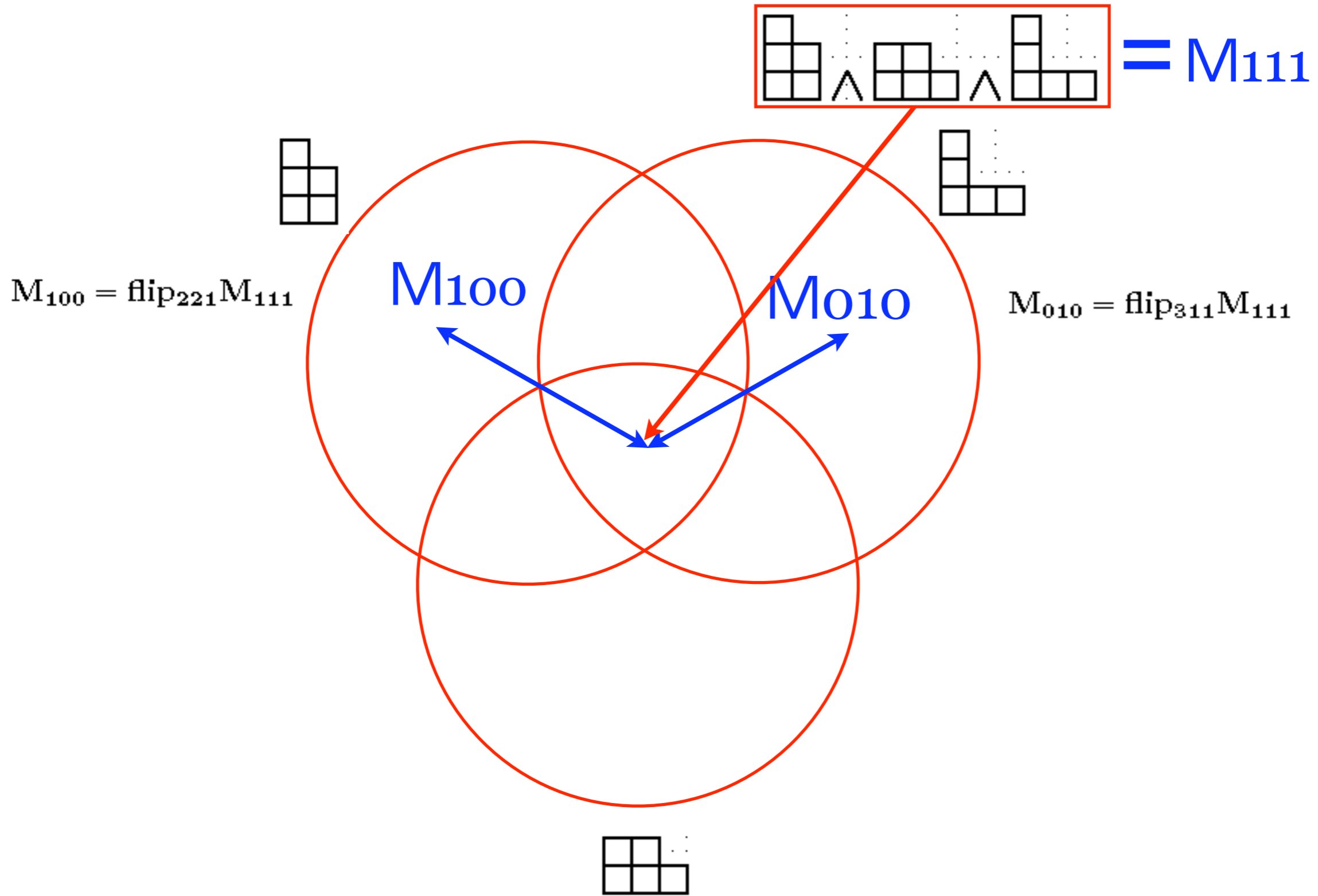
More miracles



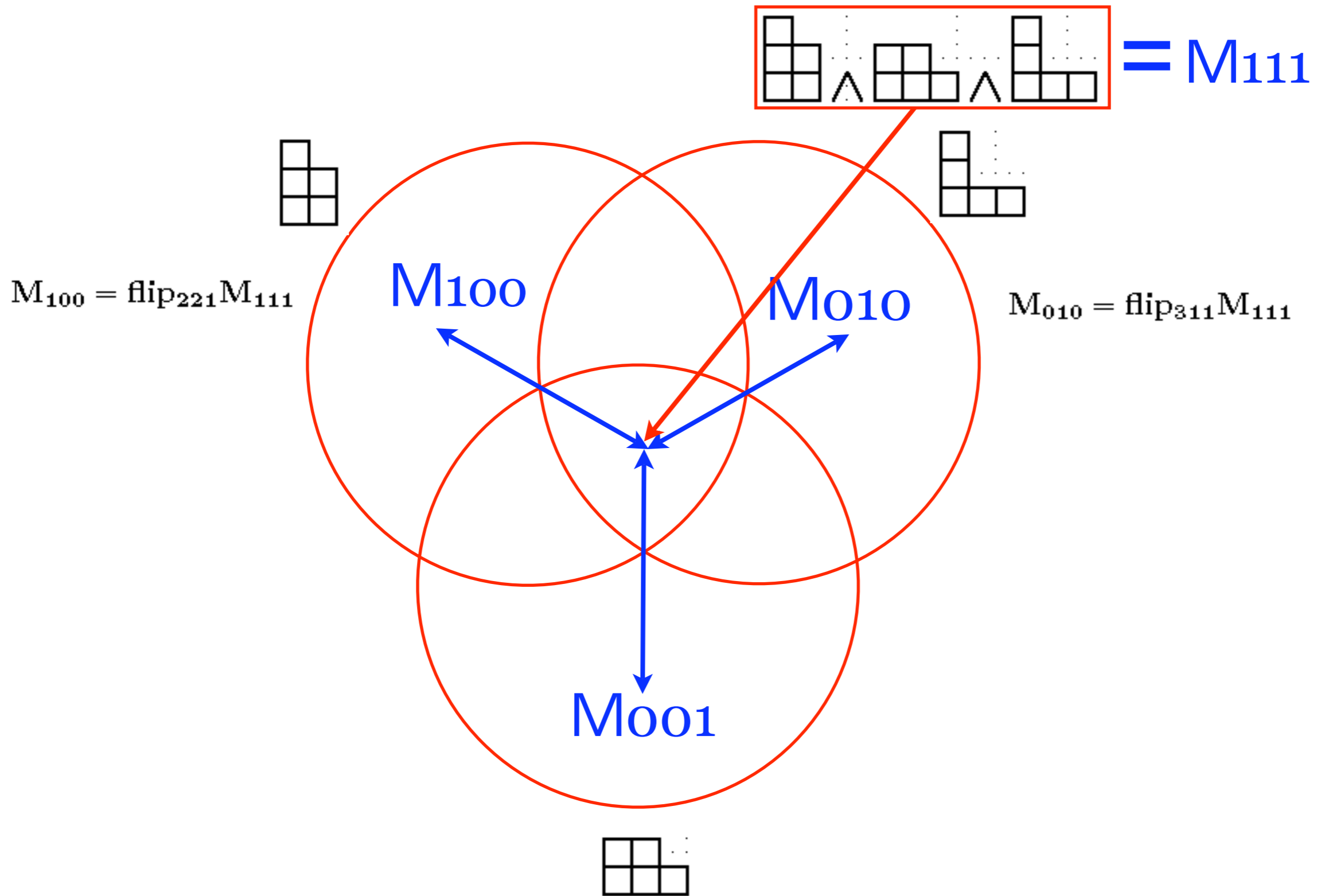
More miracles



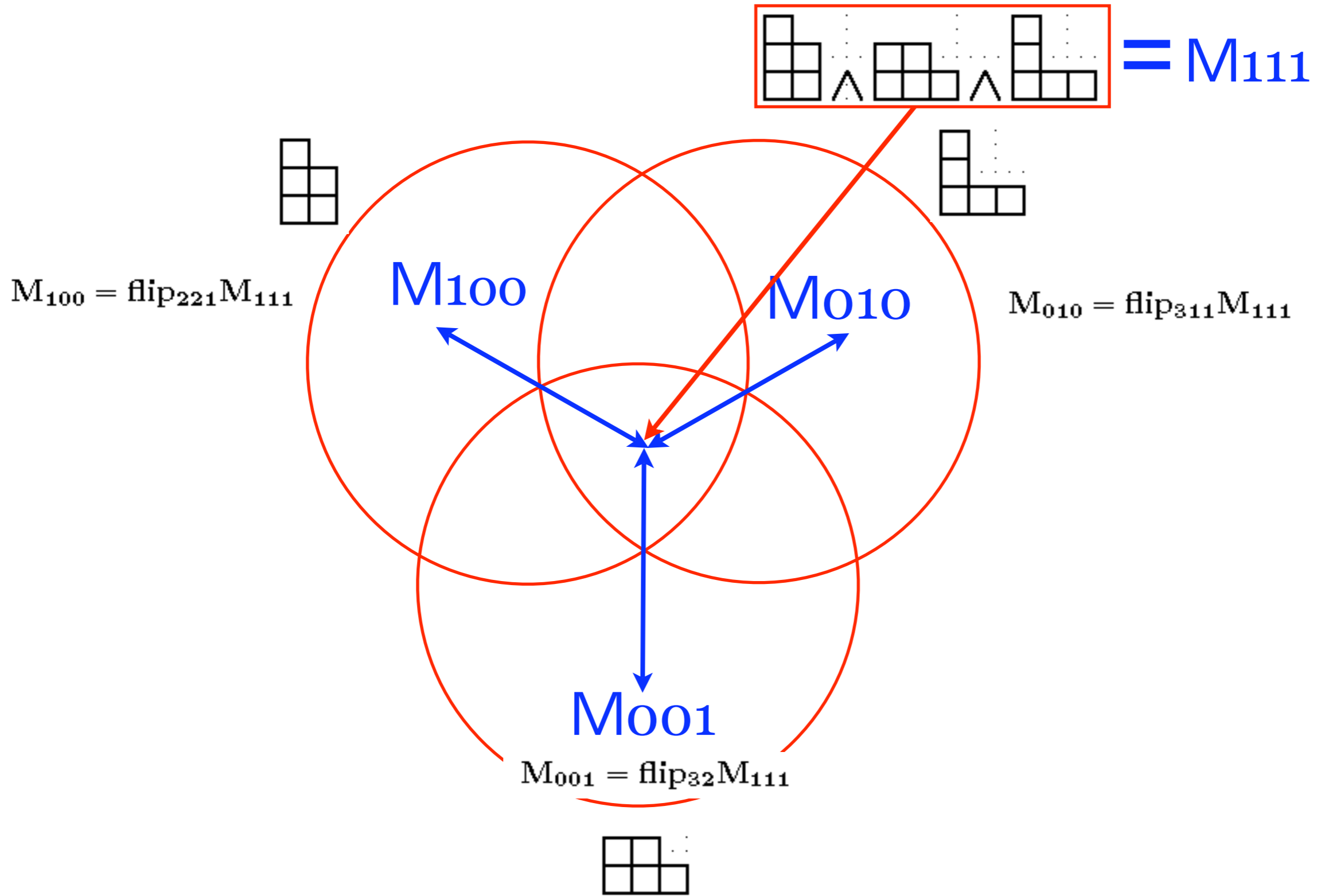
More miracles



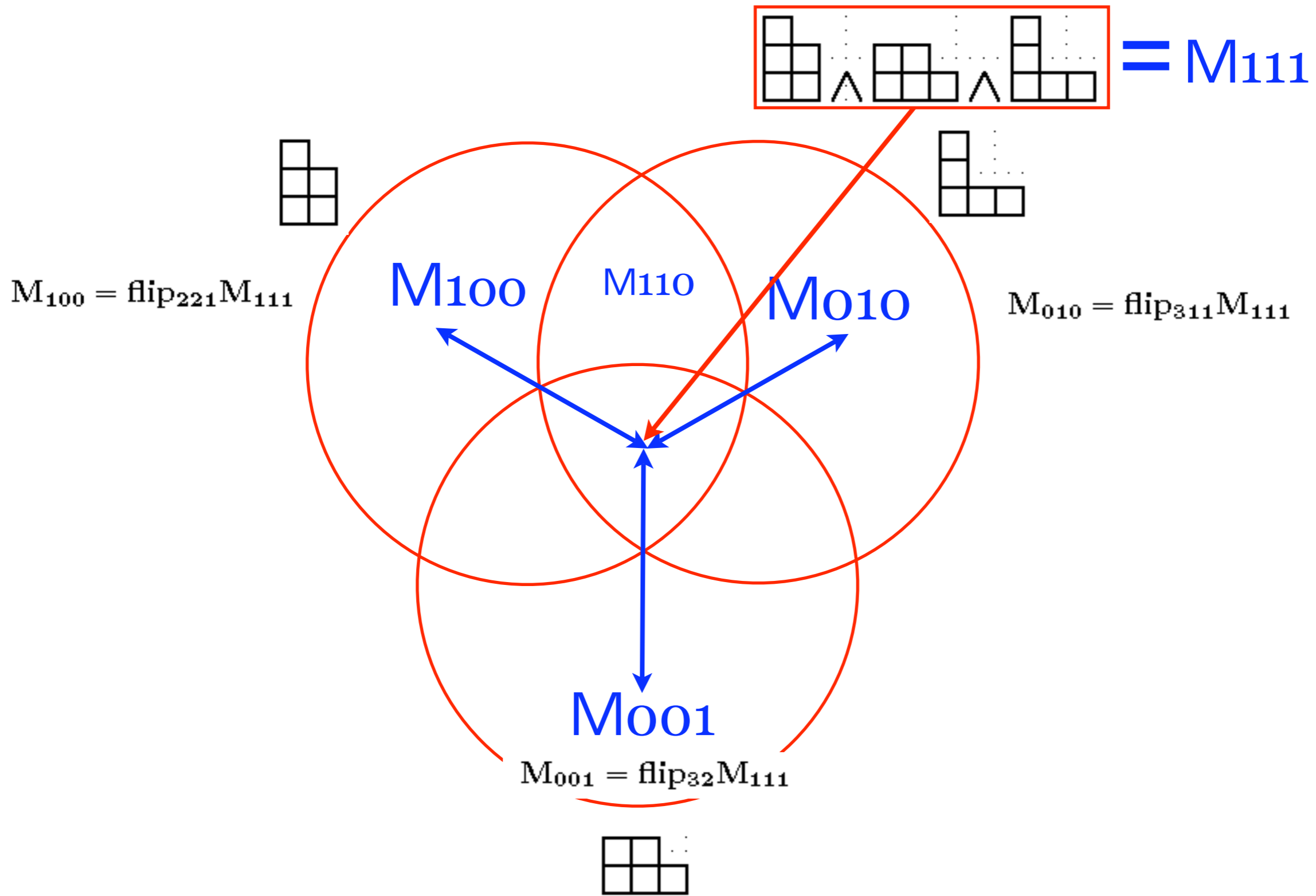
