## Problem 7.1.9

Let the vector from the center of the circle to the duck make an angle $\theta$ with the positive $x$-axis, let the vector from the dog to the duck make an angle $\phi$ with the vector from the duck to the center of the circle, and call the distance from the dog to the duck $R$, as shown below:


Let the speed of the dog be $v$ (the length of the blue vector), and that of the duck be $\omega$ (the length of the green vector). Then $R$ is decreasing by $v$ and increasing by the projection of the duck's velocity vector in the direction of the dog-duck vector: $\omega \cos \left(\frac{\pi}{2}-\phi\right)=\omega \sin \phi$. Thus

$$
\dot{R}=-v+\omega \sin \phi
$$

To understand how the angle $\phi$ is changing, extend the lines from the duck $(k)$ to the center and the duck $(k)$ to the dog $(g)$ across the circle so that they become chords. Recall that the arc on the circle between the endpoints of these chords is $2 \phi$. Consider the corresponding chords a moment later as the duck moves to a new position ( $k^{\prime}$ ), as shown in the next figure. The diameter is rotating at angular velocity $\omega$, so the arc on the circle between the endpoints of the chords is decreasing by $\omega$, but also increasing by the rate at which the chord through the dog is changing its endpoint $(l)$. To see what this rate is, recall that the power of a point inside the circle is the product of the lengths into which it divides any chord. This means that the triangle $k k^{\prime} g$ is similar to the triangle $l l^{\prime} g$, and the ratio is $2 \cos \phi-R$ (the length of the chord $k l$ minus the length of the segment $k g$ ) to $R$ (the length of the segment $k g$ ). Thus the endpoint $l$ is moving at angular velocity
$\omega(2 \cos \phi-R) / R$, since the endpoint $k$ is moving at angular velocity $\omega$, and hence

$$
2 \dot{\phi}=-\omega+\frac{2 \cos \phi-R}{R} \omega \quad \Longrightarrow \quad \dot{\phi}=\frac{\cos \phi-R}{R} \omega
$$



