

Math 220 A - Lecture 3

October 9, 2023

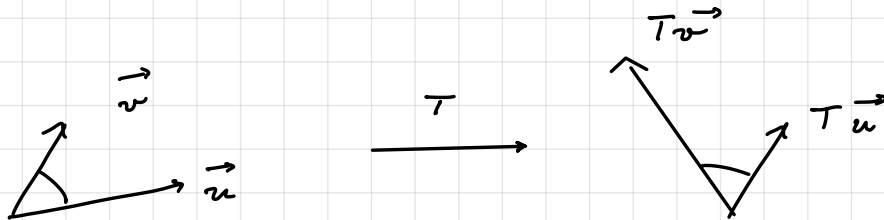
I. Conformal maps

Def $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ \mathbb{R} -linear, invertible

\square T is orientation preserving if $\det T > 0$.

\square T is angle preserving if for any vectors $\vec{u}, \vec{v} \in \mathbb{R}^2$

$$\angle(\vec{u}, \vec{v}) = \angle(T\vec{u}, T\vec{v}).$$



Remark $T = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$ is both orientation & angle

preserving (unless $a = b = 0$).

- $\det T = a^2 + b^2 > 0$ if $(a, b) \neq (0, 0)$

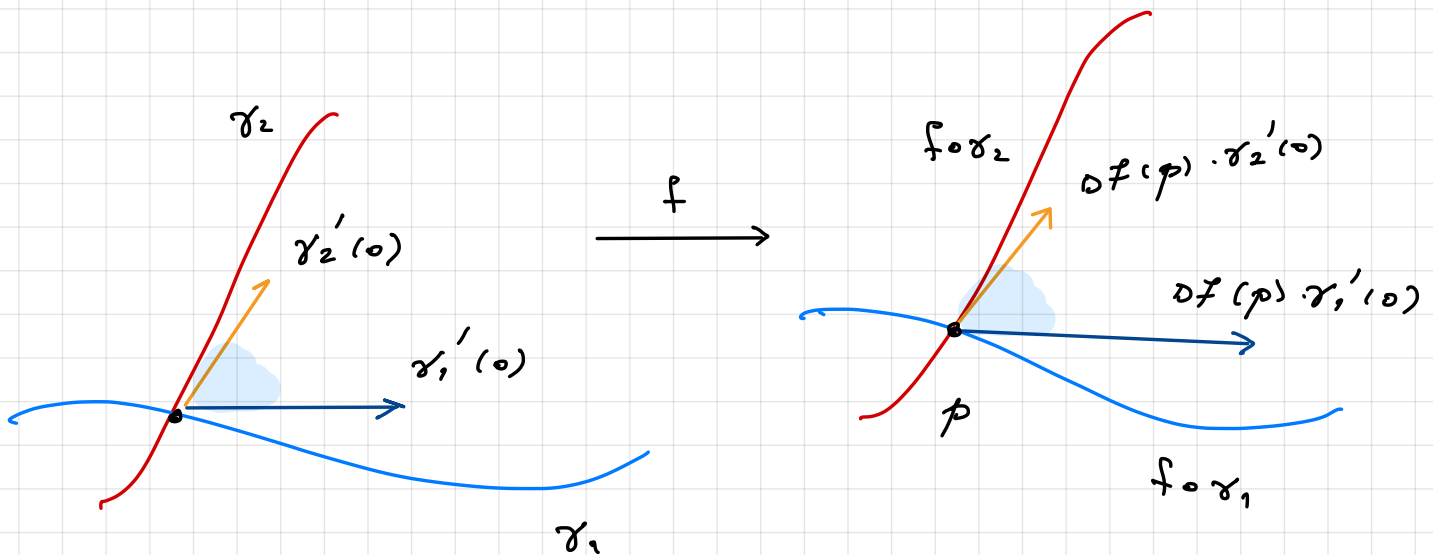
- angles are preserved since $Tz = \alpha z = r e^{i\theta} z$, $\alpha = r e^{i\theta}$

is composition of rotation & dilation.

Remark f holomorphic \Rightarrow either $f'(z) = 0$ or else

$Df(z)$ is orientation & angle preserving.