More miracles



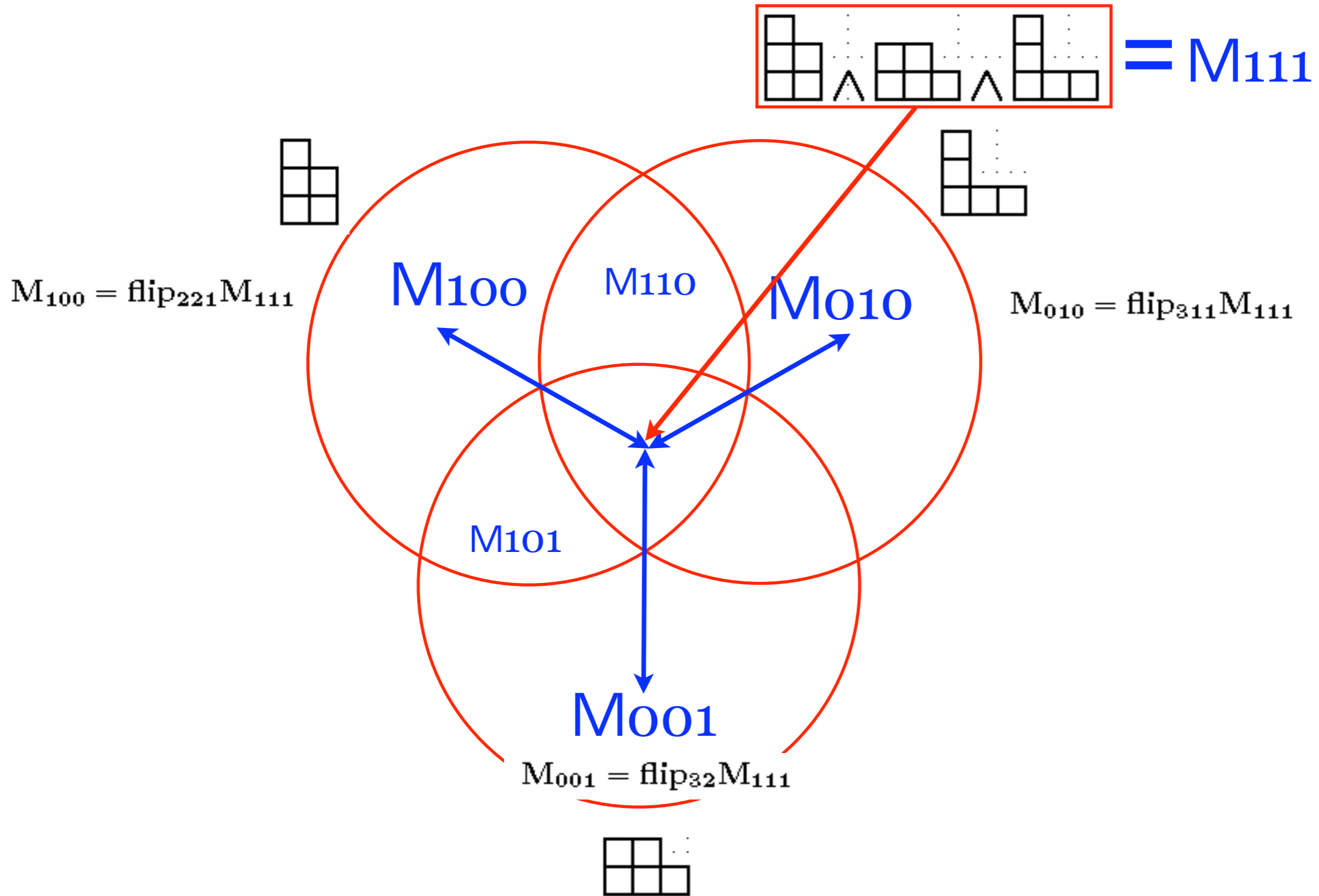
More miracles



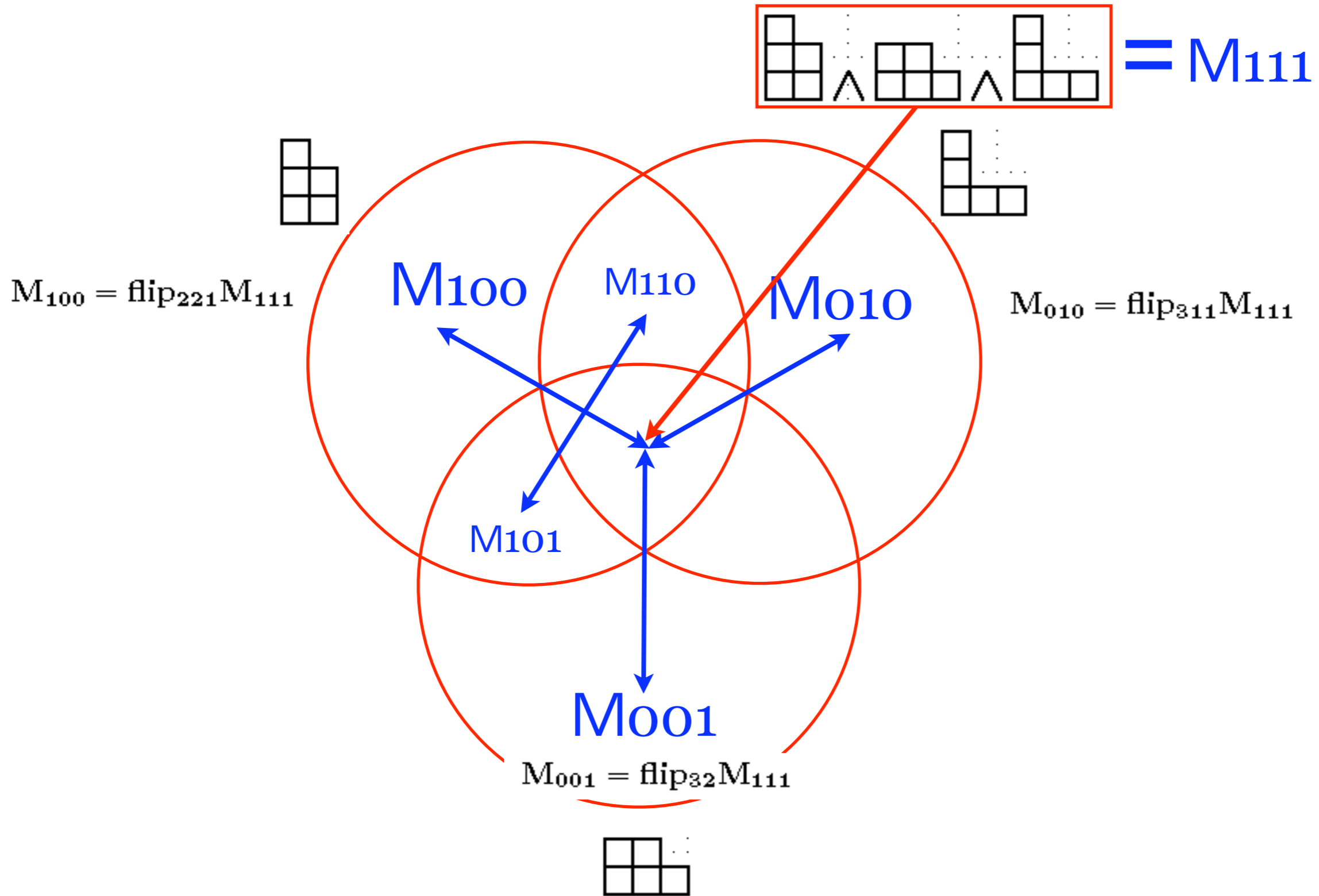
More miracles



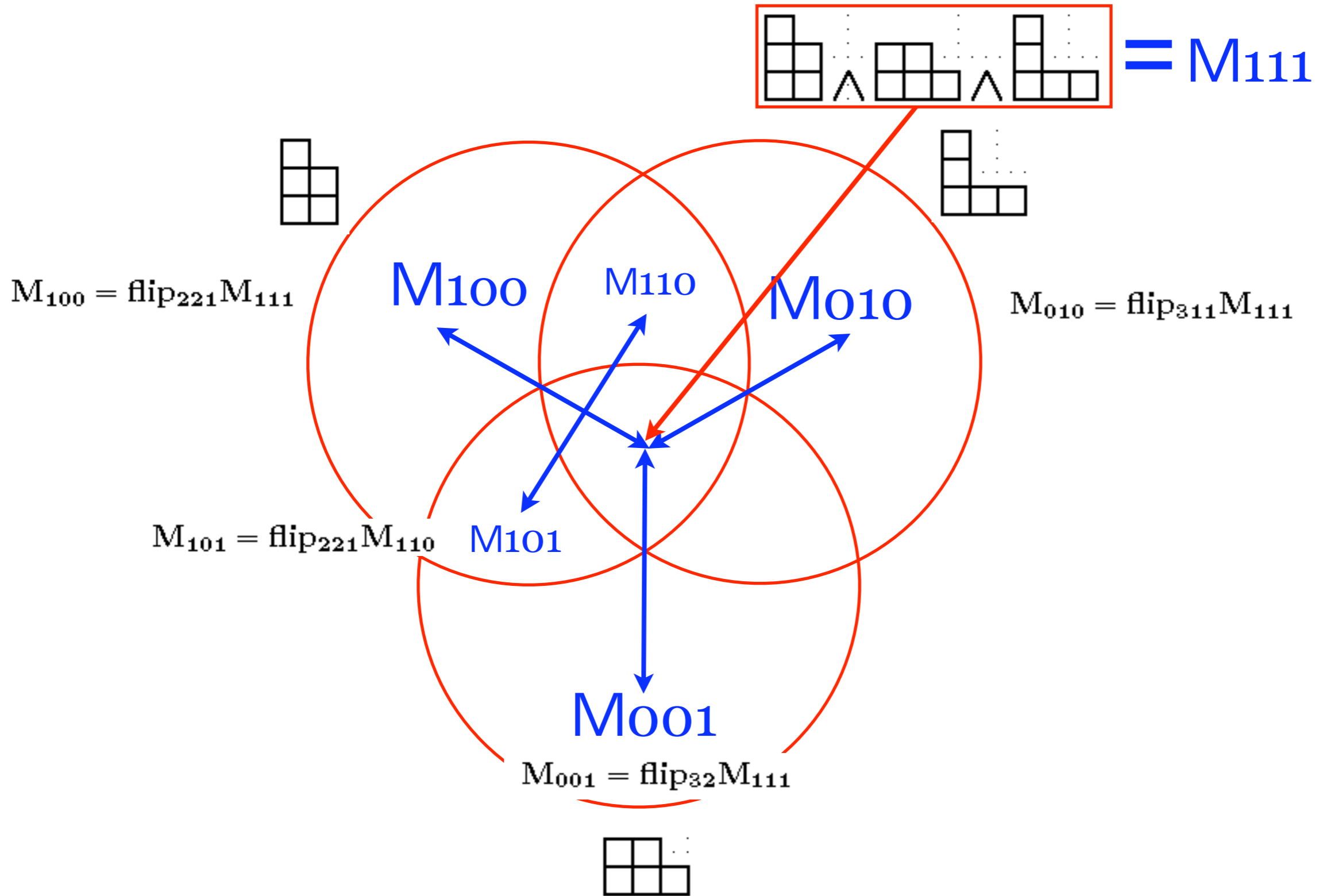
More miracles



