

SELBERG'S TRACE FORMULA ON THE k -REGULAR TREE AND APPLICATIONS

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Abstract. This paper surveys graph theoretic analogues of the Selberg trace and pre-trace formulas along with some applications. It includes a review of the basic geometry of a k -regular tree Ξ (symmetry group, geodesics, horocycles, and the analogue of the Laplace operator). There is a detailed discussion of the spherical functions. The spherical and horocycle transforms are considered (along with 3 basic examples, which may be viewed as a short table of these transforms). Two versions of the pre-trace formula for a finite connected k -regular graph $X \cong \Gamma \backslash \Xi$ are given along with two applications. The first application is to obtain an asymptotic formula for the number of closed paths of length r in X (without backtracking but possibly with tails). The second application is to deduce the chaotic properties of the induced geodesic flow on X (which is analogous to a result of Wallace for a compact quotient of the Poincaré upper half plane). Finally the Selberg trace formula is deduced and applied to the Ihara zeta function of X , leading to a graph theoretic analogue of the prime number theorem.

1. Introduction

The Selberg trace formula has been of great interest to mathematicians for almost 50 years. It was discovered by Selberg [16], who also defined the Selberg zeta function, by analogy with the Riemann zeta function, to be a product over prime geodesics in a compact Riemann surface. But the analogue of the Riemann hypothesis is provable for the Selberg zeta function. The trace formula shows that there is a relation between the length spectrum of these prime geodesics and the spectrum of the Laplace operator on the surface.

More recently quantum physicists (specifically those working on quantum chaos theory) have been investigating the Selberg trace formula and its generalizations because it provides a connection between classical and quantum physics. See Hurt [11]. In fact, of late there has been much communication between mathematicians and physicists on this and matters related to the statistics of spectra and zeta zeros. See, for example, Hejhal et al [10]. Here our goal is to consider a simpler trace formula and a simpler analogue of Selberg's zeta function. The proofs will require only elementary combinatorics rather than functional analysis. The experimental computations require only a home computer rather than a supercomputer.

The trace formula we discuss here is a graph-theoretic version of Selberg's result. Here let Ξ be the k -regular tree where $k > 2$ (as the case $k = 2$ is degenerate). This means that Ξ is an infinite connected k -regular graph without cycles. We often write $k = q + 1$ as this turns out to be very convenient. In this paper, the Riemann

surface providing a home for the Selberg trace formula is replaced by a finite k -regular graph X . We can view X as a quotient $\Gamma \backslash \Xi$, where Γ is the fundamental group of the X . There are at least three ways to think about Γ - topological, graph theoretical, and algebraic. We will say more about Γ in Sections 3 and 4 below. At this point, you can think of Γ as a subgroup of the group graph isomorphisms of the tree Ξ .

We will normally assume that X is simple (i.e., has no multiple edges or loops), undirected, and connected. We will attempt to keep our discussion of the tree trace formula as elementary as possible and as close to the continuous case in [20] as possible. Thus you will find in Figures 3 and 4 a tree analogue of the tessellation of the Poincaré upper half plane by the modular group (in [20], p. 166 of Vol. I).

The outline of this paper is as follows. Section 2 concerns the basic geometry of k -regular trees. We consider the geodesics, horocycles, adjacency operator (which gives the tree-analogue of the Laplacian of a Riemann surface), and the isomorphism group of the tree. We also investigate the rotation invariant eigenfunctions of the adjacency operator, i.e., the spherical functions, in some detail. The horocycle transform of a rotation invariant function f on Ξ is defined in this section.

In Section 3 we obtain two versions of the pre-trace formula for a finite k -regular graph X . These formulas involve the spherical transform of a rotation invariant function f on the tree, which is just the tree-inner product of f with a spherical function. The relation between the spherical and horocycle transforms is given in Lemma 3. Three examples of horocycle and spherical transforms are computed.

Also to be found in section 3 are two applications of pre-trace formulas. The first is an asymptotic formula for the number of closed paths of length r in X without backtracking but possibly having tails as r goes to infinity (see formula (3.10)). Here “without backtracking but possibly having tails” means that adjacent edges in the path cannot be inverse to each other except possibly for the first and last edges. The second application of a pre-trace formula is Theorem 1 which says that the intersection of a small rotation-invariant set B in X with the image of B propagated forward by the induced geodesic flow on X (when averaged over shells) tends to be what one expects when one intersects two random sets in X . This result is a graph-theoretic analogue of a result of Wallace [24] where it is proved that the induced horocycle flow on a compact quotient of the Poincaré upper half plane exhibits chaotic properties in the sense that, in the long term, the area of the intersection of a small rotation-invariant set B with the image of B propagated forward by the induced horocycle flow (and averaged over rotations) tends to be what one expects if one intersects two random sets. This property is a measure-theoretic analogue of the ergodic “mixing property.” Theorem 1 gives a graph-theoretic analogue of Wallace’s theorem in which the horocycle flow on a compact quotient of the Poincaré upper half plane is replaced with the geodesic flow on a finite k -regular graph. This result also has an interesting combinatorial interpretation. See the example following Theorem 1.

In Section 4 we consider Selberg’s trace formula. Here we apply the formula to deduce the basic fact about the Ihara zeta function of a finite regular graph. That is, we show that this zeta function is the reciprocal of a polynomial which is easily computed if one knows the spectrum of the adjacency matrix. And we obtain a graph theoretic analogue of the prime number theorem (see formula (4.2)).

Some additional references for the subject are Ahumada [1], Brooks [3], Cartier [5], Figá-Talamanca and Nebbia [7], Hashimoto [9], Quenell [15], Stark and Terras [17], Sunada [18], Terras [19], Venkov and Nikitin [23].

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2. Basic Facts about k-regular Trees

2.1. Geodesics and Horocycles. The k -regular tree has a distance function $d(x, y)$ defined for $x, y \in \Xi$ as the number of edges in the unique path connecting x and y . We have a Hilbert space $L^2(\Xi)$ consisting of $f : \Xi \rightarrow \mathbb{R}$ such that $(f, f)_\Xi < \infty$, where $(f, g)_\Xi = \sum_{x \in \Xi} f(x)g(x)$.

Our formulas involve the adjacency operator A on Ξ which is defined on f in $L^2(\Xi)$ by

$$(2.1) \quad Af(x) = \sum_{d(x,y)=1} f(y).$$

A is a self-adjoint operator (i.e., $(f, Ag) = (Af, g)$, for $f, g \in L^2(\Xi)$) with continuous spectrum in the interval

$$[-2\sqrt{k-1}, 2\sqrt{k-1}].$$

For a proof, see Sunada [18], p. 252 or Terras [19], p. 410.

However, the adjacency operator is not a compact operator (i.e., there is a bounded sequence f_n such that Af_n does not have a convergent subsequence). Thus the spectral theorem for A involves a computation of the spectral measure. We summarized the theory for differential operators briefly in Terras [20], Vol. I, p. 110. See formula (3.4) for the spectral measure on the tree. We will not actually need this result here.

A **chain** $c = \{x_0, x_1, x_2, \dots, x_n, \dots\}$ in Ξ is a semi-infinite path, i.e., vertex x_j is adjacent to vertex x_{j+1} . It is assumed that the chain is without **backtracking**; i.e., $x_{n+1} \neq x_{n-1}$. A doubly infinite path is a **geodesic**. It may be viewed as the union of 2 chains c and c' both of which start at the same vertex x_0 .

In the Poincaré upper half plane, the y -axis is an example of a geodesic and the horizontal lines perpendicular to it are horocycles. We have an analogous concept for the tree.

The **boundary** Ω of Ξ is the set of equivalence classes of chains where 2 chains $c = \{x_n | n \geq 0\}$ and $c' = \{y_n | n \geq 0\}$ are equivalent if they have infinite intersection. If we fix an element $\omega \in \Omega$, a horocycle (with respect to ω) is defined as follows. The chain connecting x in Ξ to infinity along ω is $[x, \infty]$. If x and y are any vertices in Ξ , then $[x, \infty] \cap [y, \infty] = [z, \infty]$. We say that x and y are **equivalent** if $d(x, z) = d(y, z)$. **Horocycles** with respect to ω are the equivalence classes for this equivalence relation. See Figure 1. Note that horocycles are infinite.