\Leftrightarrow " f preserves angles" (f "conformal" if $f'(z) \neq 0 \forall z$).



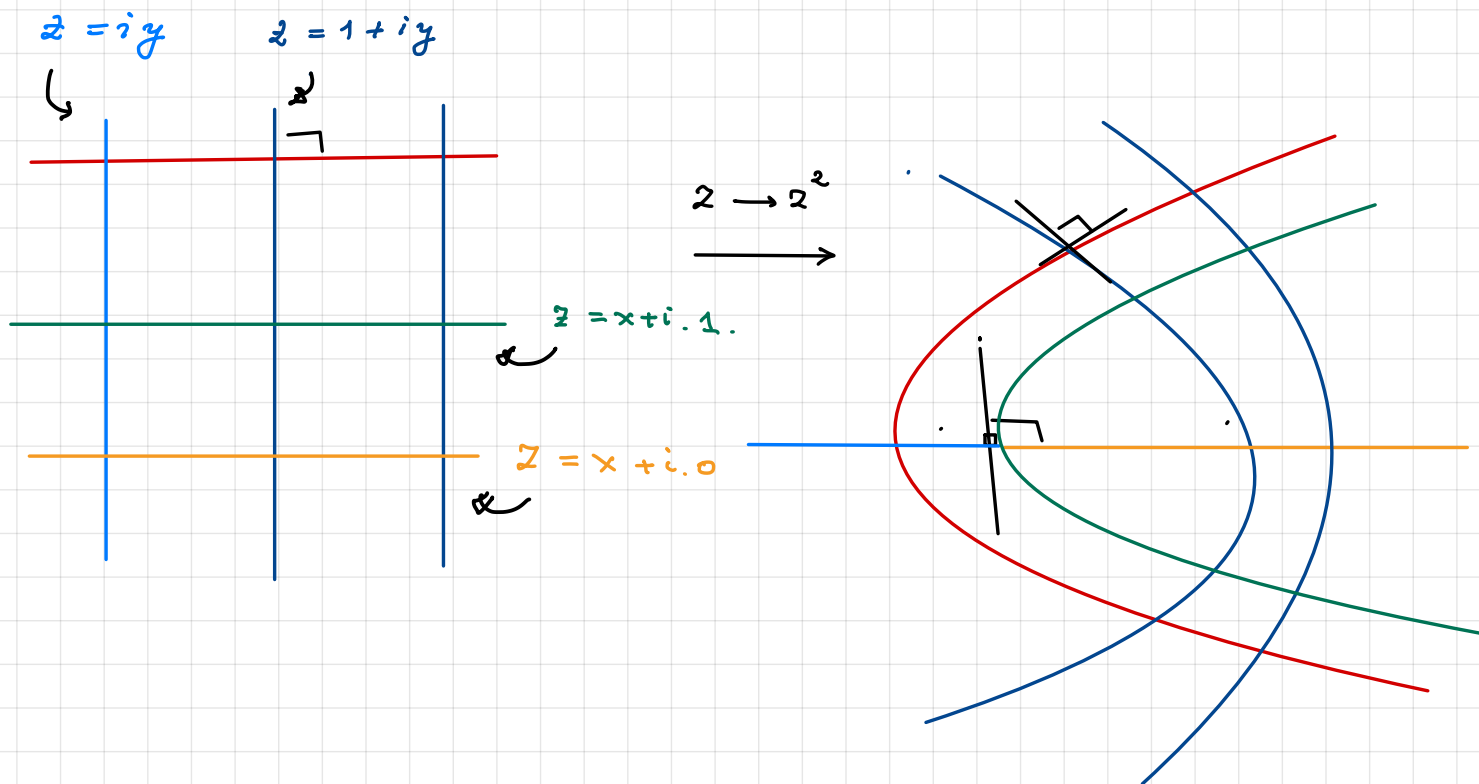
Def $f : U \rightarrow \mathbb{C}$ holomorphic is conformal if

$$\forall z \in U, f'(z) \neq 0$$

Some other definitions exist in the literature (requiring f to be injective for instance).