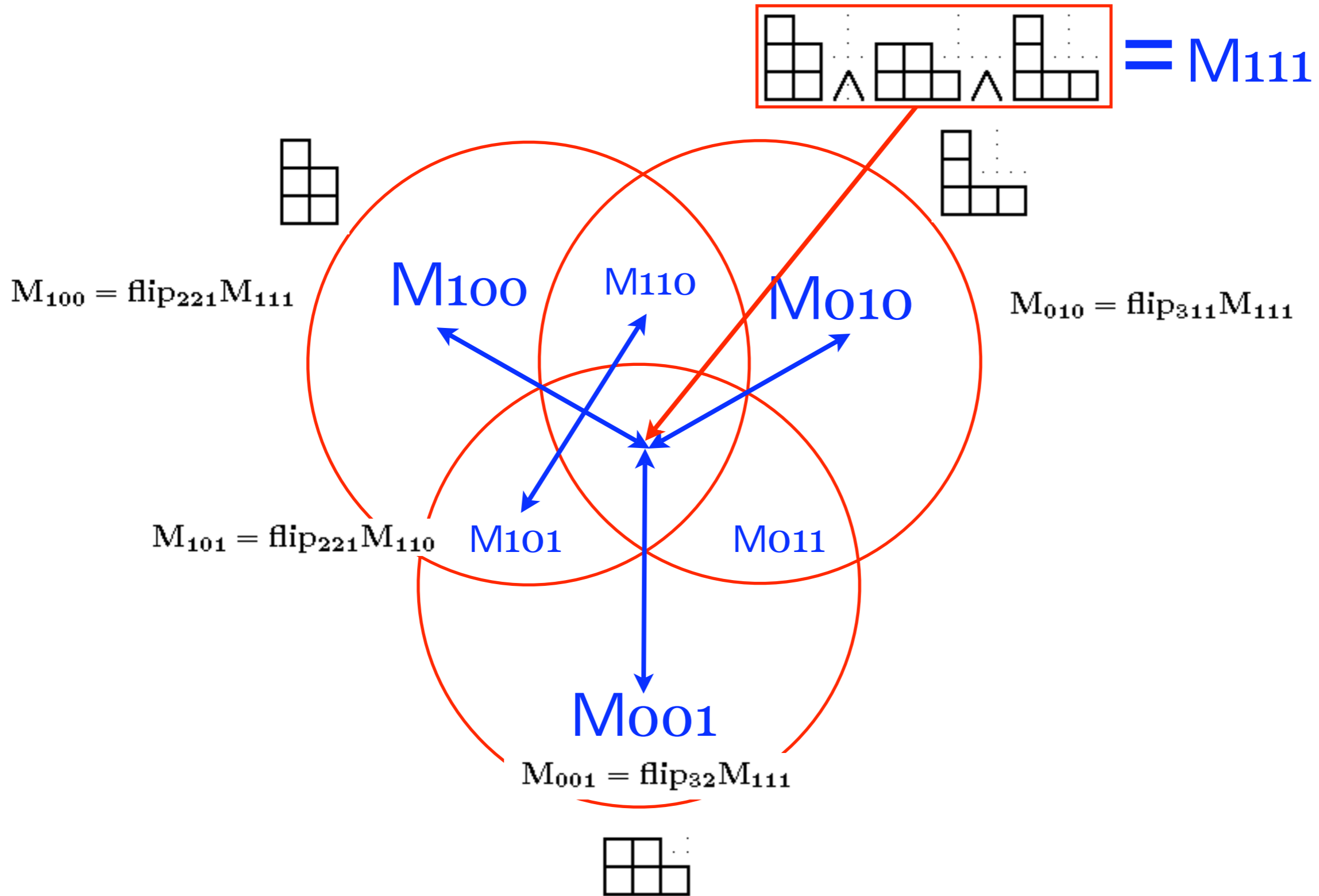
More miracles



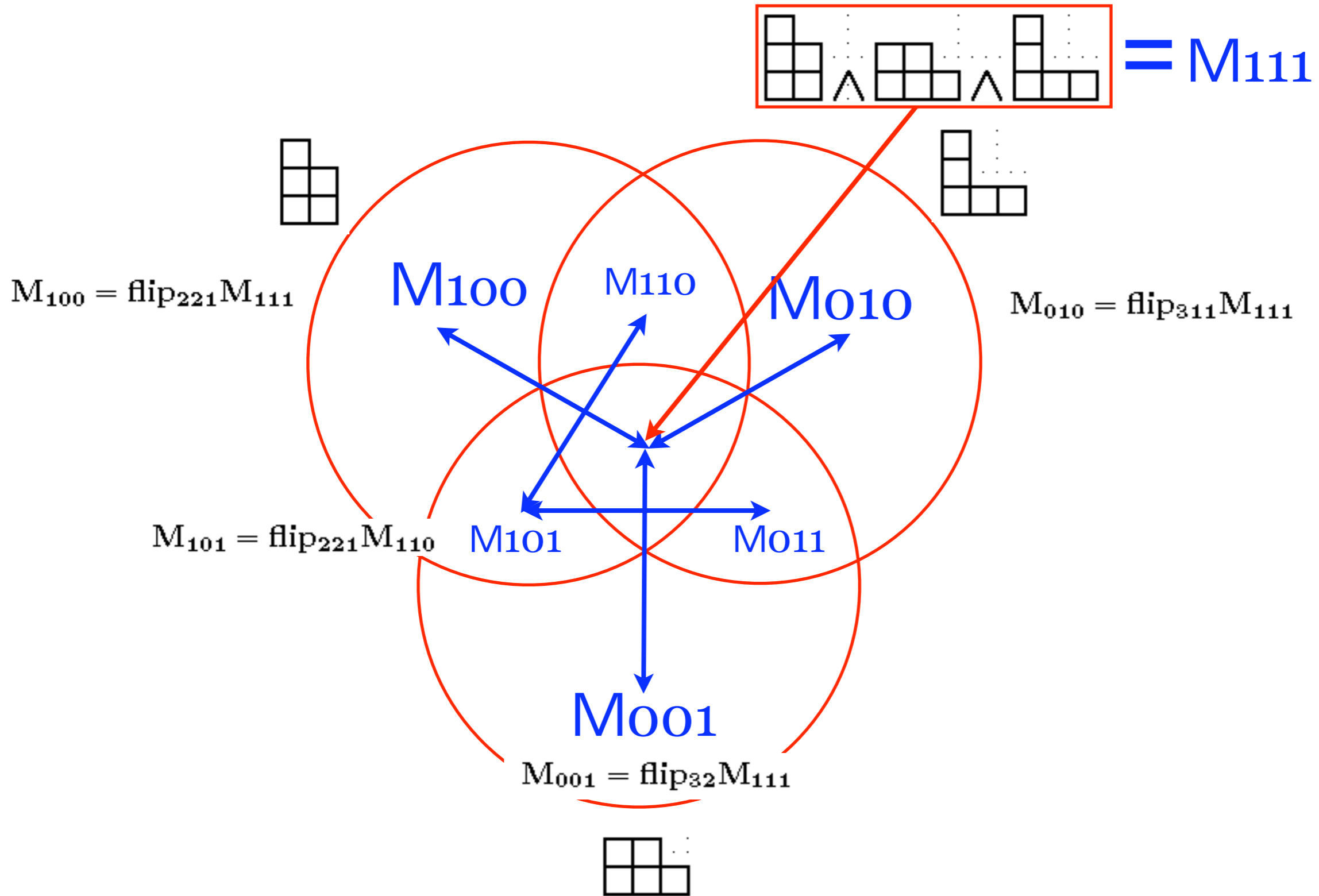
More miracles



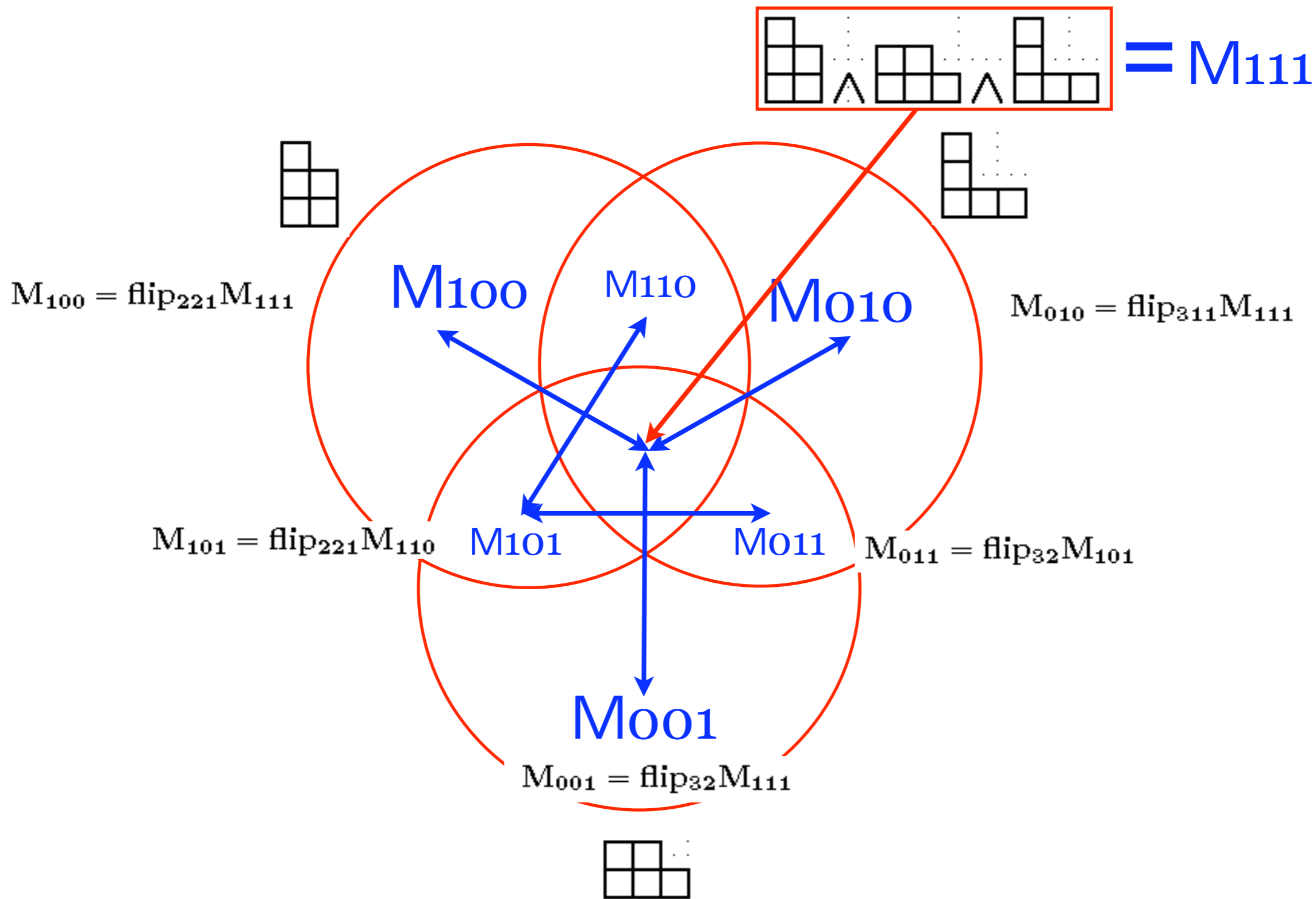
More miracles



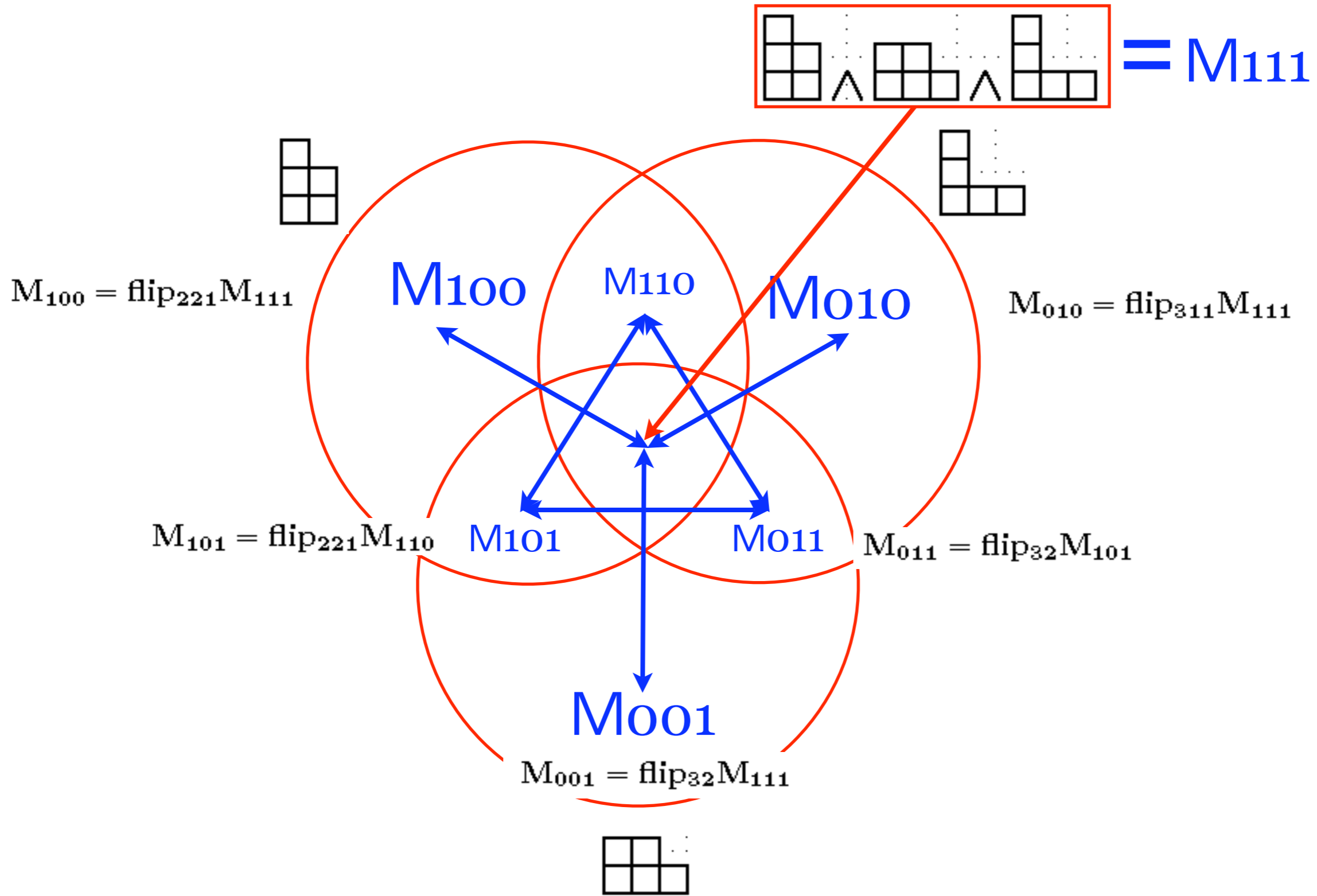