The horocycle transform of a function $f : \Xi \rightarrow \mathbb{C}$ is a sum over a horocycle h of our function f :

$$(2.2) \quad F(h) = \sum_{x \in h} f(x).$$

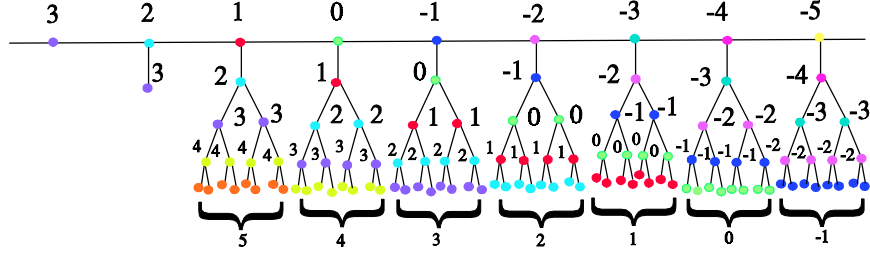


Figure 1. Horocycles in the 3-Regular Tree. Points in the n th horocycle are labeled n . We fix a boundary element represented by the chain c and a geodesic $c \cup c'$. Here c consists of the points labeled with $n \leq 0$ and c' consists of the points labeled with $n > 0$.

If we fix a boundary element ω of Ξ represented by $\{x_n \mid n \geq 0\}$ and a geodesic $c \cup c'$ in our tree Ξ , then we can label the horocycles \mathfrak{h} with numbers as in Figure 1, where each element of horocycle \mathfrak{h}_n is labeled n . Assume that f is invariant under rotation about the origin and write $f(x) = f(d(x, \mathbf{0}))$, where $\mathbf{0}$ is the origin of our tree Ξ and the point $\mathbf{0}$ is the intersection of c and c' . Then we find that $F(n) = F(\mathfrak{h}_n) = c_n Hf(n)$, where $c_n = q^n$, if $n > 0$; $c_n = 1$, otherwise. Here Hf is defined by:

$$(2.3) \quad Hf(n) = f(|n|) + (q-1) \sum_{j \geq 1} q^{j-1} f(|n| + 2j), \quad \text{for } n \in \mathbb{Z}.$$

This transform is invertible:

$$(2.4) \quad f(|n|) = Hf(|n|) - (q-1) \sum_{j \geq 1} (Hf)(|n| + 2j).$$

2.2. Isomorphism Group of the Tree. The elements of the group G of graph-theoretic isomorphisms of Ξ may be classified as follows into three types of elements:

Type 1. Rotations fix a vertex of Ξ .

Type 2. Inversions fix an edge of Ξ and exchange endpoints.

Type 3. Hyperbolic elements ρ fix a geodesic $\{x_n \mid n \text{ in } \mathbb{Z}\}$ and $\rho(x_n) = x_{n+s}$. That is, ρ shifts along the geodesic by $s = \nu(\rho)$ (Definition). See Figá-Talamanca and Nebbia [7] for a proof of this result.

Notes. A subgroup of G is the free group generated by k elements. The tree is the Cayley graph on this group with edge set the set of k generators and their inverses. By a Cayley graph $X = X(G, S)$, we mean that the vertices are the elements of the group G and there are edges from $g \in G$ to gs , for all $s \in S$. The Cayley graph will be undirected if $s \in S$ implies $s^{-1} \in S$.

If Γ is the subgroup of G consisting of covering transformations of a finite graph X , then Γ consists only of hyperbolic elements and the identity.

Now consider our finite connected k -regular graph $X = \Gamma \backslash \Xi$, where Γ is the fundamental group of X (which may be viewed as covering transformations of the covering of X by Ξ , its universal cover). Then Γ is a strictly hyperbolic group of automorphisms of Ξ ; i.e., if $\rho \in \Gamma$ and ρ is not the identity, then ρ acts without

fixed points. We say that ρ is **primitive** if it generates the centralizer Γ_ρ of ρ in Γ . Note that Γ_ρ must be cyclic since Γ is free.

2.3. Spherical Functions on Trees. Next we consider tree-analogues of the Laplace spherical harmonics in Euclidean space. These are also analogous to the spherical functions on the Poincaré upper half plane which come from Legendre functions $P_{-s}(\cosh(r))$, $r =$ geodesic radial distance to origin. See [20], Vol. I, p. 141, where it is noted that these spherical functions are obtained by averaging power functions $(\text{Im}(z))^s$ over the rotation subgroup $K = SO(2)$ of $G = SL(2, \mathbb{R})$.

Fix $\mathbf{0}$ to be the origin of the tree. Define $h : \Xi \rightarrow \mathbb{C}$ to be **spherical** iff it has the following 3 properties:

- 1) $h(x) = h(d(x, \mathbf{0}))$; i.e., h is invariant under rotation about the origin $\mathbf{0}$;
- 2) $Ah = \lambda h$; i.e., h is an eigenfunction of the adjacency operator;
- 3) $h(\mathbf{0}) = 1$.

The spherical function corresponding to the eigenvalue λ is unique and can be written down in a very elementary and explicit manner (cf. Brooks [3] and Figá-Talamanca and Nebbia [7]).

Start with the power function $p_s(x) = q^{-sd(x, \mathbf{0})}$, for s in \mathbb{C} . Here $q + 1 = k$, as usual. Then, as long as $d = d(x, \mathbf{0})$ is non-zero, we have

$$(2.5) \quad Ap_s = (q^s + q^{1-s})p_s$$

However, if $d(x, \mathbf{0}) = 0$, we get $Ap_s = (q + 1)p_s$. So the power function p_s just fails to be an eigenfunction of A . Now write

$$(2.6) \quad h_s(d) = c(s)p_s(d) + c(1-s)p_{1-s}(d)$$

This is analogous to a formula for the spherical functions on the Poincaré upper half plane. See [20], Vol. I, p. 144.

You can use what you know about spherical functions to compute the coefficients $c(s)$. This gives

$$(2.7) \quad c(s) = \frac{q^{s-1} - q^{1-s}}{(q+1)(q^{s-1} - q^{-s})}, \quad \text{if } q^{2s} \neq 1.$$

Writing $z = q^{s-1/2}$, yields:

$$h_s(d) = \frac{q^{-d/2}}{q+1} \left\{ \frac{qz^{-d}(z^{2+2d} - 1) - z^d(1 - z^{2-2d})}{z^2 - 1} \right\}.$$

We can rewrite this as a polynomial in z divided by z^d .

$$(2.8) \quad \begin{aligned} h_s(d) &= \frac{1}{z^d q^{d/2} (q+1)} \left\{ q \sum_{j=0}^d z^{2j} - \sum_{j=1}^{d-2} z^{2+2j} \right\} \\ &= \frac{1}{z^d q^{d/2} (q+1)} \left\{ q + qz^{2d} + (q-1) \sum_{j=1}^{d-1} z^{2j} \right\}. \end{aligned}$$

Take limits as z^2 goes to 1 to obtain the value if $z^2 = 1$, which is

$$h_s(d) = \frac{1}{z^d q^{d/2}} \left\{ \frac{q+1 + (q-1)d}{q+1} \right\}, \quad \text{if } z^2 = 1.$$

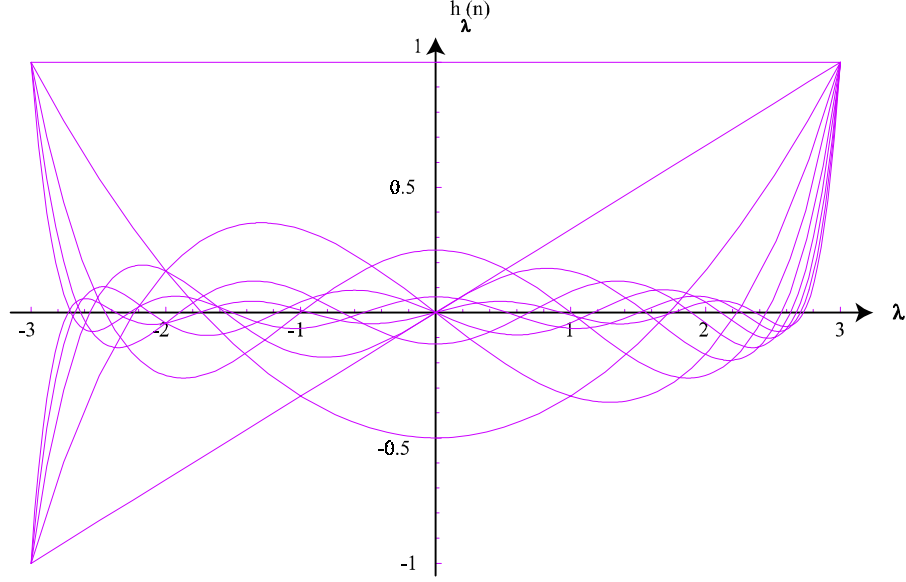


Figure 2. 10 spherical functions $h_\lambda(n)$, $n = 0, 1, \dots, 9$, for the degree 3 tree as a function of the eigenvalue λ of the adjacency matrix