Example

$$f(z) = z^2$$



$$z = x + i.1 \Rightarrow z^2 = \underbrace{x^2 - 1}_u + \underbrace{2x}_v i$$

$$\Rightarrow u = \frac{v^2}{4} - 1 \quad \text{parabola (green)}$$

$$z = iy \Rightarrow \text{half line } \mathbb{R}_{\leq 0}, \quad z = x \Rightarrow \text{half line } \mathbb{R}_{\geq 0}$$

$$z = 1 + iy \Rightarrow z^2 = \underbrace{1 - y^2}_u + \underbrace{2y}_v i$$

$$\Rightarrow u = 1 - \frac{v^2}{4} \quad \text{parabola (dark blue)}$$

Check : Angles are preserved. in these examples

A better piece of terminology is:

Remark Given $U, V \subseteq \mathbb{C}$, a **biholomorphic** map

$f: U \rightarrow V$ is

\square f **bijective**, **holomorphic**

\square $g = f^{-1}: V \rightarrow U$ **holomorphic**.

$$\text{If } f(p) = z \Rightarrow f \circ g(z) = z$$

$$\Rightarrow g'(z) = \frac{1}{f'(p)}, \quad f'(p) \neq 0.$$

Thus **biholomorphic** \Rightarrow **conformal**

Important Question

Given $u, v \subseteq \mathbb{C}$, are they biholomorphic?

II. Möbius Transforms

Today we study a class of transformations which are important for geometric arguments.

Möbius transformations (MT)

Fractional linear transformations (FLT)

linear fractional transformations (LFT)



August Ferdinand Möbius (1790-1868)

Möbius strip, Möbius inversion, Möbius transform

Möbius published important work in astronomy.

Definition

$$\hat{\mathbb{C}} = \mathbb{C}_\infty = \mathbb{C} \cup \{\infty\} \text{ Riemann sphere}$$

Topology

on $\hat{\mathbb{C}}$ - usual open sets in \mathbb{C}

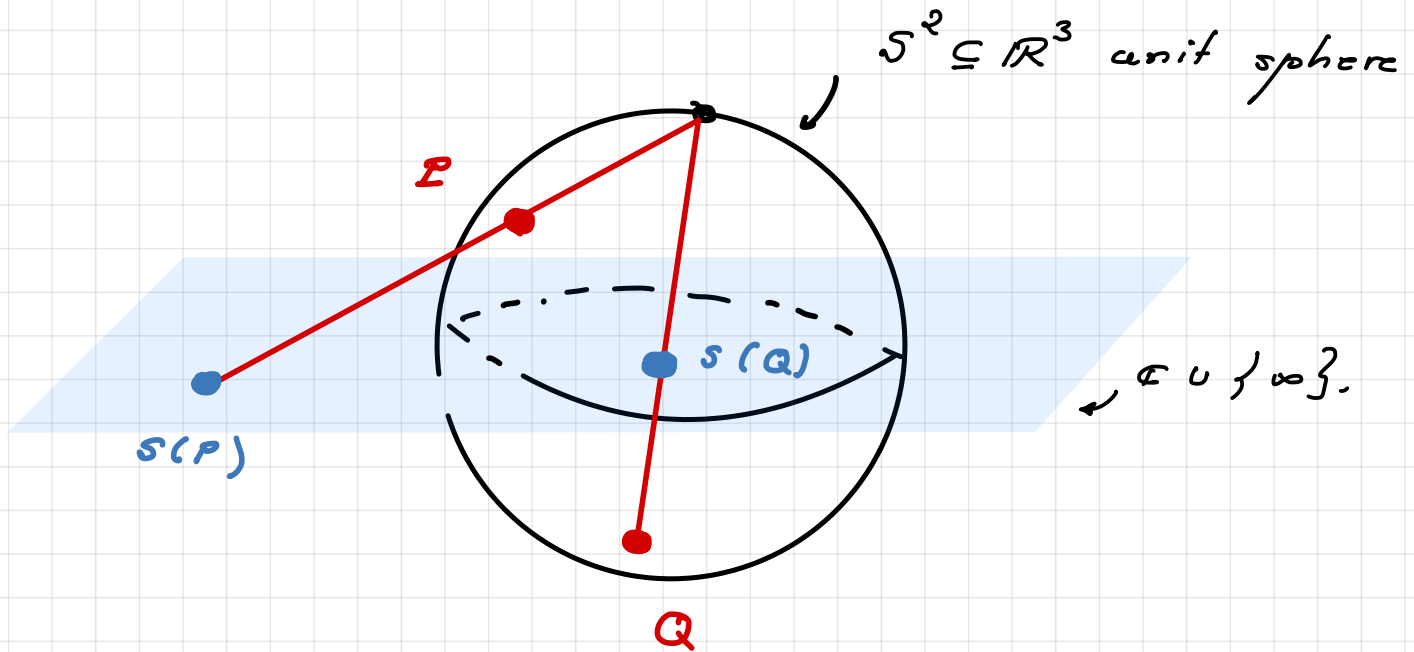
- open sets containing ∞ .