More miracles



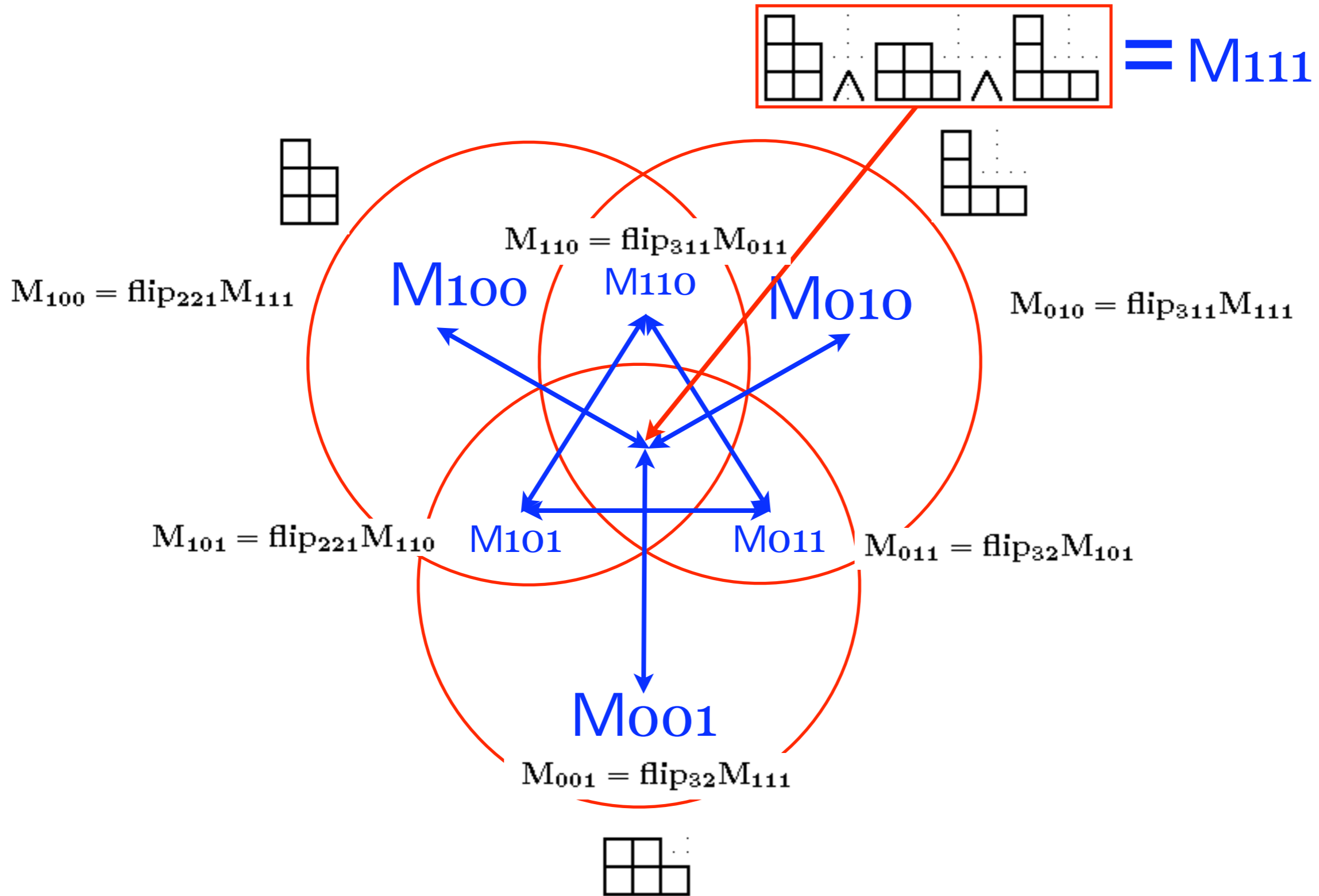
More miracles



More miracles

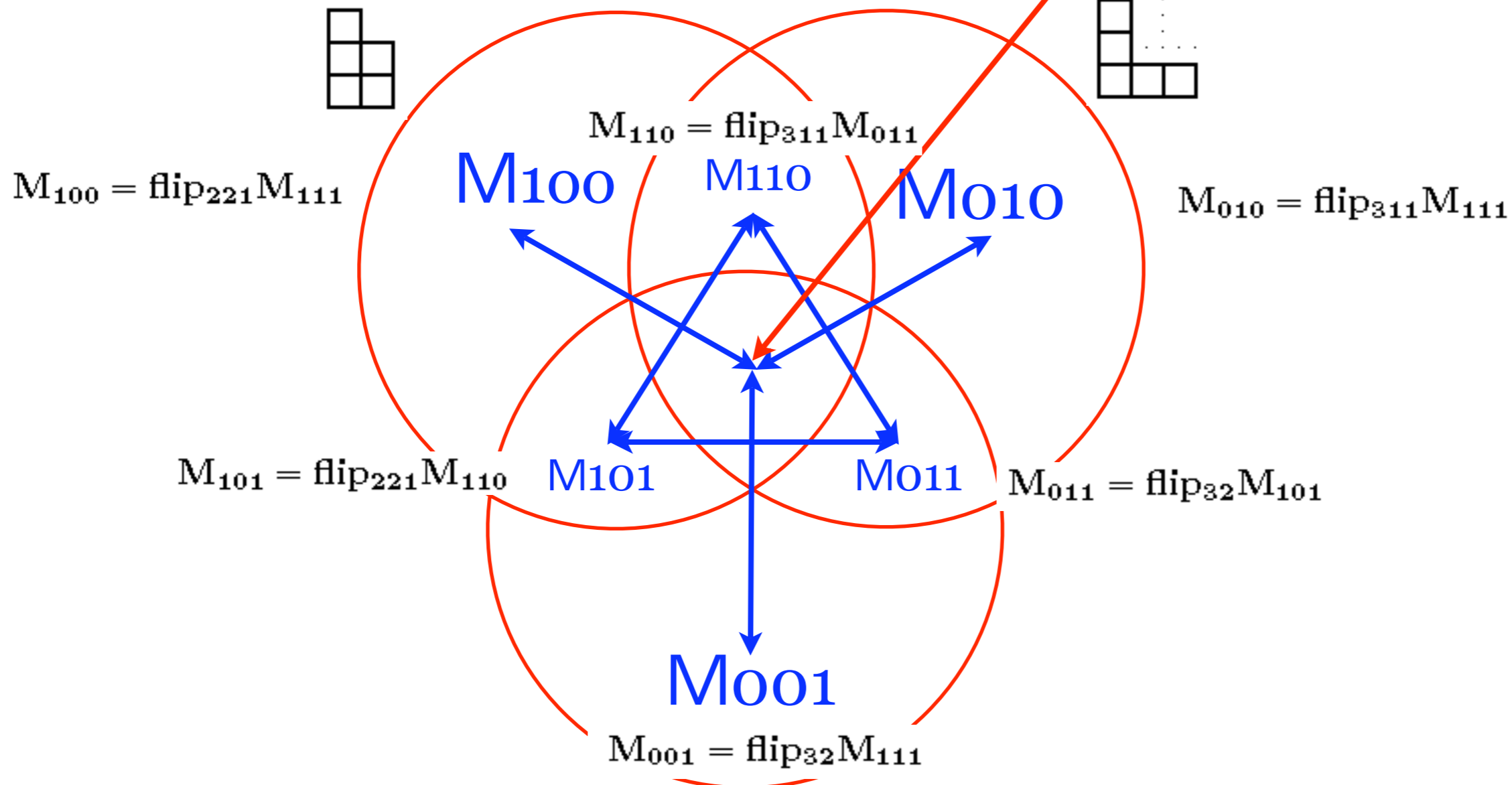


More miracles



More miracles

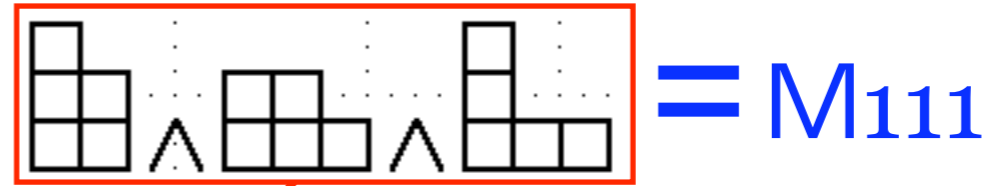