Perhaps the easiest way to understand the spherical functions as a function of the eigenvalue λ of the adjacency operator A is to write $h_s(d) = h_\lambda(d)$, where $\lambda = q^s + q^{1-s}$. Then obtain a recursion from $Ah_\lambda(d) = \lambda h_\lambda(d)$. You obtain

$$(2.9) \quad h_\lambda(d+1) = \frac{1}{q}(\lambda h_\lambda(d) - h_\lambda(d-1)), \quad \text{for } d = d(x, 0) > 0,$$

$$h_\lambda(1) = \frac{\lambda}{q+1}h_\lambda(0).$$

This allows you to write $h_\lambda(n)$ in terms of the Chebyshev polynomials of the first and second kinds $T_n(x)$ and $U_n(x)$ defined by

$$T_n(\cos \theta) = \cos(n\theta) \quad \text{and} \quad U_n(\cos \theta) = \frac{\sin((n+1)\theta)}{\sin \theta}.$$

See Erdélyi et al [6], pp. 183-187, for more information on these polynomials. The final result is

$$(2.10) \quad h_\lambda(n) = q^{-n/2} \left(\frac{2}{q+1} T_n\left(\frac{\lambda}{2\sqrt{q}}\right) + \frac{q-1}{q+1} U_n\left(\frac{\lambda}{2\sqrt{q}}\right) \right).$$

Note that since λ is real, so is $h_\lambda(n)$. Figure 2 shows graphs of $h_\lambda(d)$ as a function of λ when $q = 2$ and $d = 0, 1, \dots, 9$.

We will need to know what happens to the spherical function as d goes to infinity. Suppose the eigenvalue λ of the adjacency operator A on the tree acting on the

spherical function $h_s(d)$ is given by $\lambda = q^s + q^{1-s}$. And suppose λ is actually an eigenvalue of the adjacency operator on a connected, k -regular, finite graph X . In this situation, we need to know the locations of the complex numbers s in the complex plane. The answer is given in the following Lemma.

Before stating the Lemma, we note that a **bipartite graph** is one in which the vertices can be partitioned into 2 disjoint sets V_1 and V_2 such that every edge has one vertex in V_1 and the other in V_2 . For such graphs, if λ is an eigenvalue of the adjacency operator, so is $-\lambda$ (and conversely).

Lemma 1. Suppose that X is a connected k -regular finite graph. Here $k = q + 1$.

a) Assume that X is not bipartite. Then any eigenvalue λ of the adjacency operator on X , with λ not equal to the degree $k = q + 1$, satisfies $\lambda = q^s + q^{1-s}$ where $0 < \text{Re}(s) < 1$. We may assume $\text{Re}(s) \geq 1/2$.

b) If X is not bipartite and $k = q + 1 = q^s + q^{1-s}$, we can take $s = 0$ or 1 .

c) If X is bipartite and $\lambda = q^s + q^{1-s}$ is an eigenvalue of A , so is $-\lambda = q^{s'} + q^{1-s'}$, with $s' = s + i\pi/\log q$.

Proof. a) Let $s = a + ib$, with a, b real. Then

$$\frac{\lambda}{\sqrt{q}} = 2 \cosh \left\{ \left(a - \frac{1}{2} \right) \log q \right\} \cos(b \log q) + 2i \sinh \left\{ \left(a - \frac{1}{2} \right) \log q \right\} \sin(b \log q).$$

Since λ is real, the imaginary part of this expression vanishes. This can happen in 2 ways.

$$(1) \quad \sin(b \log q) = 0 \quad \text{and} \quad \lambda q^{-1/2} = \pm 2 \cosh \{ (a - 1/2) \log q \}.$$

$$(2) \quad a = 1/2 \quad \text{and} \quad \lambda q^{-1/2} = 2 \cos(b \log q).$$

In part a), our hypothesis is: $|\lambda| < q + 1$, which implies that in case 1, we have

$$\cosh \{ (a - 1/2) \log q \} < \cosh \{ (1/2) \log q \}.$$

Thus, in case (1), $|a - 1/2| < 1/2$ and $0 < a < 1$.

In case (2), $a = 1/2$, and we are done. In case (2), the eigenvalues satisfy $|\lambda| \leq 2\sqrt{q}$, which is the Ramanujan bound (see Terras [19] for more information on this subject).

We leave parts b) and c) to the reader. □

Note. In order for the $\lambda = q^s + q^{1-s}$ in the preceding Lemma to be actual eigenvalues of the adjacency operator corresponding to the spherical function h_s , it is necessary for the spherical function to be in $L^2(\Xi)$. This will not be the case, as you can see by noting that for the power function $p_s(x) = q^{-sd(x,0)}$ to be in $L^2(\Xi)$ we need $\text{Re } s > 1/2$. But then we cannot find any s for which both p_s and p_{1-s} are in p_s . This is similar to the situation in the Poincaré upper half plane when one considers the continuous spectrum of the non-Euclidean Laplacian on the fundamental domain of the modular group. See the discussion after formula (4.4) below and Terras [20], Vol. I, pp. 206-7.

Corollary 1. Asymptotics of Spherical Functions. Suppose that X is a finite, connected, k -regular graph which is not bipartite. Let λ be an eigenvalue of the adjacency operator on X , with λ not equal to the degree $k = q + 1$. Write $\lambda = q^s + q^{1-s}$ where $1/2 \leq \text{Re } s < 1$. Then the corresponding spherical function $h_s(d)$ goes to 0 as d goes to infinity.

Proof. If s is not $1/2$, note that $0 < \operatorname{Re} s < 1$ implies

$$h_s(d) = c(s)q^{-sd} + c(1-s)q^{-(1-s)d}$$

approaches 0 as d goes to infinity. If $\operatorname{Re} s = 1/2$ and $\operatorname{Im} s = \frac{n\pi}{\log q}$, $n \in \mathbb{Z}$, then

$$|h_s(d)| = \frac{1}{q^{d/2}} \left| 1 - \frac{q-1}{q+1}d \right|$$

approaches 0 as d goes to infinity. □

Note. For any finite connected k -regular graph X , the degree k is an eigenvalue of the adjacency operator corresponding to the constant spherical function $h_0(d) = 1$, $d = d(x, \mathbf{0})$, for $\mathbf{0}$ the origin of the tree. If the graph X is finite connected k -regular and bipartite, then $-k$ is also an eigenvalue of the adjacency operator and the corresponding spherical function is $(-1)^d$, where $d = d(x, \mathbf{0})$.

3. The Pre-Trace Formula

Again we assume that $X = \Gamma \backslash \Xi$ is a finite connected k -regular graph. To obtain the pre-trace formula, we follow the elementary discussion of Brooks [3]. Consider any rotation-invariant function on the tree: $f(y) = f(d(y, x))$, where $x = \mathbf{0}$ is the origin of the tree. Suppose that f has finite support. Define the Γ -invariant kernel associated to f to be:

$$(3.1) \quad K_f(x, y) = \sum_{\gamma \in \Gamma} f(d(x, \gamma y)).$$

So $K_f(x, \gamma y) = K_f(\gamma x, y) = K_f(x, y)$, for all $\gamma \in \Gamma$ and all x, y in the tree. We may as well take

$$(3.2) \quad f_r(x, y) = \begin{cases} 1, & \text{if } d(x, y) = r, \\ 0, & \text{otherwise.} \end{cases}$$

For any finitely supported and rotation-invariant function about x will be a linear combination of the functions f_r .

We need more lemmas.

Lemma 2. Suppose that ϕ is any eigenfunction of the adjacency operator A on Ξ . That is, suppose $A\phi = \lambda\phi$. Then if $r > 0$,

$$\sum_{y \in \Xi} f_r(x, y)\phi(y) = k(k-1)^{r-1}h_{s_\lambda}(r)\phi(x),$$

and the sum is equal to $\phi(x)$, if $r = 0$. Here h_{s_λ} is the spherical function (expressed as a function of the distance to the origin x) corresponding to the eigenvalue

$$\lambda = q^{s_\lambda} + q^{1-s_\lambda}$$

for the adjacency operator.