$\infty \in \mathcal{U} \subseteq \hat{\mathbb{C}}$ open if $\forall z \in \mathcal{U}, z \neq \infty \exists \Delta(z, R) \subseteq \mathcal{U}$

• for $z = \infty$, $\exists R$ with

$$\{z : |z| > R\} \subseteq \mathcal{U}$$

\rightsquigarrow neighborhood of ∞ .



stereographic projection

Definition Möbius transformations MT.

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, h_A : \hat{\mathbb{C}} \rightarrow \hat{\mathbb{C}}, z \mapsto \frac{az + b}{cz + d}$$

invertible matrix

using

This is a "biholomorphism" of $\hat{\mathbb{C}}$.

$$\frac{1}{0} = \infty, \frac{1}{\infty} = 0$$

h_A is a homeomorphism of $\hat{\mathbb{C}}$.

Remark

i $A = I \Rightarrow h_A = \text{id}$.

ii $A = \lambda B \Leftrightarrow h_A = h_B$ for $\lambda \neq 0$.

iii $h_{AB} = h_A \circ h_B$ if $B = A^{-1} \Rightarrow h_{A^{-1}} = h_A^{-1}$.

Möbius transforms $\longleftrightarrow PGL_2 = GL_2 / \text{center}$

↓

"projective linear group"

Most famous example

Cayley transform

$$c(z) = \frac{z-i}{z+i}, \quad c^{-1}(w) = i \cdot \frac{1+w}{1-w}$$

Notation:

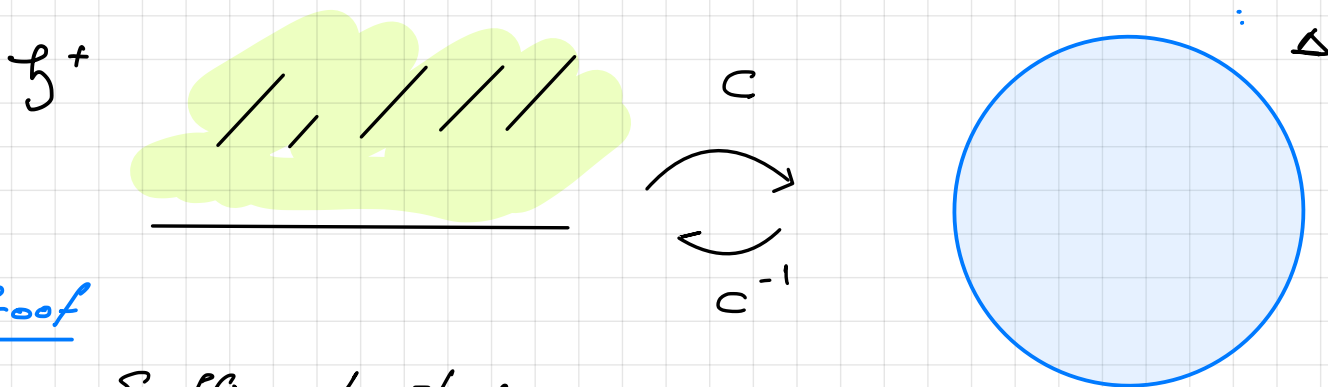
$\Delta = \Delta(0,1) = \text{unit disc}$