$$\begin{array}{|c|c|c|} \hline \square & \dots & \square \\ \hline \square & \wedge & \square \\ \hline \square & \wedge & \square \\ \hline \end{array} = M_{111}$$



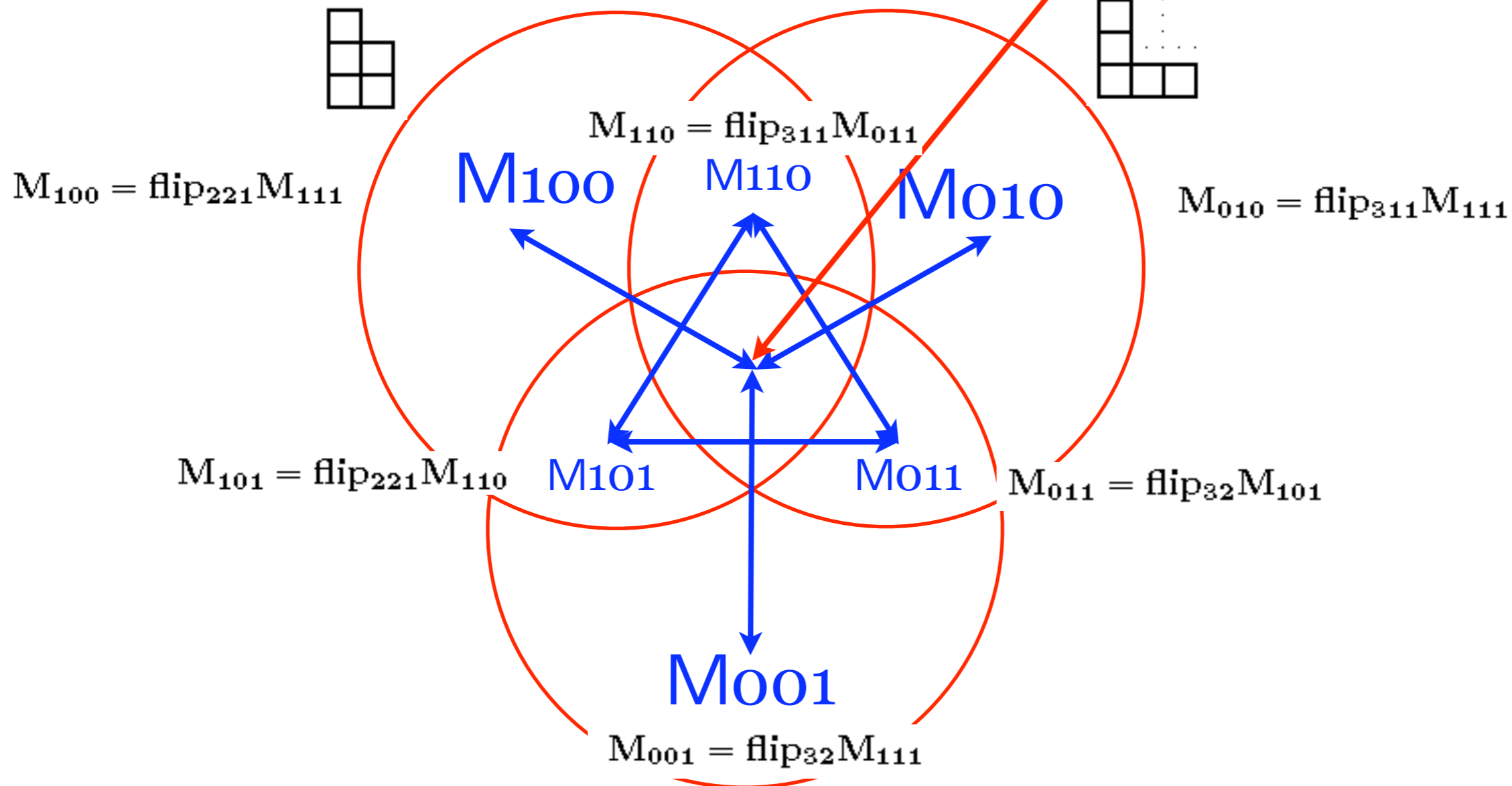
$\frac{n!}{k!}$ Conjecture



More miracles



$$\boxed{\begin{array}{ccc} \square & \dots & \square \\ \square & \dots & \square \\ \square & \dots & \square \end{array}} = M_{111}$$