Proof. The case $r = 0$ is clear. When $r > 0$, fix y_0 in a shell of radius r about x . Let $\phi^\#(y_0)$ denote the average of ϕ over the shell of radius $r = d(x, y_0)$ about x . To get $\phi^\#(y_0)$, you must sum $\phi(u)$ over all u with $d(u, x) = d(y_0, x) = r$ and divide by the number of such points u which is $k(k-1)^{r-1}$. So $\phi^\#(y_0)$ is invariant under rotation about x and it is an eigenfunction of A (as A commutes with the action of the rotation subgroup of G or any element of G).

By the uniqueness of the spherical function associated to the eigenvalue λ of A ,

$$\phi^\#(y_0) = h_{s_\lambda}(d(x, y_0))\phi(x),$$

where s_λ is defined by $\lambda = q^{s_\lambda} + q^{1-s_\lambda}$.

Note. You have to think a bit about what happens if $\phi^\#$ is zero. See Quenell [15].

So now we find that, with y_0 fixed such that $d(y_0, x) = r$:

$$\sum_{y \in \Xi} f_r(x, y)\phi(y) = \sum_{\substack{y \in \Xi \text{ such that} \\ d(x, y) = r}} \phi(y) = \phi^\#(y_0)k(k-1)^{r-1}.$$

This completes the proof of the Lemma. □

Note. The operator on the left in Lemma 2 (with x =the origin) is the r th Hecke operator which we denote $T_r\phi$. See Cartier [5]. The algebra generated by the T_r is called the Hecke algebra. One sees that $T_0 = \text{Identity}$, $T_1 = A$ and $(T_1)^2 = T_2 + (q+1)T_0$, $T_1T_m = T_{m+1} + qT_{m-1} = T_mT_1$, for $m > 1$. Thus the Hecke algebra is a polynomial algebra in $A = T_1$. Moreover

$$\sum_{m \geq 0} T_m u^m = (1 - u^2)(1 - uT_1 + qu^2)^{-1}.$$

Corollary 2. (Selberg's Lemma). If f is a finitely supported rotation-invariant (real-valued) function on Ξ and ϕ is an eigenfunction of the adjacency operator A on Ξ , with $A\phi = \lambda\phi$, then, writing \mathbf{o} for the origin of Ξ ,

$$(f, \phi)_\Xi = \phi(\mathbf{o})(f, h_s)_\Xi,$$

where $\lambda = q^s + q^{1-s}$ and h_s is the spherical function in (2.6). Here $(f, g)_\Xi$ denotes the inner product defined by

$$(f, g)_\Xi = \sum_{x \in \Xi} f(x)g(x).$$

Proof. Set $x = \mathbf{o}$ in Lemma 2. If $r = 0$, we get $(f_0, \phi)_\Xi = \phi(\mathbf{o}) = \phi(\mathbf{o})(f_0, h_s)_\Xi$, since $h_s(\mathbf{o}) = 1$. If $r > 0$, then Lemma 2 says that

$$(f_r, \phi)_\Xi = k(k-1)^{r-1}h_s(r)\phi(\mathbf{o}) = \phi(\mathbf{o})(f_r, h_s)_\Xi.$$

Since the f_r form a vector space basis of the space of finitely supported rotation invariant functions on Ξ , the proof is complete. □

The inner product on the right hand side of the formula in Selberg's Lemma has a name - the spherical transform of f . The spherical transform of any rotationally invariant function f on the tree is defined to be

$$(3.3) \quad \widehat{f}(s) = (f, h_s)_\Xi.$$

This is an invertible transform. The inversion formula is part of the spectral theorem for the adjacency operator on the tree. It can be obtained by making use of the resolvent $R_\mu = (A - \mu I)^{-1}$. See Figà-Talamanca and Nebbia [7], p. 61. The Plancherel theorem for rotation-invariant functions f on the tree with finite support says:

$$(3.4) \quad f(0) = \int_0^{\pi/\log q} \widehat{f}\left(\frac{1}{2} + it\right) \frac{q \log q}{2\pi(q+1)|c(\frac{1}{2} + it)|^2} dt,$$

for $c(s)$ as in (2.7).

We will not need this result here.

The following Lemma proves useful when applying the Selberg trace formula in the last section.

Lemma 3. (Relation Between Spherical and Horocycle Transforms). Suppose that f is a rotation-invariant function on the tree and that $z = q^{s-1/2}$. If $\widehat{f}(s)$ denotes the spherical transform in formula (3.3) and Hf denotes the horocycle transform in (2.3), then

$$\widehat{f}(s) = \sum_{n \in \mathbb{Z}} Hf(n) q^{|n|/2} z^n.$$

Proof. Using (2.8), we have

$$\begin{aligned} (f, h_s) &= f(0) + \sum_{n=1}^{\infty} (q+1)q^{n-1} f(n) h_s(n) \\ &= f(0) + \sum_{n=1}^{\infty} f(n) q^{n/2} z^{-n} \left(1 + z^{2n} + \frac{q-1}{q} \sum_{j=1}^{n-1} z^{2j} \right). \end{aligned}$$

Rearranging the sums finishes the proof after a bit of work. \square

In the following examples, we essentially find a short table of horocycle and spherical transforms.

Example 1. By the preceding Lemma, one finds that if the horocycle transform is defined to be

$$H\alpha(n) = \begin{cases} u^{|n|-1}, & \text{for } n \neq 0, \\ 0, & \text{for } n = 0, \end{cases}$$

then the spherical transform $(\alpha, h_s) = \frac{q^s}{1-uq^s} + \frac{q^{1-s}}{1-uq^{1-s}}$, when $|u| < \frac{1}{q}$. Setting $\lambda = q^s + q^{1-s}$, as usual, this means

$$(3.5) \quad (\alpha, h_s) = \frac{d}{du} \log \frac{1}{1 - \lambda u + qu^2}.$$

Then using the inversion formula for the horocycle transform with $|u| < 1$, one has

$$\alpha(n) = \begin{cases} \frac{(1-q)u}{1-u^2}, & \text{for } n = 0. \\ \frac{u^{|n|-1}(1-qu^2)}{1-u^2}, & \text{for } n > 0. \end{cases}$$

Example 2. Set $f = f_r$ as in (3.2). Then

$$(f, h_s) = \begin{cases} 1, & \text{for } r = 0, \\ (q+1)q^{r-1}h_s(r), & \text{for } r > 0. \end{cases}$$

and

$$Hf_r = \begin{cases} 1, & \text{if } |n| = r, \\ (q-1)q^{j-1}, & \text{if } |n| + 2j = r, \\ 0, & \text{otherwise.} \end{cases}$$

So

$$(3.6) \quad Hf_r = \delta_r(|n|) + (q-1) \sum_{j=1}^{\lfloor r/2 \rfloor} q^{j-1} \delta_{r-2j}(|n|).$$

Example 3. Suppose that $Hg_n(m) = \delta_n(|m|)$. Then using the inversion formula for the horocycle transform in formula (2.4), one has

$$g_n = \delta_n - (q-1) \sum_{j=1}^{\lfloor n/2 \rfloor} \delta_{n-2j}.$$

By the preceding Lemma, with $z = q^{s-1/2}$, the spherical transform is

$$(g_n, h_s) = q^{n/2}(z^n + z^{-n}) = q^{ns} + q^{n(1-s)}.$$

Let A be the adjacency operator on the finite graph $X = \Gamma \backslash \Xi$. It is essentially the same as that on the tree covering X by the local isomorphism. Suppose that $\{\phi_i\}_{i=1, \dots, |X|}$ is a complete orthonormal set of eigenfunctions of A on X . We can assume that the ϕ_i are real-valued. Let Φ_i be the lift of ϕ_i to the tree Ξ ; i.e., $\Phi_i(x) = \phi_i(\pi(x))$, for $x \in \Xi$, where $\pi : \Xi \rightarrow X$ is the natural projection map. Then $A\Phi_i = \lambda\Phi_i$, since $\pi : \Xi \rightarrow X$ is a local graph isomorphism. Usually we will omit π .

Now, using our favorite functions $f_r(x, y)$, defined in (3.2), we have for $\pi(x), \pi(y) \in X$:

$$(3.7) \quad K_{f_r}(x, y) = K_{f_r}(\pi(x), \pi(y)) = \sum_{\gamma \in \Gamma} f_r(d(x, \gamma y)) = (A_r)_{\pi(x), \pi(y)}.$$

Here the right-hand side is the number of paths of length r without backtracking from $\pi(x)$ to $\pi(y)$ in X . A path C in X consists of a set of adjacent vertices $C = (v_0, \dots, v_n)$, $v_j \in X$. As before, we say C has backtracking if $v_{j-1} = v_{j+1}$, for some j , $2 \leq j \leq r-1$. To see that we are counting paths without backtracking consider Figure 3.