$\mathfrak{H}^+ = \{z : \text{Im } z > 0\} = \text{half-plane}$

Very Important

c is a biholomorphism

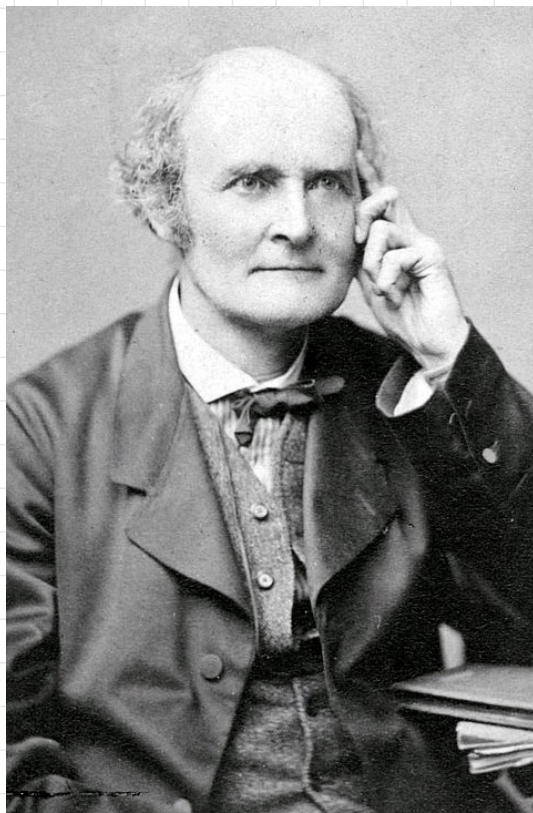
$$c: \mathfrak{H}^+ \longrightarrow \Delta$$



Proof

It suffices to show

$$z \in \mathfrak{H}^+ \iff c(z) \in \Delta. \quad \text{Write } z = x + iy$$
$$\begin{aligned} & \iff y > 0 \\ & \iff |z-i| < |z+i| \\ & \iff x^2 + (y-1)^2 < x^2 + (y+1)^2 \end{aligned}$$



Arthur Cayley (1821 - 1895)

- worked in algebraic geometry, Group theory
- Cayley - Hamilton theorem
- modern definition of a group

Remark

$$\frac{az + b}{cz + d} = \frac{bc - ad}{c^2} \cdot \frac{1}{z + \frac{d}{c}} + \frac{a}{c}$$

$$c = 0: \quad \frac{az + b}{d} = \frac{a}{d} \cdot z + \frac{b}{d}$$

Types of Möbius transforms

I translation $Tz = z + \lambda$

II rotations $Rz = e^{i\theta} \cdot z$

III dilations $Dz = m \cdot z, m \in \mathbb{R}$

IV inversion $Sz = \frac{1}{z}$

Lemma All Möbius transforms are compositions of

I - IV

Generalized circles in $\hat{\mathbb{C}}$

\square circles in \mathbb{C}

\square line $L \cup \{\infty\}$ = "circle in $\hat{\mathbb{C}}$
through ∞ ."

Main theorems about Möbius transforms

Theorem A Any Möbius transform maps
generalized circles to generalized circles.

Theorem B PGL_2 acts triply transitively on $\hat{\mathbb{C}}$.

Given $(z_1, z_2, z_3), (z'_1, z'_2, z'_3)$ triples of distinct elts in

$\hat{\mathbb{C}}$, $\exists!$ h with $h(z_i) = z'_i$.

Proof of Thm A Suffices to consider the cases

II translation $z \rightarrow z + \lambda$ clear

III rotation $z \rightarrow e^{i\alpha} z$ clear

IV dilation $z \rightarrow m z$ clear

V inversion $z \rightarrow 1/\bar{z}$

Claim A generalized circle is given by

(*) $A z \bar{z} + B z + C \bar{z} + D = 0$, where $A, D \in \mathbb{R}$,
and B, C are conjugates.