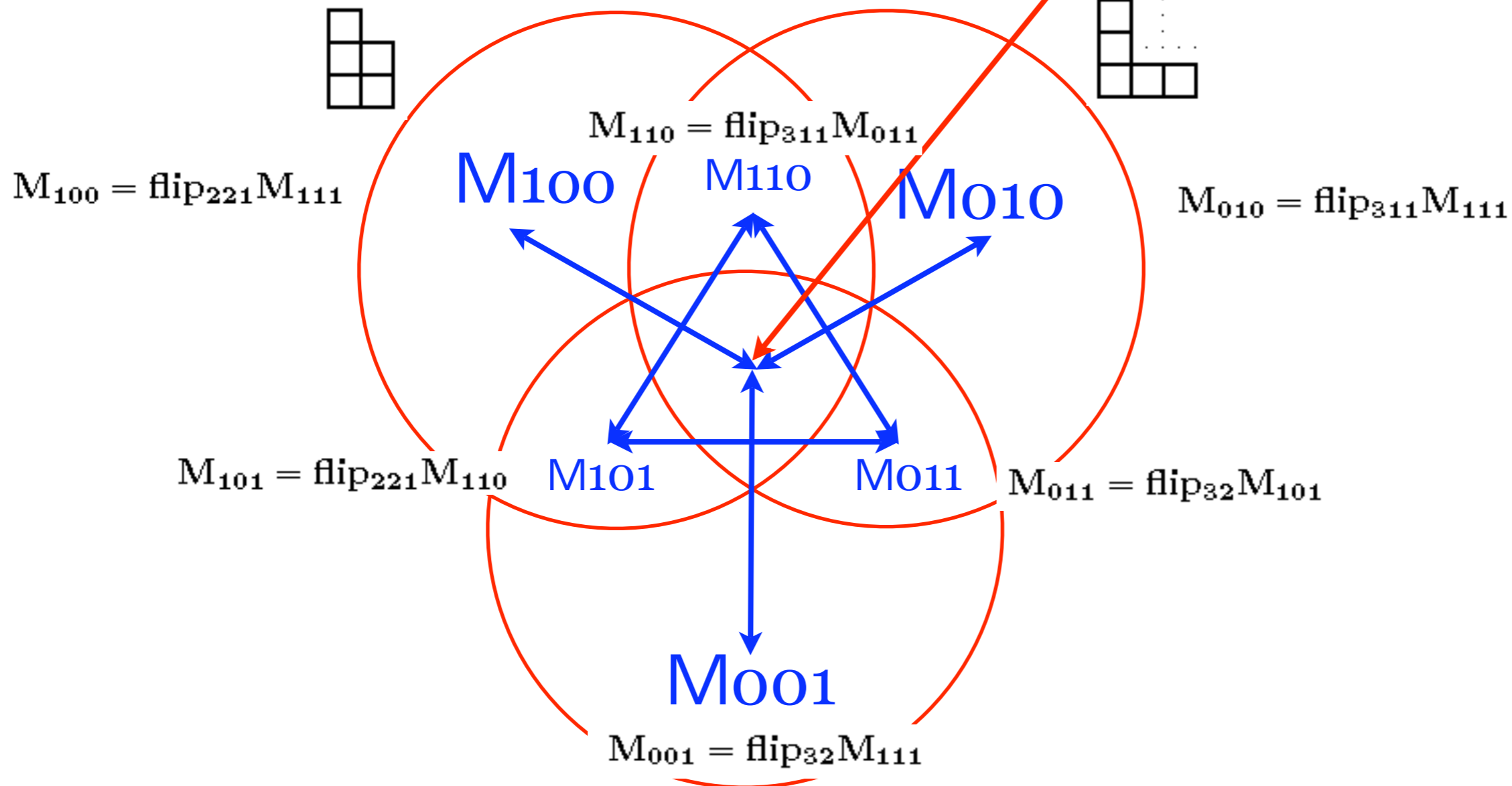
$\frac{n!}{k!}$ Conjecture

If $\alpha_1, \alpha_2, \dots, \alpha_k \vdash n$ differ only by one cell from each other then



More miracles

$$\boxed{\begin{array}{ccc} \begin{array}{c} \square \\ \square \\ \square \end{array} & \wedge & \begin{array}{ccc} \square & \square & \square \\ \square & \square & \square \end{array} & \wedge & \begin{array}{c} \square \\ \square \\ \square \end{array} \\ \square & & \square & & \square \end{array}} = M_{111}$$



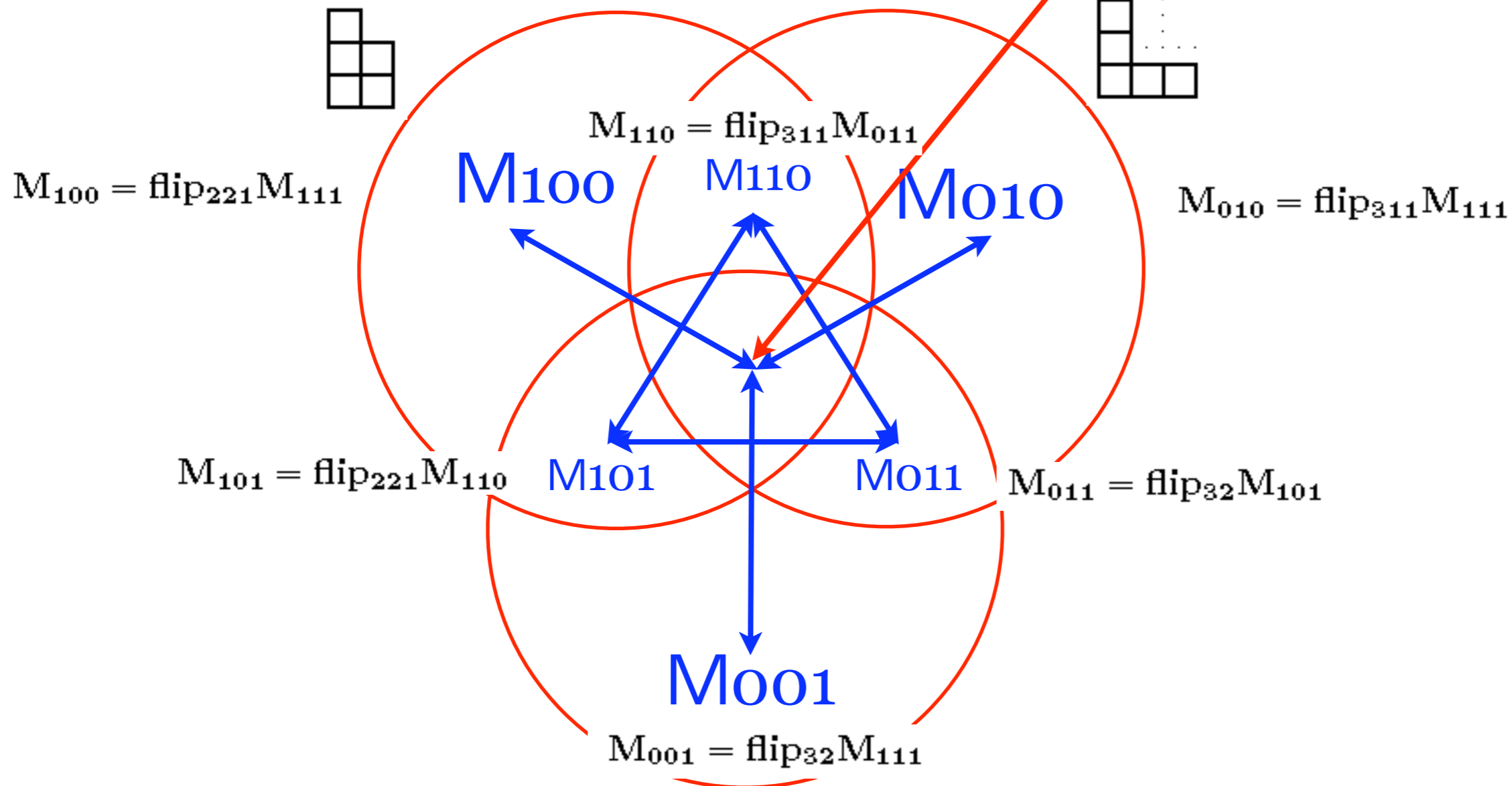
$\frac{n!}{k!}$ Conjecture

If $\alpha_1, \alpha_2, \dots, \alpha_k \vdash n$ differ only by one cell from each other then

$$\boxed{\dim M_{\alpha_1} \wedge M_{\alpha_2} \wedge \dots \wedge M_{\alpha_k} = \frac{n!}{k}}$$

More miracles

$$\boxed{\begin{array}{ccc} \begin{array}{c} \square \\ \square \\ \square \end{array} & \wedge & \begin{array}{ccc} \square & \square & \square \\ \square & \square & \square \end{array} & \wedge & \begin{array}{c} \square \\ \square \\ \square \end{array} \\ \square & & \square & & \square \end{array}} = M_{111}$$