So there must be constants $c_{i,j}$ such that K_f is a sum over i, j from 1 to $|X|$ of $c_{i,j}\phi_i(x)\phi_j(y)$. We find these constants in the next Lemma.

Lemma 4. Suppose that the notation is as above and $\{\phi_i, i = 1, \dots, |X|\}$ forms a complete orthonormal set of eigenfunctions of the adjacency operator on X . Let h_{s_i} be the spherical function associated to the same eigenvalue for the adjacency operator on Ξ

$$\lambda_i = q^{s_i} + q^{1-s_i}$$

as ϕ_i . Then for $r > 0$,

$$K_{f_r}(x, y) = \sum_{i=1}^{|X|} k(k-1)^{r-1} h_{s_i}(r) \phi_i(x) \phi_i(y).$$

If $r = 0$, you get the sum of $\phi_i(x) \phi_i(y)$.

Proof. Look at $r > 0$. Then, as above, Φ_i is the lift of ϕ_i to Ξ . So by Lemma 2, we have:

$$\begin{aligned} \sum_{y \in X} K_{f_r}(x, y) \phi_m(y) &= \sum_{y \in \Gamma \setminus \Xi} \sum_{\gamma \in \Gamma} f_r(x, \gamma y) \phi_m(y) \\ &= \sum_{y \in \Xi} f_r(x, y) \Phi_m(y) = k(k-1)^r h_{s_m}(r) \phi_m(x). \end{aligned}$$

□

Now by Lemma 4, pre-trace formula I says:

$$(3.8) \quad \sum_{x \in X} K_{f_r}(x, x) = \sum_{i=1}^{|X|} k(k-1)^{r-1} h_{s_i}(r) = \sum_{i=1}^{|X|} (f_r, h_{s_i}).$$

This can be viewed as the trace of the operator K_{f_r} , acting on functions $g \in L^2(X)$ via $K_{f_r}(g) = \sum_{y \in X} K_{f_r}(x, y) g(y)$ and it is the left-hand side of the trace formula in Theorem 2 below when $f = f_r$.

Note that using (3.7), the trace of K_{f_r} is $a_X(r)$ = the number of closed paths without backtracking of length r in X . Here we count paths as different if they start at a different vertex. Note also that the paths being counted can have tails. A tail in a path means that the starting edge is the inverse of the terminal edge. More explicitly we have for $r > 0$

$$(3.9) \quad \begin{aligned} a_X(r) &= \# \text{ closed paths sans backtracking, length } r \text{ in } X \\ &= \sum_{i=1}^{|X|} (q+1) q^{r-1} h_{s_i}(r), \end{aligned}$$

where s_i corresponds to the eigenvalue $\lambda_i = q^{s_i} + q^{1-s_i}$ of the adjacency operator A of X .

Brooks [3] uses formula (3.9) to obtain bounds on the 2nd largest (in absolute value) eigenvalue of A on X . We shall use it to obtain an asymptotic formula for $a_X(r)$.

Suppose that X is a non-bipartite k -regular finite graph. Then

$$(3.10) \quad a_X(r) \sim \left(1 + \frac{1}{q}\right) q^r, \quad \text{as } r \longrightarrow \infty.$$

To prove this, one can use (3.9) and the method of generating functions. For set

$$w(\lambda, x) = \sum_{n=1}^{\infty} x^{n-1} h_\lambda(n).$$

From the recursion (2.9) we see that

$$w(\lambda, x) = \frac{\frac{\lambda}{q+1} - \frac{x}{q}}{\frac{x^2}{q} - \frac{\lambda x}{q} + 1}.$$

It follows that

$$\sum_{n=1}^{\infty} a_X(n)x^{n-1} = \sum_{i=1}^{|X|} \frac{\lambda_i - x(q+1)}{qx^2 - \lambda_i x + 1}.$$

The closest pole to the origin of the right hand side is $x = 1/q$. It comes from the largest eigenvalue (the degree of the graph). Then a standard method from generating function theory using the formula for the radius of convergence of a power series leads to (3.10). See Wilf [25], p. 171.

Now we need to begin to discuss the right-hand side of the trace formula.

Define $\Gamma_\gamma =$ the centralizer of γ in Γ ; i.e.,

$$(3.11) \quad \Gamma_\gamma = \{\sigma \in \Gamma \mid \gamma\sigma = \sigma\gamma\}.$$

And let $\{\gamma\}$ be the conjugacy class of γ in Γ ; i.e.,

$$(3.12) \quad \{\gamma\} = \{\sigma\gamma\sigma^{-1} \mid \sigma \in \Gamma\}.$$

Then we break up Γ into the disjoint union of its conjugacy classes and note that the conjugacy class $\{\gamma\}$ is the image of $\Gamma_\gamma \backslash \Gamma$ under the map that send σ to $\sigma\gamma\sigma^{-1}$. And $\Gamma_\gamma \backslash \Xi$ is a union of images of $\Gamma \backslash \Xi$ under elements of $\Gamma_\gamma \backslash \Gamma$. So we obtain, writing $f(d(x, y)) = f(x, y)$

$$\begin{aligned} \sum_{x \in X} K_{f_r}(x, x) &= \sum_{x \in \Gamma \backslash \Xi} \sum_{\gamma \in \Gamma} f_r(x, \gamma x) \\ &= \sum_{\{\gamma\}} \sum_{x \in \Gamma_\gamma \backslash \Xi} f_r(x, \gamma x), \end{aligned}$$

where the sum over $\{\gamma\}$ is a sum over all conjugacy classes in Γ .

Thus we have the pre-trace formula II which says that for any f which is rotation invariant and of finite support on Ξ

$$(3.13) \quad \sum_{i=1}^{|X|} \hat{f}(s_i) = \sum_{\{\gamma\}} I_\gamma(f),$$

where $\{\gamma\}$ is summed over all conjugacy classes in Γ . Here the orbital sum is:

$$(3.14) \quad I_\gamma(f) = \sum_{x \in \Gamma_\gamma \backslash \Xi} f(x, \gamma x).$$

Note that $\gamma \in \Gamma$, $\gamma \neq$ identity, implies that γ is hyperbolic. For Γ is the group of covering transformations of X . See Figure 3 for a tessellation of the 3-regular tree covering the tetrahedron or K_4 , the complete graph with 4 vertices. See Stark and Terras [17] for examples of finite covers of the tetrahedron.

We say that $\rho \in \Gamma$ is a primitive hyperbolic element if $\rho \neq$ the identity and ρ generates its centralizer in Γ . As in the case of discrete groups Γ acting on the Poincaré upper half plane, primitive hyperbolic conjugacy classes $\{\gamma\}$ in Γ correspond to closed paths in X which are the graph theoretic analogues of prime geodesics or curves minimizing distance which are not traversed more than once. We call the equivalence classes of such paths “primes” in X . Here the equivalence relation on paths simply identifies closed paths with different initial vertices. See Terras [20], Vol. I, p. 277. We will make use of this fact when considering the Ihara zeta function (4.1).

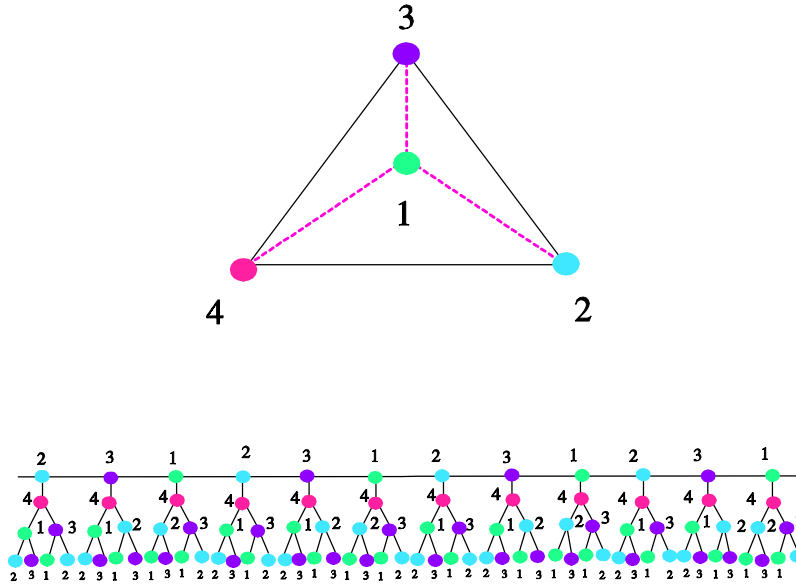


Figure 3. Tesselation of the 3-regular tree from the complete graph on 4 vertices (K_4 or the tetrahedron). Obtain the tesselation by choosing a spanning tree in K_4 - the dashed edges. Repeat the spanning tree for each of the infinitely many sheets of the cover. Connections between sheets are forced on you by the ordering of points on the geodesic labelled with 1,2,3 repeated infinitely many times.