Proof A circle in \mathbb{C} is given by

$$|z - z_0| = r \iff (z - z_0) \cdot (\bar{z} - \bar{z}_0) = r^2$$

$$\iff z \bar{z} - \bar{z}_0 z - z_0 \bar{z} + (z_0 \bar{z}_0 - r^2) = 0$$

$$\implies (*) \text{ for } A=1, D = z_0 \bar{z}_0 - r^2, B = -\bar{z}_0, C = -z_0.$$

Conversely, if $A \neq 0$, (*) can be brought into this form.

(why?)

When $A = 0$: $\underbrace{B z + C \bar{z}} + D = 0 \iff$ line.
linear

Proof IV preserves generalized circles.

$$A z \bar{z} + B z + C \bar{z} + D = 0.$$

$$\text{Let } w = \frac{1}{z} \Rightarrow A \cdot \frac{1}{w \bar{w}} + \frac{B}{w} + \frac{C}{\bar{w}} + D = 0$$

$$\Rightarrow A + B \bar{w} + C w + D w \bar{w} = 0.$$

\Rightarrow generalized circle. \Rightarrow Thm A.

In the case of lines $L \cup \infty$, 0 and ∞ correspond under IV.

Proof of Thm B Uniqueness Assume $\exists h, h'$

$$z_1 \xrightarrow{h} z_1'$$

$$z_2 \xrightarrow{h} z_2'$$

$$z_3 \xrightarrow{h} z_3'$$

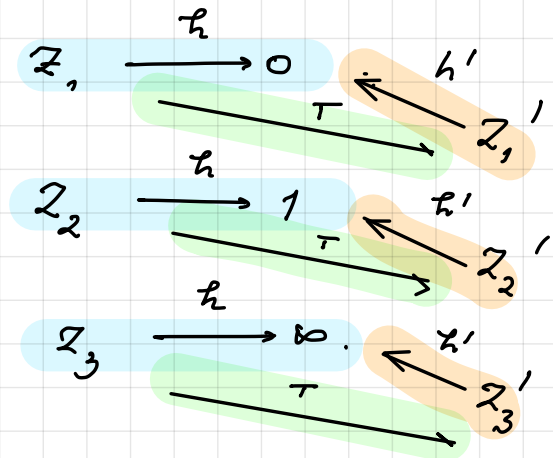
$$\text{Let } T = h^{-1} \circ h' \Rightarrow T(z_i) = z_i,$$

$$\Leftrightarrow \frac{az + b}{cz + d} = z \text{ has 3 roots } z_1, z_2, z_3$$

$$\Leftrightarrow az + b = cz^2 + dz \text{ has 3 roots}$$

$$\Rightarrow a = d, b = c \Rightarrow T = \text{id} \Rightarrow h = h'.$$

Existence Suffices: $\exists h$ with



$$h(z_1) = 0$$

$$h(z_2) = 1$$

$$h(z_3) = \infty.$$

If (z_1', z_2', z_3') is another triple, find h' with

$$h'(z_1') = 0, \quad h'(z_2') = 1, \quad h'(z_3') = \infty.$$

Define $T = h' \circ h \Rightarrow T(z_i) = z_i'$ as needed.

To deal with (z_1, z_2, z_3) and $(0, 1, \infty)$.

(Modified) Cross ratio

If $z_1, z_2, z_3 \neq \infty$,

$$h(z) = \frac{z - z_1}{z - z_3} \bigg/ \frac{z_2 - z_1}{z_2 - z_3}$$

This is sometimes denoted $[z : z_1 : z_2 : z_3]$.

Check $h(z_1) = 0$

$$h(z_2) = 1$$

$$h(z_3) = \infty.$$

There are 3 remaining cases $z_1 = \infty$, $z_2 = \infty$ or $z_3 = \infty$.

For example, when $z_1 = \infty$, the above expression is

$$h(z) = \frac{z_2 - z_3}{z - z_3}, \quad h(z_1) = 0, \quad h(z_2) = 1, \quad h(z_3) = \infty.$$

The other cases are similar.

Remark Conway's cross ratio sends z_1, z_2, z_3 to $1, 0, \infty$.

We will not need the notion later, so the difference will not concern us.

Next Integration & Cauchy theory.