$\frac{n!}{k!}$ Conjecture

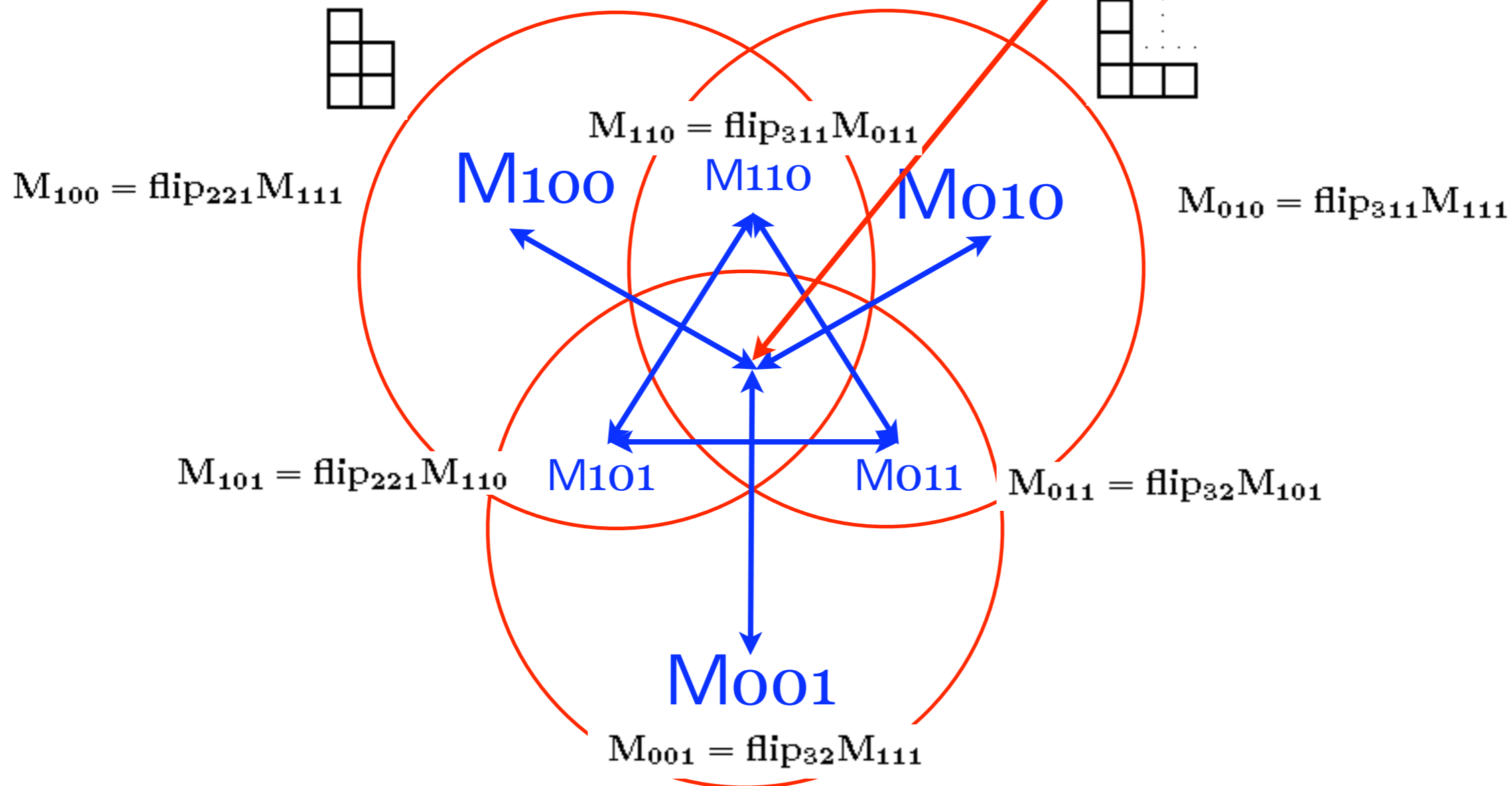
If $\alpha_1, \alpha_2, \dots, \alpha_k \vdash n$ differ only by one cell from each other then

$$\boxed{\dim M_{\alpha_1} \wedge M_{\alpha_2} \wedge \dots \wedge M_{\alpha_k} = \frac{n!}{k}}$$

Etc Etc Etc

More miracles

$$\boxed{\begin{array}{c} \square \dots \square \\ \square \wedge \square \wedge \square \\ \square \dots \square \end{array}} = M_{111}$$



$\frac{n!}{k!}$

Conjecture (still open!)



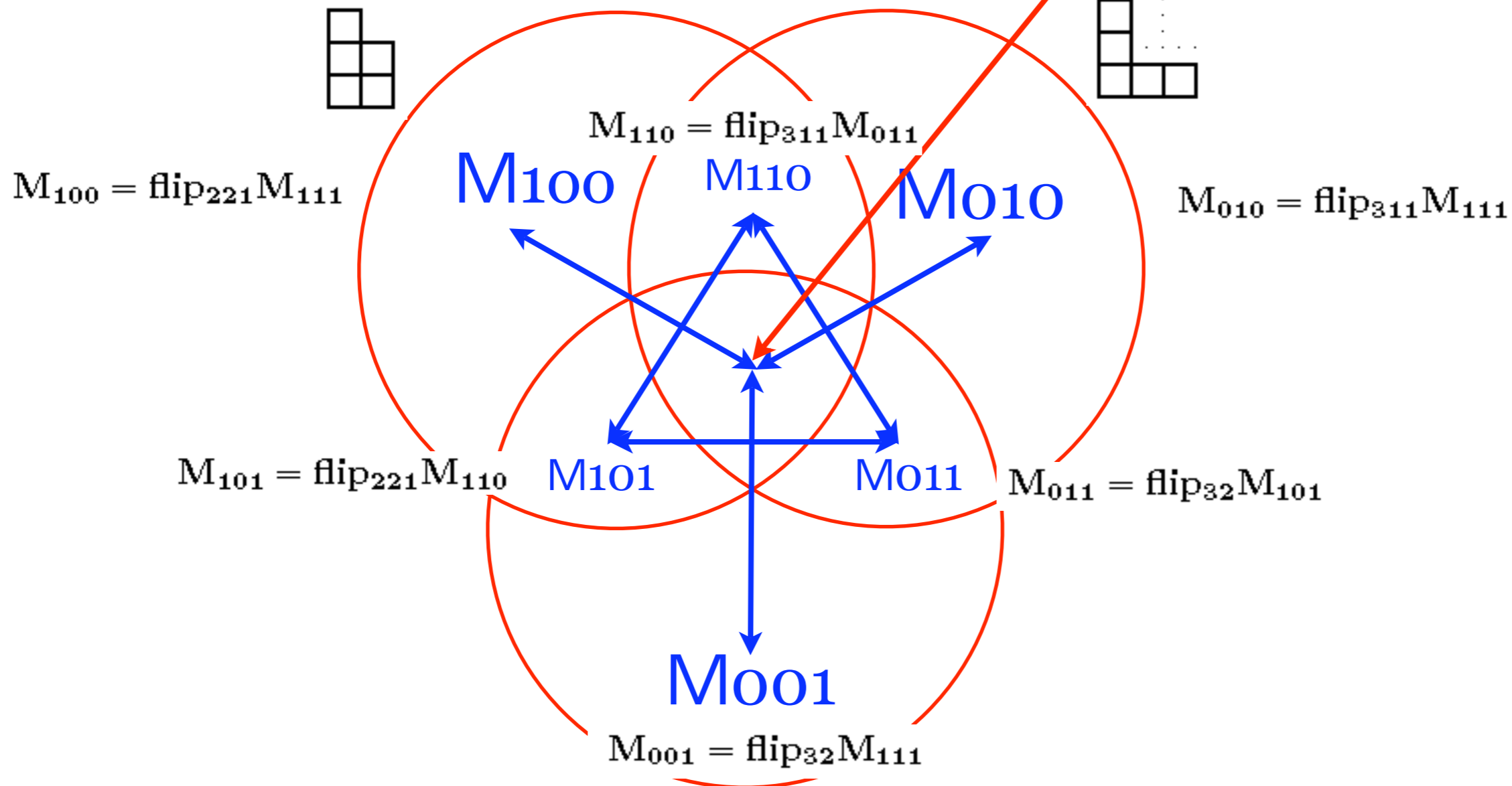
If $\alpha_1, \alpha_2, \dots, \alpha_k \vdash n$ differ only by one cell from each other then

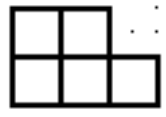
$$\boxed{\dim M_{\alpha_1} \wedge M_{\alpha_2} \wedge \dots \wedge M_{\alpha_k} = \frac{n!}{k}}$$

Etc Etc Etc

More miracles

$$\boxed{\begin{array}{ccc} \begin{array}{c} \square \\ \square \\ \square \end{array} & \wedge & \begin{array}{ccc} \square & \square & \square \\ \square & \square & \square \end{array} & \wedge & \begin{array}{c} \square \\ \square \\ \square \end{array} \\ \square & & \square & & \square \end{array}} = M_{111}$$



$\frac{n!}{k!}$ Conjecture (still open!) 

If $\alpha_1, \alpha_2, \dots, \alpha_k \vdash n$ differ only by one cell from each other then

$$\boxed{\dim M_{\alpha_1} \wedge M_{\alpha_2} \wedge \dots \wedge M_{\alpha_k} = \frac{n!}{k}}$$

Etc Etc Etc

next