Now we proceed to a discussion of another application of a pre-trace formula. Take some geodesic $\{x_m\}_{m \in \mathbb{Z}}$ which is a union of 2 chains c and c' on Ξ . We assume that c and c' intersect in the origin 0 of Ξ . The geodesic flow is defined by $\tau_n(x_m) = x_{m+n}$ on the geodesic itself and by moving points off the geodesic by just shifting the whole picture n units to the left if the geodesic is, for example, the top horizontal line in Figure 1.

We could also consider the horocycle flow but this seems somewhat less natural since it does not travel along edges of the tree. By a small set B in Ξ , we mean a set contained in a fundamental region for $\Gamma \backslash \Xi$. If B is a small rotation-invariant set in Ξ such as the shell of radius r defined by $S(r) = \{y \in \Xi \mid d(y, 0) = r\}$, for r sufficiently small, then define $B_n = \tau_n(B)$. For example, consider Figure 1 and let $B = \{x \mid d(x, 0) = 1\}$. Then B_n consists of points having distance $\geq n - 1$ from the origin.

This flow induces trajectories on X which are not true flows, as they have many self-intersections. If the radius of B is less than or equal to 1, it is locally mapped, by the projection $\pi : \Xi \rightarrow X = \Gamma \backslash \Xi$, one-to-one, onto the corresponding set in X . It is natural to ask: to what extent does the “induced flow” on X mix up the vertices of B on X ? The next theorem gives an answer to this question.

Let f denote the characteristic function of the set B and define $F(x)$ to be the Γ -periodization of f :

$$(3.15) \quad F(x) = \sum_{\gamma \in \Gamma} f(\gamma x).$$

Similarly define the rotationally averaged Γ -periodization of the shift of f :

$$(3.16) \quad F_n^\#(x) = \sum_{\gamma \in \Gamma} \frac{1}{k(k-1)^{d-1}} \sum_{\substack{y \in \Xi \\ d(y, \mathbf{o}) = d(\gamma x, \mathbf{o}) = d}} f(\tau_{-n}y).$$

Theorem 1. Assume that the k -regular graph X is connected and non - bipartite. Using definitions (3.15) and (3.16) above, with f equal to the characteristic function of the rotation-invariant set B , consider the sum:

$$U(n, B) = \frac{1}{|X|} \sum_{x \in X} F(x) F_n^\#(x)$$

Then $U(n, B)$ approaches $|B|^2|X|^{-2}$, as n goes to infinity.

Proof. Suppose $\phi_i, i = 1, \dots, |X|$, denotes a complete orthonormal set of eigenfunctions of the adjacency operator on X . Now

$$F(x) = \sum_{i=1}^{|X|} c_i \phi_i(x).$$

where $c_i = (F, \phi_i)_X$. By Selberg's Lemma, we have

$$c_i = \sum_{x \in X} F(x) \phi_i(x) = \sum_{y \in \Xi} f(x) \phi_i(x) = \widehat{f}(s_i) \phi_i(\mathbf{o}),$$

with $\widehat{f}(s_i)$ defined by (3.3).

So then the sum $U(n, B)$ is

$$U(n, B) = \frac{1}{|X|} \sum_{x \in X} \sum_{i=1}^{|X|} \widehat{f}(s_i) \phi_i(\mathbf{o}) \phi_i(x) F_n^\#(x).$$

Let us look at the term corresponding to $i = 1$, where we have chosen $\phi_1 = |X|^{-1/2}$ to be the constant eigenfunction of the adjacency operator on X . This term is

$$(3.17) \quad S = \frac{1}{|X|^2} \sum_{x \in X} \widehat{f}(s_1) F_n^\#(x).$$

Since f is the characteristic function of the set B and the spherical function corresponding to $s_1 = 0$ is the function which is identically 1, we have

$$(3.18) \quad \widehat{f}(s_1) = (f, 1)_\Xi = |B|.$$

Therefore we find, using definition (3.16), that the sum S in (3.17) is $|B|^2|X|^{-2}$. It remains to estimate the terms given by

$$R = \frac{1}{|X|} \sum_{i=2}^{|X|} c_i \sum_{x \in X} \sum_{\gamma \in \Gamma} \frac{1}{(q+1)q^{d-1}} \sum_{\substack{y \in \Xi; d(y, \mathbf{o}) = \\ d(\gamma x, \mathbf{o}) = d}} f(\tau_{-n}y) \phi_i(x).$$

We can combine the sums over X and Γ to get a sum over the tree Ξ . Then by Selberg's Lemma, we have

$$R = \frac{1}{|X|} \sum_{i=2}^{|X|} c_i \sum_{x \in \Xi} \frac{1}{(q+1)q^{d-1}} \sum_{\substack{y \in \Xi; d(y, \mathbf{o})= \\ d(x, \mathbf{o})=d}} f(\tau_{-n}y) h_{s_i}(x) \phi_i(\mathbf{o}).$$

Here $y = kx$ where k is a rotation about \mathbf{o} . Make the change of variables from x to y and use the fact that the spherical function is rotation invariant to see that

$$R = \frac{1}{|X|} \sum_{i=2}^{|X|} c_i \sum_{y \in \Xi} f(\tau_{-n}y) h_{s_i}(y) \phi_i(\mathbf{o}).$$

Since $f(y)$ is the characteristic function of the rotation-invariant set B , $f(\tau_{-n}y)$ is the characteristic function of $B_n = \tau_n(B)$, whose distance from \mathbf{o} approaches infinity as n goes to infinity.

So now we must make use of the asymptotics of the spherical function as d approaches infinity. The corollary to Lemma 1 says that our spherical function does approach 0 as the distance from the origin increases. And thus the sum R of the remaining terms approaches 0 and the theorem is proved. \square

Theorem 1 says that the intersection of a small rotation-invariant set B with the image of B propagated forward by the geodesic flow induced on X (when averaged over shells) tends to be what one expects when one intersects 2 random sets in X .

What happens if X is bi-partite? Then you must look at the term corresponding to the eigenvalue $-k$ separately and this is harder to compute.

Example. Consider Figure 3. Let X be the tetrahedron. Take $f = f_0$ in Theorem 1. Then the function $F_n^\#$ in (3.16) has support consisting of Γ -translates of rotations of $\tau_n \mathbf{o}$. So the sum in Theorem 1 is $U(n, \{\mathbf{o}\}) = \frac{u_n}{12(2^n - 1)}$, where u_n is the number of points in the tree of Figure 3 which are labeled 1 and are at a distance n from the origin \mathbf{o} .

It might help to have a more detailed version of Figure 3. So look at Figure 4.

From Figure 4, one sees that $u_3 = u_4 = u_5 = 6$ and $u_6 = 30$, $u_7 = 54$. Theorem 1 says that $U(n, \mathbf{o})$ approaches $1/16$ as n approaches infinity. We see in the example that $16U(n, \mathbf{o})$ has the values $2, 1, 1/2, 5/4, 9/8$ for $n = 3, 4, 5, 6, 7$. When $n \geq 35$, one can check using a computer, that $16U(n, \mathbf{o})$ is very close to 1.

There is another interpretation of u_n . As in formula (3.7), let A_n be the 4×4 matrix whose i, j entry is the number of paths in X of length n with no back-tracking starting at vertex i in X and ending at j in X . Then u_n is the $1, 1$ entry of A_n . Lemma 1 in Stark and Terras [17] says that $A_0 = I$, $A_1 = A$ = the adjacency matrix of the tetrahedron, $A_2 = A^2 - 3I$, $A_n = A_{n-1}A - 2A_{n-2}$, for $n \geq 3$. One can use this recursion to prove Theorem 1 in the case that $B = \{\mathbf{o}\}$. These recursions for A_n are the same as those defining the Hecke operator T_n in the note after formula (3.3). Using the method of generating functions (see Wilf [25], p. 171) plus the fact that $(A_n)_{1,1} = \frac{1}{|X|} Tr(A_n)$, one easily proves $u_n \sim 3 \cdot 2^{n-3}$, as $n \rightarrow \infty$.

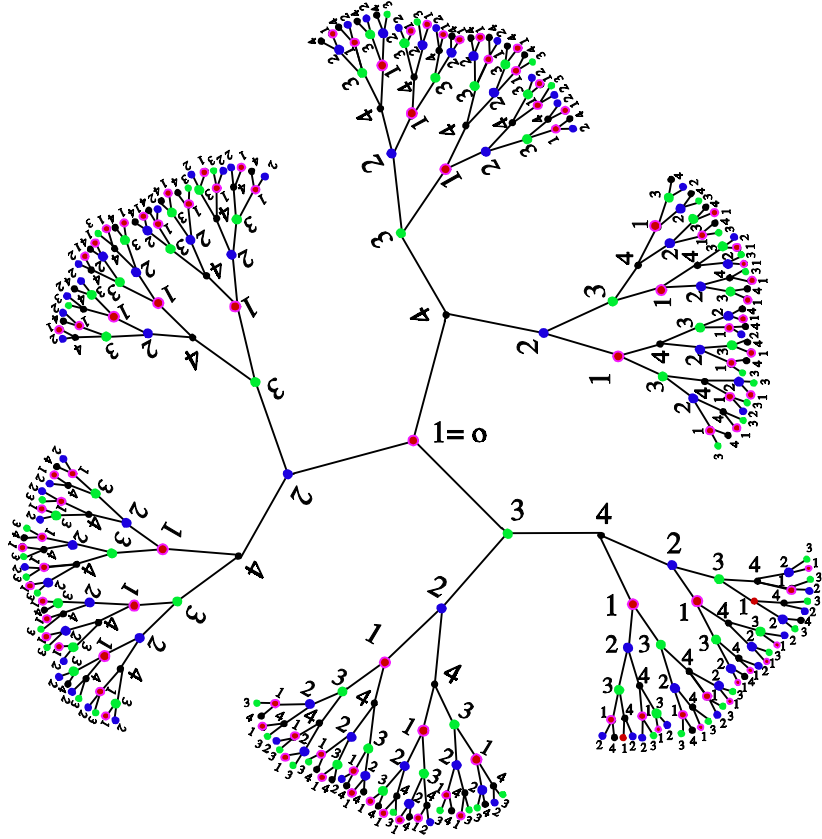


Figure 4. Another view of the Tessellation in Figure 3.

4. The Trace Formula

In order to derive the trace formula, we only need to recall pre-trace formula II (3.13) and to evaluate our orbital sums I_γ (3.14). If γ is the identity, this is easy. Writing $f(x, y) = f(d(x, y))$, we find $I_\gamma = f(0)|X|$. Otherwise use the next Lemma. Recall that we say $\rho \in \Gamma$ is primitive hyperbolic if $\rho \neq$ the identity and ρ generates its centralizer in Γ .

Lemma 5. Orbital Sums for Hyperbolic Elements are Horocycle Transforms. Suppose that ρ is a primitive hyperbolic element of Γ . Then we have the following formula relating the orbital integral defined by (3.14) and the horocycle transform defined by (2.3) for $r \geq 1$

$$I_{\rho^r}(f) = \nu(\rho)Hf(r\nu(\rho)).$$

Here $\nu(\rho)$ is the integer giving the size of the shift by ρ along its fixed geodesic.

Proof. The quotient $\Gamma_\rho \backslash \Xi$ is found by looking at the geodesic fixed by the primitive hyperbolic element ρ . Then consider this geodesic modulo ρ . Assume $\nu(\rho) = 3$ and look at Figure 5 where there are only three Γ_ρ -inequivalent points on the geodesic fixed by ρ , which is the left line of points in the picture.

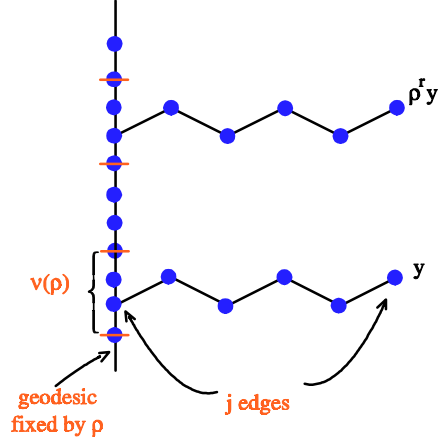


Figure 5. Finding the fundamental domain $\Gamma_\rho \setminus \Xi$, when $\nu(\rho) = 3$, $r = 2$, $j = 5$.

We claim that

$$\#\{y \in \Gamma_\rho \setminus \Xi \mid d(y, \rho^r y) = r\nu(\rho) + 2j\} = \nu(\rho)(q-1)q^{j-1}.$$

For Figure 5, we have $q = 2$, $j = 5$, $r = 2$, $\nu(\rho) = 3$ and the number above is $3 \cdot 16$. Why $\nu(\rho)$? Because y can be any of $\nu(\rho)$ things. It follows that the orbital sum of f associated to ρ^r is

$$\begin{aligned} I_{\rho^r}(f) &= \sum_{y \in \Gamma_\rho \setminus \Xi} f(d(y, \rho^r y)) \\ &= \nu(\rho)f(r\nu(\rho)) + \nu(\rho)(q-1) \sum_{j=1}^{\infty} q^{j-1} f(r\nu(\rho) + 2j). \end{aligned}$$

This completes the proof of the Lemma. \square

So we have proved the trace formula finally.

Theorem 2. The Trace Formula for a k -Regular finite Graph. Suppose that $f : \Xi \rightarrow \mathbb{R}$ has finite support and is invariant under rotation about the origin o of Ξ . Then if P_Γ denotes the set of primitive hyperbolic conjugacy classes in Γ , we have

$$\sum_{i=1}^{|X|} \hat{f}(s_i) = f(o)|X| + \sum_{\{\rho\} \in P_\Gamma} \nu(\rho) \sum_{e \geq 1} Hf(e\nu(\rho))$$

Here $A\phi_i = \lambda_i\phi_i$, where the ϕ_i form a complete orthonormal set of eigenfunctions of the adjacency operator A on X . Here the sum on the left is of spherical transforms of f at the s_i corresponding to the eigenvalues λ_i as in Lemma 4. In the sum on the right Hf is the horocycle transform defined by (2.3).

Special Case. Suppose $f = f_0$ defined by (3.2) with $r = 0$. Then the trace formula is trivial - saying that $|X| = |X|$. If $f = f_r$ defined by (3.2) for $r > 0$, the trace formula says

$$k(k-1)^{r-1} \sum_{i=1}^{|X|} h_{s_i}(r) = f_r(0)|X| + \sum_{\{\rho\} \in \mathbf{P}_\Gamma} \nu(\rho) \sum_{e \geq 1} Hf_r(e\nu(\rho)).$$

where $Hf_r(m)$ was computed in formula (3.6).

If $r = 1$ or 2 , $f_r(e\nu(\rho) + 2j) = 0$ as $e \geq 1$, $\nu(\rho) \geq 1$, $j \geq 1$. And $f_r(e\nu(\rho)) = Hf_r(e\nu(\rho))$ is only non-zero for $e\nu(\rho) \leq 2$. In particular, when $r = 1$, we see that the trace formula says

$$k \sum_{i=1}^{|X|} h_{s_i}(1) = \#\{\{\rho\} \in \mathbf{P}_\Gamma \mid \nu(\rho) = 1\} = 0.$$

If you plug in our formula for $h_s(1)$, you see that the sum on the left is $Tr(A) = 0$. It is also obvious that there are 0 primitive hyperbolic conjugacy classes $\{\rho\}$ in Γ with $\nu(\rho) = 1$ since there are no closed paths in X of length 1. For our graph X is assumed to have no loops. It is a simple graph.

Rather than proceeding in this way to find how many primes there are of various lengths, we put all the prime information together into a zeta function - Ihara's zeta function, which is the graph theoretic analogue of the Selberg zeta function. It can also be viewed as an analogue of the Dedekind zeta function of an algebraic number field. References are Ahumada [1], Bass [2], Ihara [12], Hashimoto [9], Stark and Terras [17], Sunada [18], Venkov and Nikitin [23].

Consider a connected finite (not necessarily regular) graph with vertex set X and undirected edge set E . For an example look at the tetrahedron. We orient the edges of X and label them $e_1, e_2, \dots, e_{|E|}$, $e_{|E|+1} = e_1^{-1}, \dots, e_{2|E|} = e_{|E|}^{-1}$. Here the inverse of an edge is the edge taken with the opposite orientation. A prime $[C]$ in X is an equivalence class of tailless backtrackless primitive paths in X . Here write $C = a_1 a_2 \cdots a_s$, where a_j is an oriented edge of X . The length $\nu(C) = s$. Backtrackless means that $a_{i+1} \neq a_i^{-1}$, for all i . Tailless means that $a_s \neq a_1^{-1}$. The equivalence class of C is $[C] = \{a_1 a_2 \cdots a_s, a_s a_1 a_2 \cdots a_{s-1}, \dots, a_2 \cdots a_s a_1\}$; i.e., the same path with all possible starting points. We call the equivalence class $[C]$ a prime or primitive if $C \neq D^m$, for all integers $m \geq 2$, and all paths D in X . It can be shown that such $[C]$ are in 1-1 correspondence with primitive hyperbolic conjugacy classes \mathbf{P}_Γ . See Stark's article in Hejhal et al [10], pp. 601-615.

The Ihara zeta function of X is defined for $u \in \mathbb{C}$ with $|u|$ sufficiently small by

$$(4.1) \quad \zeta_X(u) = \prod_{\substack{[C] \text{ prime} \\ \text{in } X}} (1 - u^{\nu(C)})^{-1}.$$

Note that the preceding product is infinite since X cannot be a cycle graph as its degree is greater than 2.

The following theorem can be attributed to many people in the case of both regular and irregular finite graphs. Bass [2], Hashimoto [9], and Sunada [18] certainly should be mentioned. The proof we sketch is due to Ahumada [1]. We found the discussion we outline in Venkov and Nikitin [23]. Ihara [12] considers these zeta functions within the framework of p-adic groups.

Theorem 3. (Ihara). If A denotes the adjacency matrix of X and Q the diagonal matrix with j th entry $q_j = (\text{degree of the } j\text{th vertex} - 1)$, then

$$\zeta_X(u)^{-1} = (1 - u^2)^{r-1} \det(I - Au + Qu^2).$$

Here r denotes the rank of the fundamental group of X . That is $r = |E| - |V| + 1$.

Proof. Following Venkov and Nikitin, plug the following function into the trace formula

$$Hf(d) = g(d) = \begin{cases} u^{|d|-1}, & \text{for } d \neq 0 \\ 0, & \text{for } d = 0. \end{cases}$$

After a certain amount of computation, one finds the following formulas. The

$$\text{right-hand non-identity terms} = \frac{d \log \zeta_X(u)}{du}.$$

By the inversion formula for the horocycle transform,

$$\text{right-hand identity term} = nf(0) = \frac{d \log(1 - u^2)^{n(q-1)/2}}{du}.$$

Here $n = |X|$ and $n(q-1)/2 = r - 1$, where r is the rank of the fundamental group of X . See Stark's article in Hejhal et al [10], pp. 604-5, for a proof.

Using formula (3.5) in our 1st example of spherical and horocycle transforms after Lemma 3, the left-hand side is a sum over the eigenvalues λ of the adjacency matrix of X of terms of the form

$$\frac{-d \log(1 - \lambda u + qu^2)}{du}.$$

□

In the general case, when X is not a regular graph, the preceding formula for the Ihara zeta function still holds. There are many proofs. See Stark and Terras [17] for some elementary ones and more references.

One can use the preceding theorem to obtain an analogue of the prime number theorem. First one defines a prime path to be a closed path without backtracking or tails that is not a power of another closed path modulo equivalence. Here two running through the same edges (vertices) but starting at different vertices are called equivalent. Let $\pi_X(r)$ denote the number of prime path equivalence classes $[C]$ in X where the length of C is r . Then one has for non-bipartite $(q+1)$ -regular graphs X

$$(4.2) \quad \pi_X(r) \sim \frac{q^r}{r}, \quad \text{as } r \longrightarrow \infty.$$

To prove (4.2), look at the generating function

$$(4.3) \quad x \frac{d}{du} \log \zeta_X(u) = \sum_{m=1}^{\infty} n_X(m) u^m,$$

where $n_X(r)$ is the number of closed paths C in X of length r without backtracking or tails. Since the closest singularity of $\zeta_X(u)$ to the origin is at $1/q$, it follows that $n_X(r) \sim q^r$, as $r \longrightarrow \infty$. Compare this with (3.10), where we were counting paths that could have tails. Then one sees easily that the asymptotic behavior of

the number of prime paths C of length r is the same as that of $n_X(r)$. Counting equivalence classes $[C]$ of prime paths of length r divides the result by r .

Note that since the Ihara zeta function is the reciprocal of a polynomial, it has no zeros. Thus when discussing the Riemann hypothesis we consider only poles. When X is a finite connected $(q+1)$ -regular graph, there are many analogues of the facts about the other zeta functions. For any unramified graph covering (not necessarily normal, or even involving regular graphs) it is easy to show that the reciprocal of the zeta function below divides that above (see Stark and Terras [17]). The analogue of this for Dedekind zeta functions of extensions of number fields is still unproved. There are functional equations. Special values give graph theoretic constants such as the number of spanning trees. See the references mentioned at the beginning of this section for more details.

For example, when X is a finite connected $(q+1)$ -regular graph, we say that $\zeta_X(q^{-s})$ satisfies the Riemann hypothesis iff

$$(4.4) \quad \text{for } 0 < \operatorname{Re} s < 1, \quad \zeta_X(q^{-s})^{-1} = 0 \iff \operatorname{Re} s = \frac{1}{2}.$$

It is easy to see that (4.4) is equivalent to saying that X is a Ramanujan graph in the sense of Lubotzky, Phillips, and Sarnak [14]. This means that when λ is an eigenvalue of the adjacency matrix of X such that $|\lambda| \neq q+1$, then $|\lambda| \leq 2\sqrt{q}$. Such graphs are optimal expanders and (when X is non-bipartite) the standard random walk on X converges extremely rapidly to uniform. See Terras [19] for more information. The statistics of the zeros of the Ihara zeta function of a regular graph can be viewed as the statistics of the eigenvalues of the adjacency matrix. Such statistics have recently been of interest to number theorists and physicists. See Katz and Sarnak [13]. This has been investigated for various families of Cayley graphs such as the finite upper half plane graphs. See Terras [21], [22] for a discussion of some connections with quantum chaos.

Example. The Ihara zeta function of the tetrahedron. It is really easy to compute the eigenvalues of the adjacency operator in this case. They are

$$\{3, -1, -1, -1\}.$$

So one finds that the reciprocal of the Ihara zeta function of K_4 is

$$\zeta_{K_4}(u)^{-1} = (1-u^2)^2(1-u)(1-2u)(1+u+2u^2)^3.$$

In this case, the generating function for the $n_{K_4}(r)$ in equation (4.3) is

$$\begin{aligned} x \frac{d}{dx} \log \zeta_{K_4}(x) &= \sum_{m=1}^{\infty} n_{K_4}(m) x^m \\ &= 24x^3 + 24x^4 + 96x^6 + 168x^7 + 168x^8 + 528x^9 \\ &\quad + 1200x^{10} + 1848x^{11} + O(x^{12}). \end{aligned}$$

This says that there are 8 equivalence classes of closed paths of length 3 (without backtracking or tails) on the tetrahedron, for example. It is easy to check this result, recalling that we distinguish between paths and their inverses (the path traversed in the opposite direction). And there are 6 classes of closed paths of length 4. There are no closed paths of length 5. Note that the coefficient of x^9 is not divisible by 9. This happens since a non-prime path such as that which goes around a given

triangle three times will have only 3 equivalent paths in its equivalence class, rather than 9.

Many more examples can be found in Stark and Terras [17] - as well as examples of Artin L-functions associated to graph coverings. In Figure 19 of that paper, one finds an example of 2 non-isomorphic graphs without loops or multiple edges having the same Ihara zeta functions. This is analogous to similar examples of Dedekind zeta functions of 2 algebraic numbers fields being equal without the number fields being isomorphic. It comes from an example of Buser [4] which ultimately led to the example of two planar drums whose shape cannot be heard since they have the same Laplace spectra but cannot be obtained from one another by rotation or translation. See Carolyn Gordon et al [8].

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